



1014I – Communication systems and cybersecurity (2025/26)

A primer on digital communication systems

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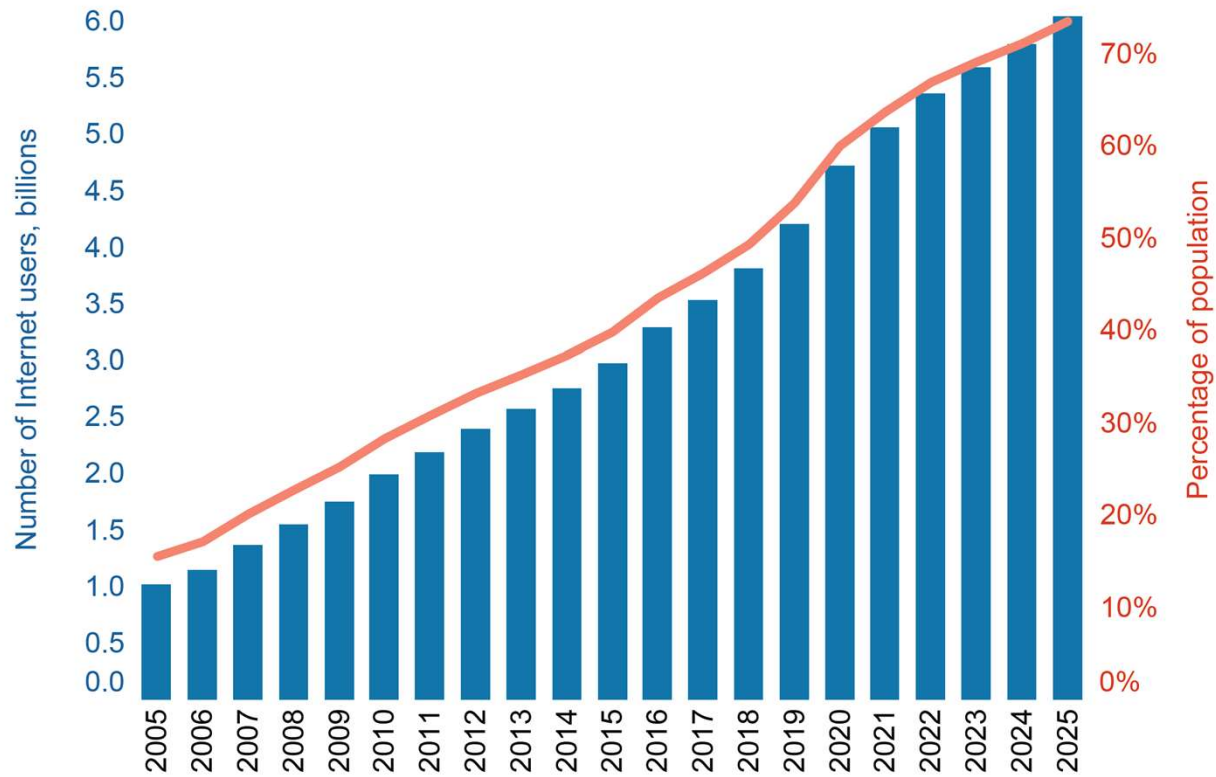


Introduction



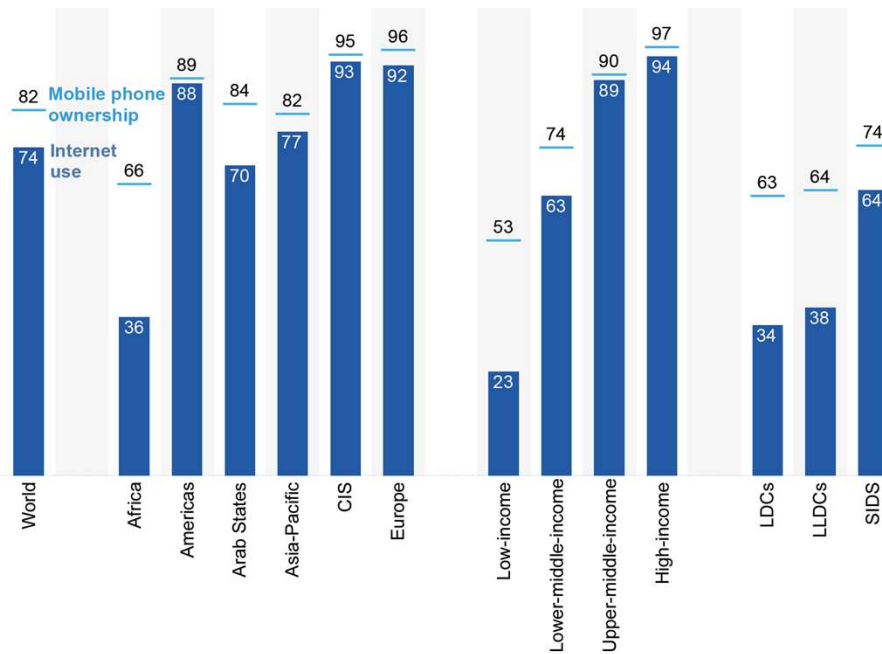
Some (whopping) facts on communications (1/5)

Individuals using the Internet

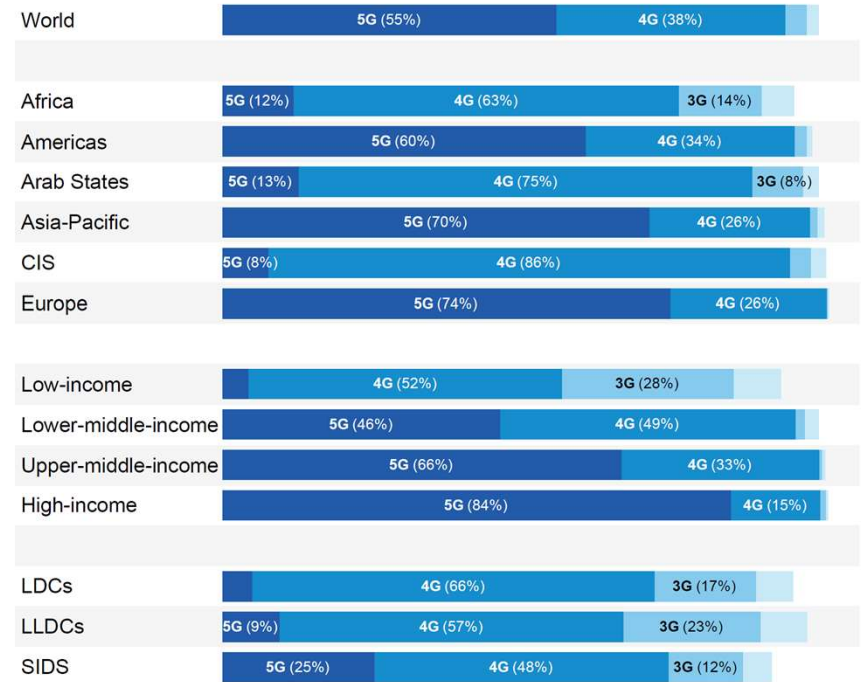


Some (whopping) facts on communications (2/5)

Percentage of individuals owning a mobile phone and using the Internet, 2025

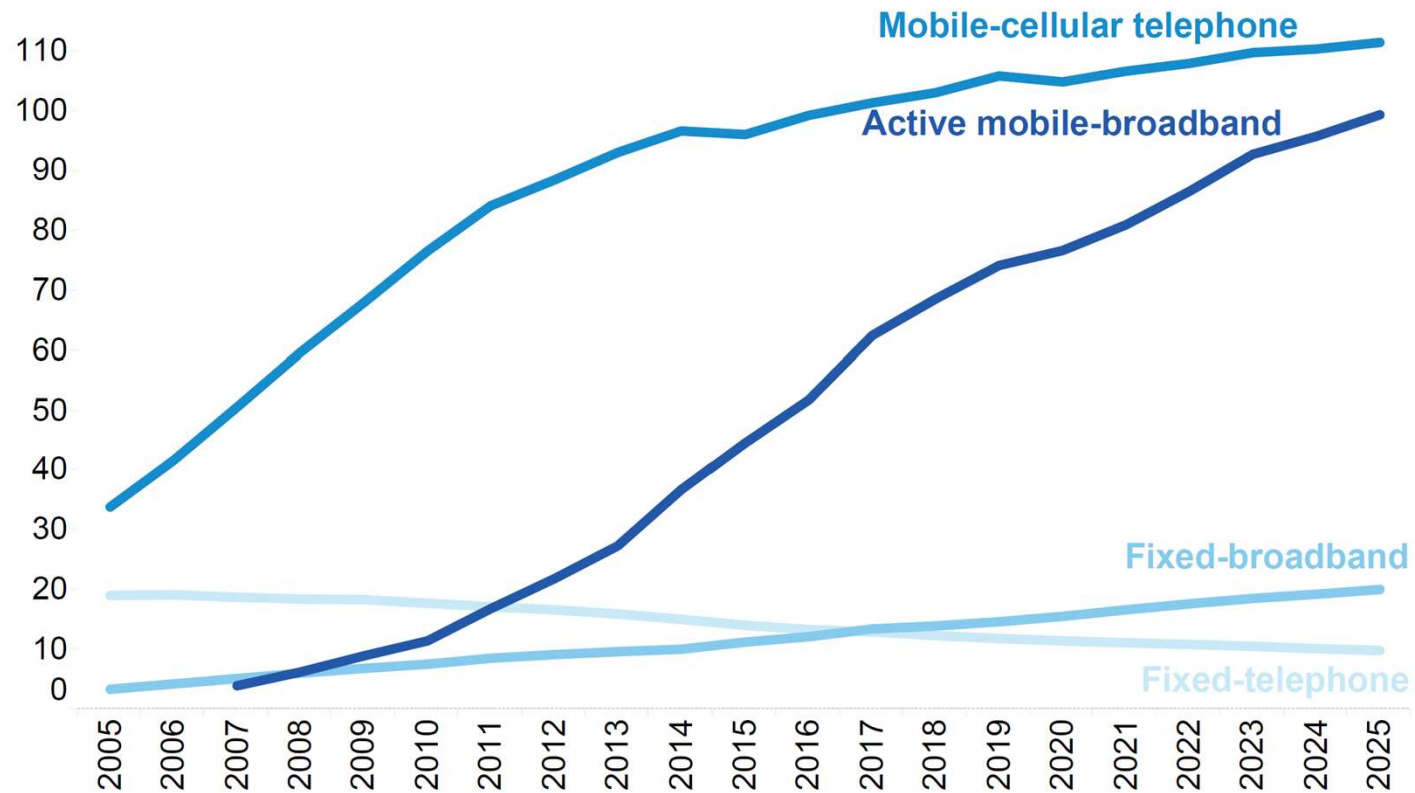


Population coverage by type of mobile network, 2025



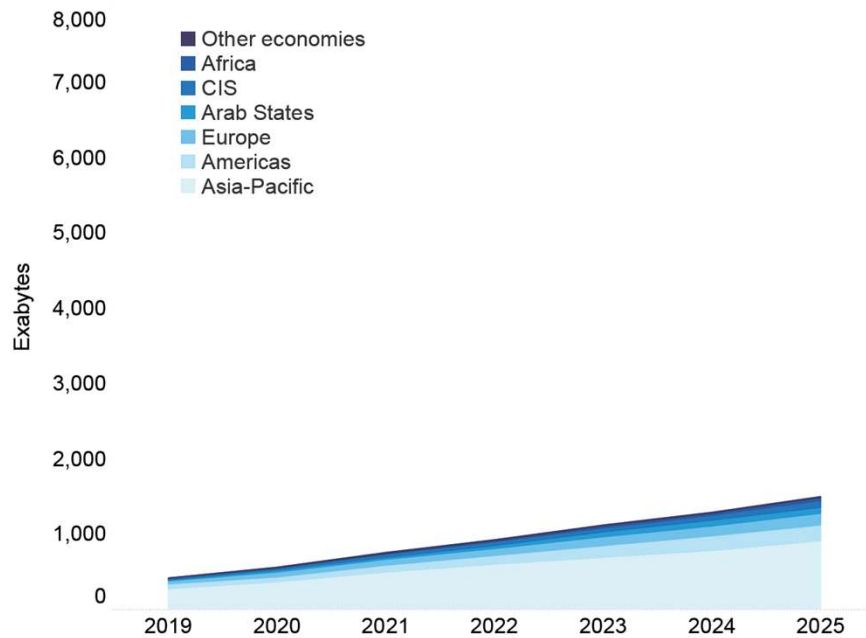
Some (whopping) facts on communications (3/5)

Subscriptions per 100 inhabitants, worldwide

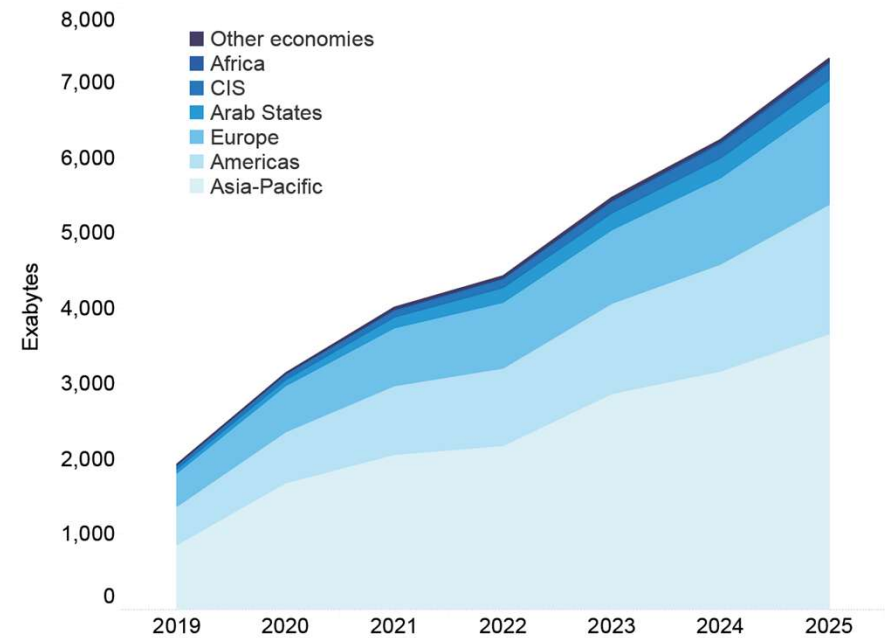


Some (whopping) facts on communications (4/5)

Mobile broadband traffic, EB



Fixed broadband traffic, EB



1 EB = 10^{18} bytes = 10^{12} MB

Some (whopping) facts on communications (5/5)

- The number of people **with access to mobile communications is higher than those with access to** working toilets (around 4.6 billions, source: World Health Organization)
- The number of people that owns a mobile phone is larger than the one that owns/uses a **toothbrush** (around 4 billions)
- Every second, more than **eight hours** of videos is uploaded to Youtube (as of 2022)



Outline of the lecture

- Overview of the architecture
- Building blocks of transmitter and receiver
- Analog-to-digital conversion
- Source coding
- Channel coding
- Modulation techniques
- Shannon capacity
- Multiplexing and multiple access

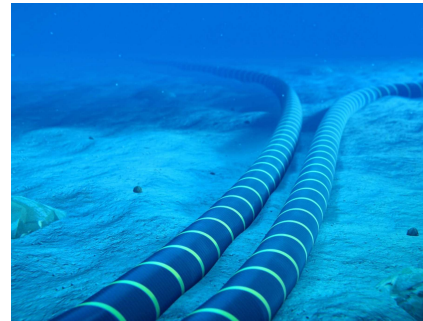


Categories of communication systems (1/3)

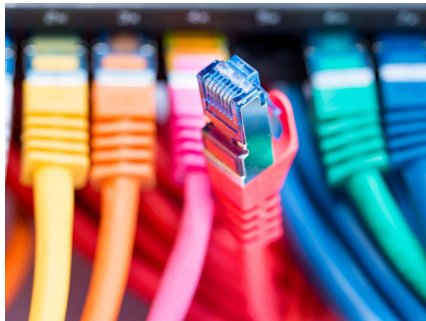
- Access vs. transport



VS.



- Wired vs. wireless



VS.



Categories of communication systems (2/3)

- Broadcast (point-to-multipoint) vs. unicast (point-to-point)



VS.



- Broadband vs. narrowband



VS.



Categories of communication systems (3/3)

- Terrestrial vs. satellite



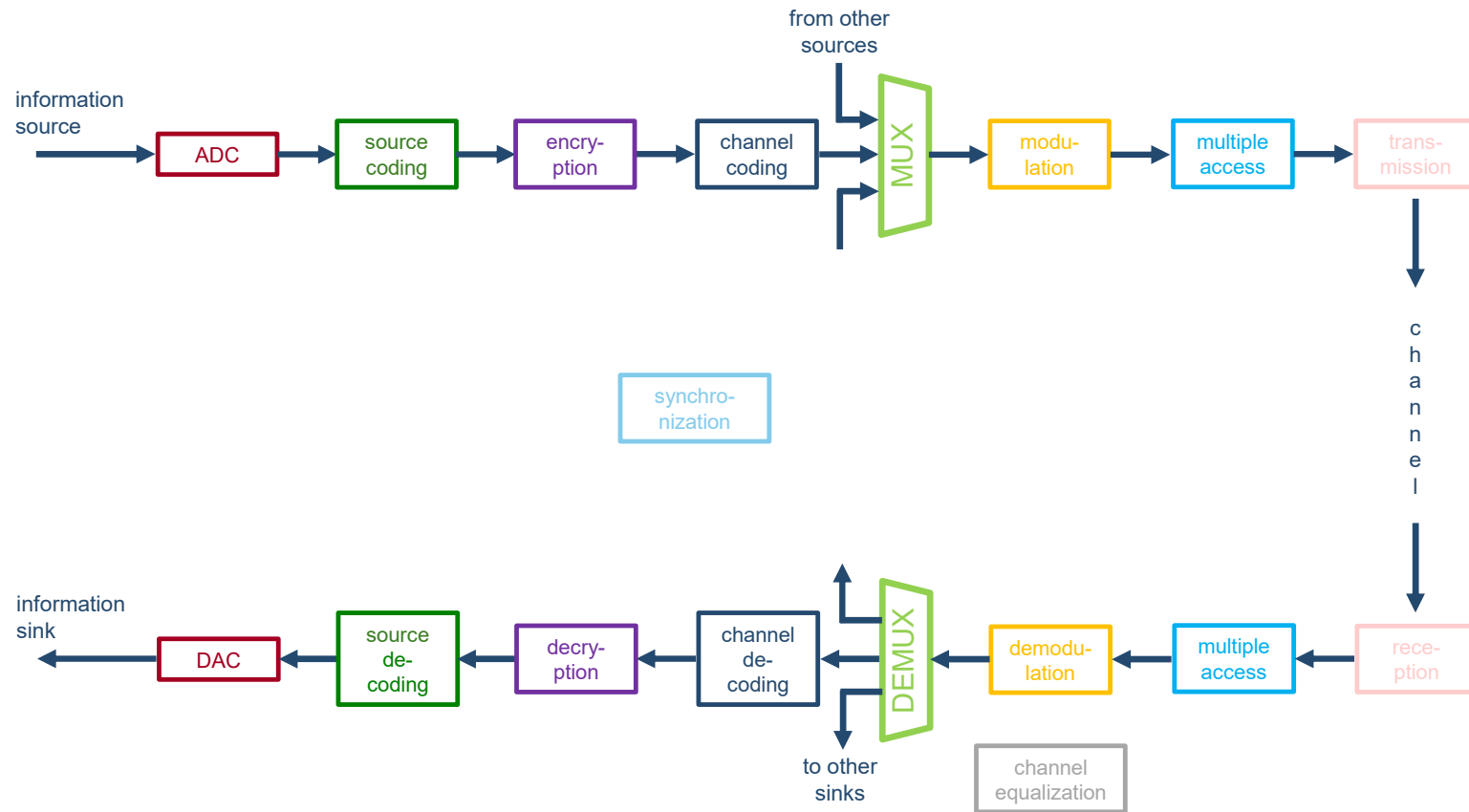
VS.



... and many more



Elements of a digital communication system



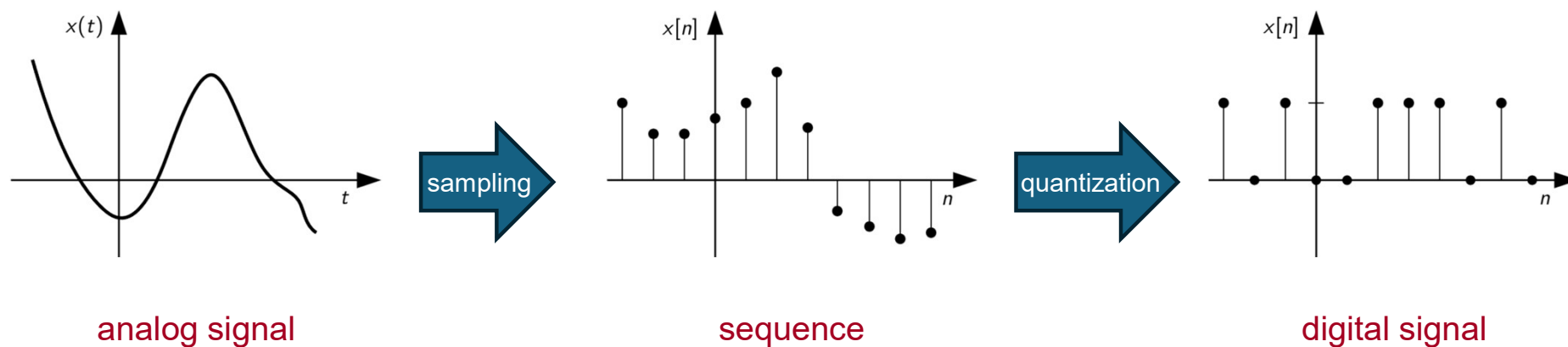
Analog-to-digital conversion (ADC)



Analog-to-digital conversion (ADC)

The **ADC** operation consists into two steps:

- **Sampling**, which makes the signal a sequence of values: time becomes discrete, values of the sequence are still in the real domain
- **Quantization**, which represents the values of the sequence with a finite number of bits: values now belong to a finite set

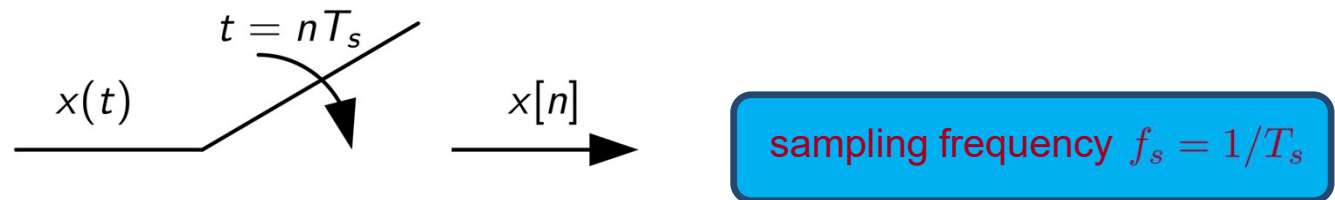


Sampling and interpolation

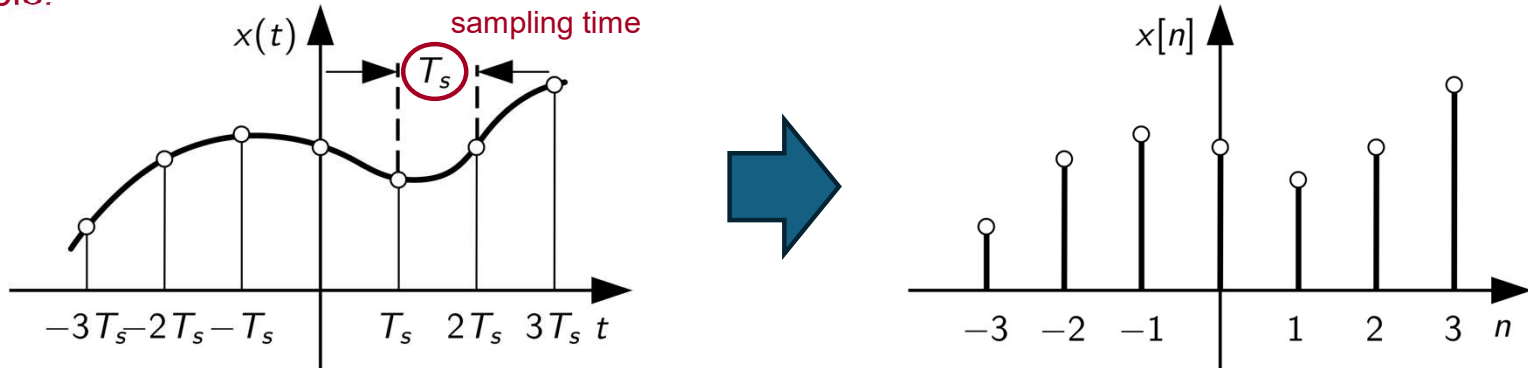


Sampling an analog signal

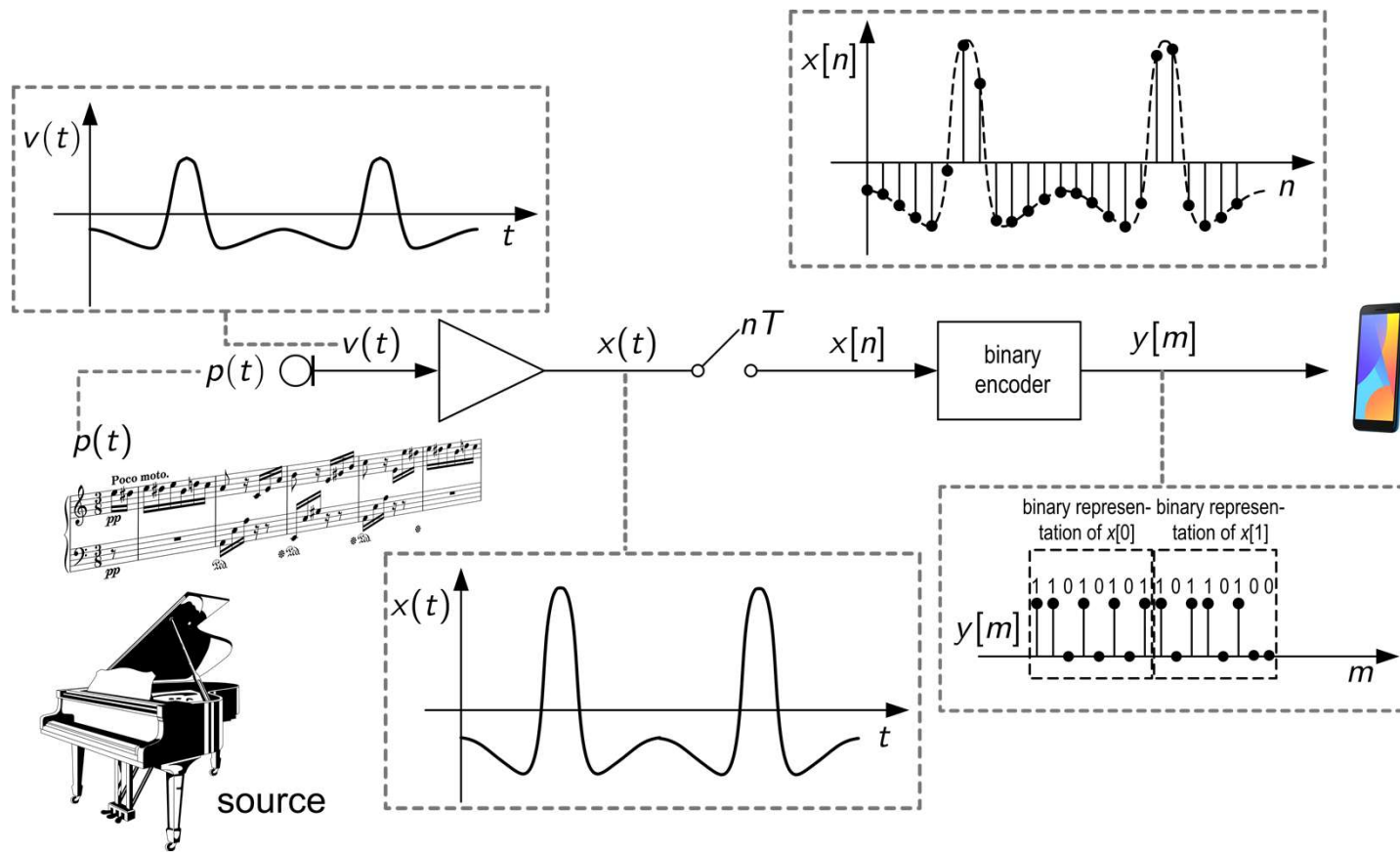
Sampling an analog signal $x(t)$ means collecting, one after the other, the **sequence** $x[n]$ of values taken by that signal at **time instants** nT_s :



Example:

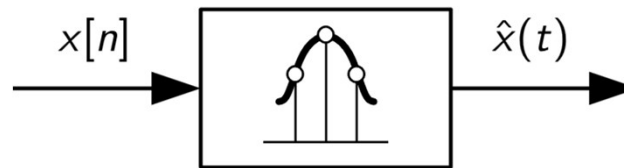


Example: digital recording of an audio signal

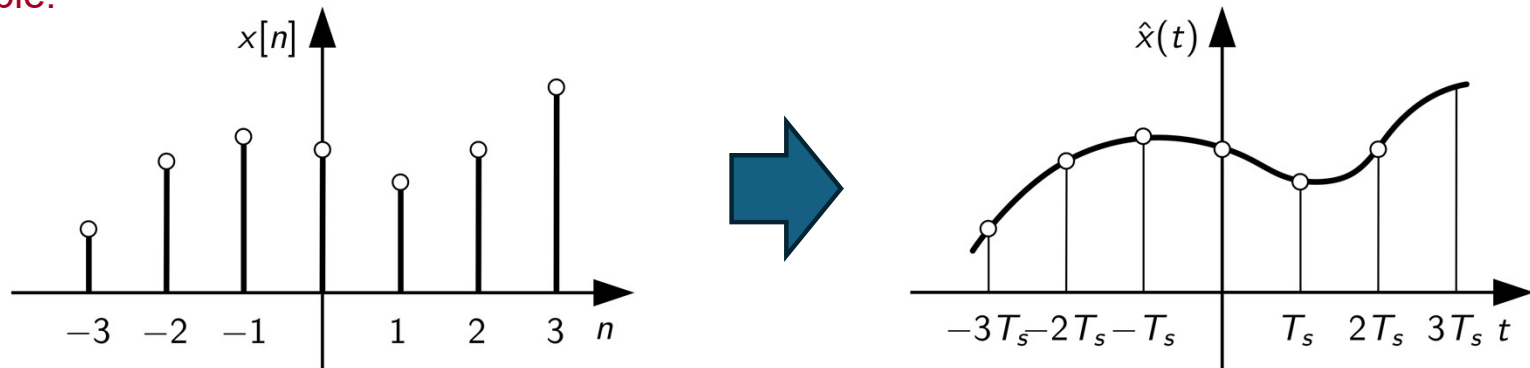


Back to the analog domain: interpolation

To **reconstruct**, with sufficiently high fidelity, the original signal starting from the sequence of samples, we can perform the operation of **interpolation**:

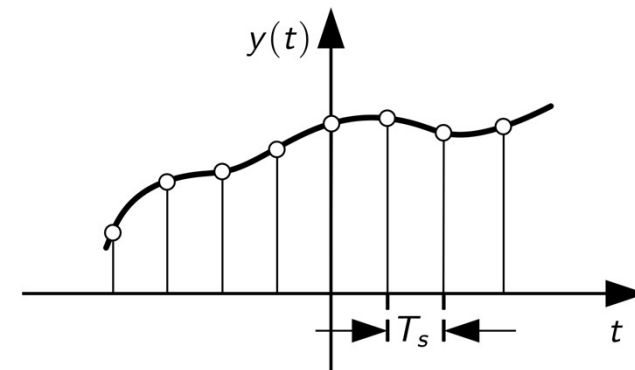
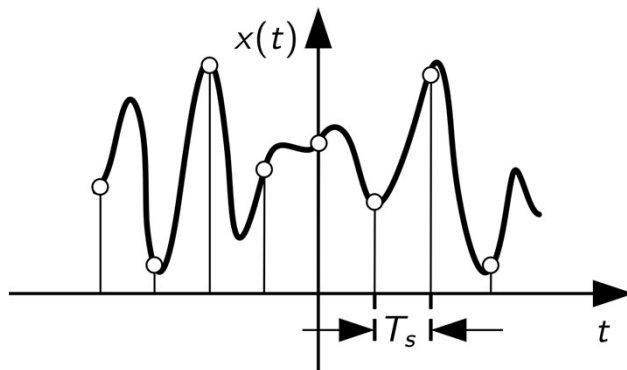


Example:



Sampling frequency (1/2)

The natural question is: how can we **properly set** the sampling frequency f_s ?



The sampling period is **adequate** for $y(t)$, but it is clearly **too large** for $x(t)$!

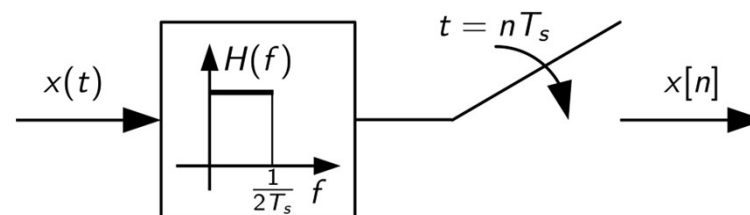
Note: increasing f_s (or equivalently, reducing T_s) means increasing the number of samples per unit of time, with drawbacks in terms of **hardware** and **storage** requirements

Sampling frequency (2/2)

To avoid **aliasing errors** when sampling a **strictly bandlimited** signal with bandwidth B , we need to satisfy the **Nyquist condition**:

$$f_s = \frac{1}{T_s} \geq 2B$$

In case of **band-unlimited** signals, we can place an **anti-aliasing** (low-pass) filter to limit the bandwidth of the analog signal, so as to avoid the aliasing error



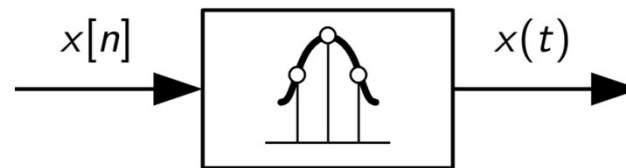


Interpolation

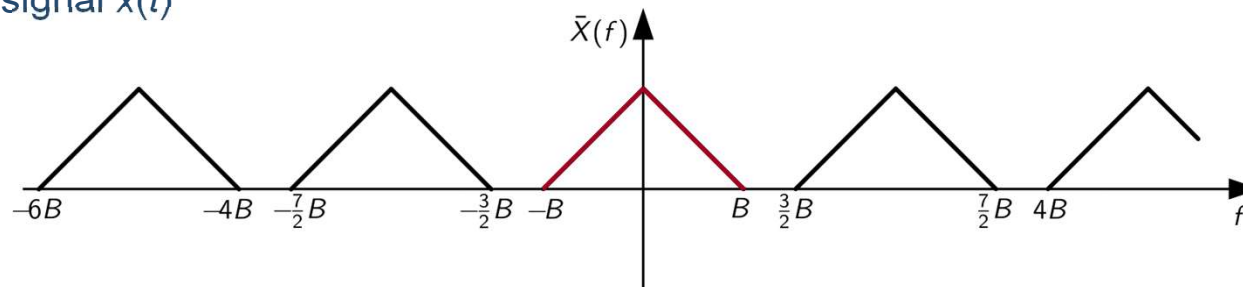
Interpolation (1/3)

How can we **reconstruct** the analog signal $x(t)$ starting from the sequence of samples $x[n]$?

This operation is called **interpolation** and is performed by the **digital-to-analog converter** (DAC)



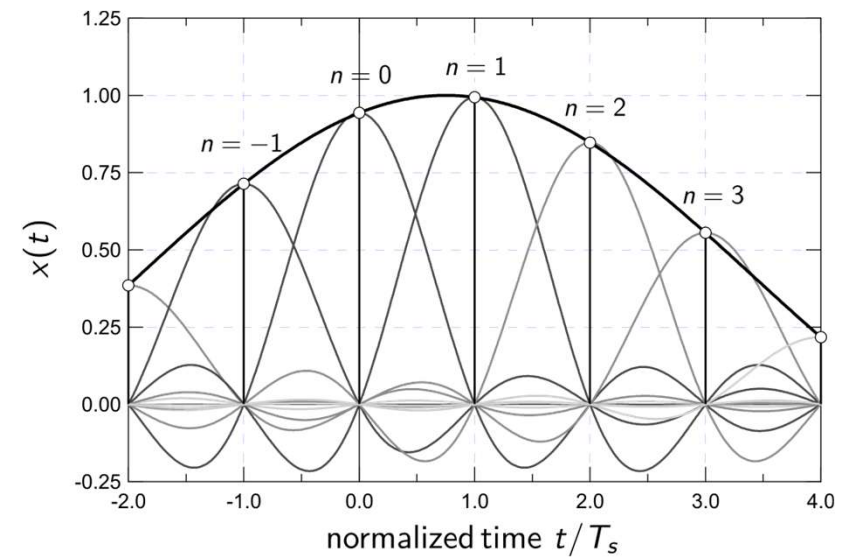
Ideally, we can apply a low-pass filtering on $x[n]$ to obtain back the original spectrum – and hence the original signal $x(t)$



Interpolation (2/3)

This goes under the name of **cardinal interpolation**, and is the result of the **Shannon's sampling theorem**:

$$x(t) = \sum_{n=-\infty}^{+\infty} x[n] \operatorname{sinc}\left(\frac{t - nT_s}{T_s}\right)$$

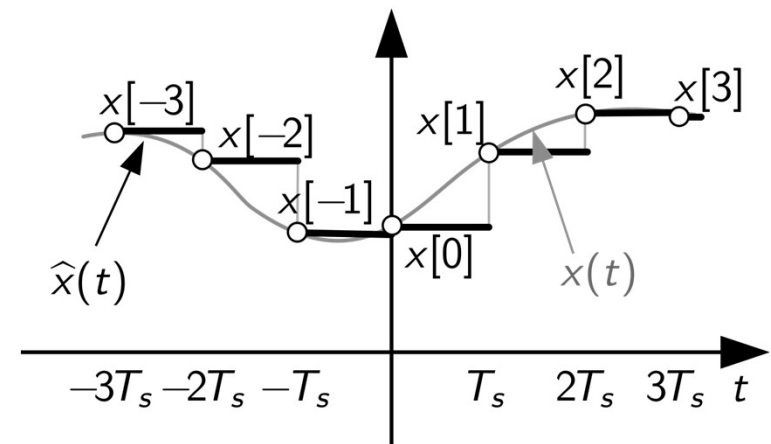
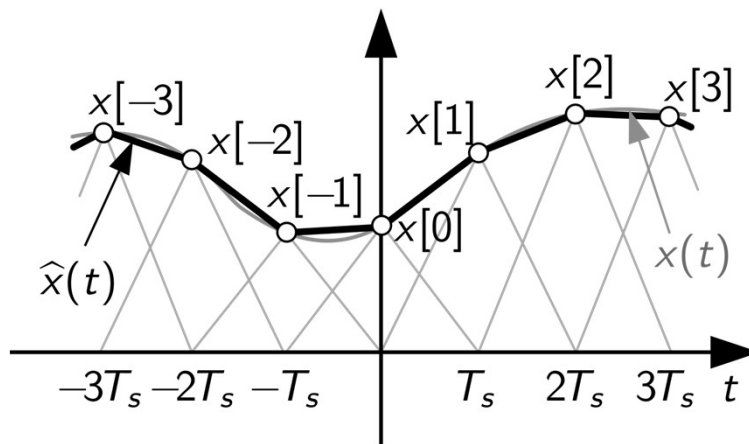


Interpolation (3/3)

The cardinal interpolator calls for an **infinite** number of samples, including **future** ones.

Simpler methods, yet achieving good results that provide an **approximated** version $\hat{x}(t)$ of the original signal, include:

- **linear interpolation**
- **sample & hold (S&H) interpolation**





Quantization

Quantization (1/3)

To transform an analog signal into a digital one, the job is not done just after sampling: we need to express the sample over a **finite number of bits**

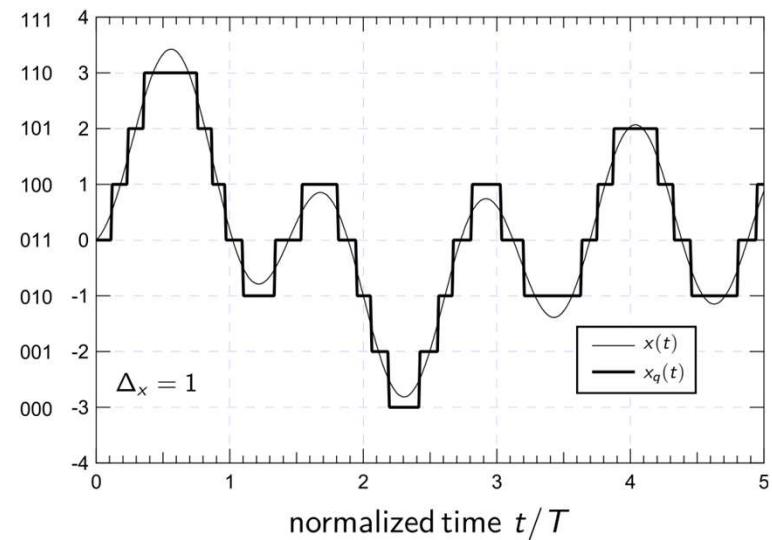
This task is called **quantization**, and works as follows:

$$x_q[n] = \Delta_x \cdot \left[\frac{x[n]}{\Delta_x} \right]$$

quantization step: $\Delta_x = \frac{D_x}{2^b - 1}$

b : number of quantization bits

rounding

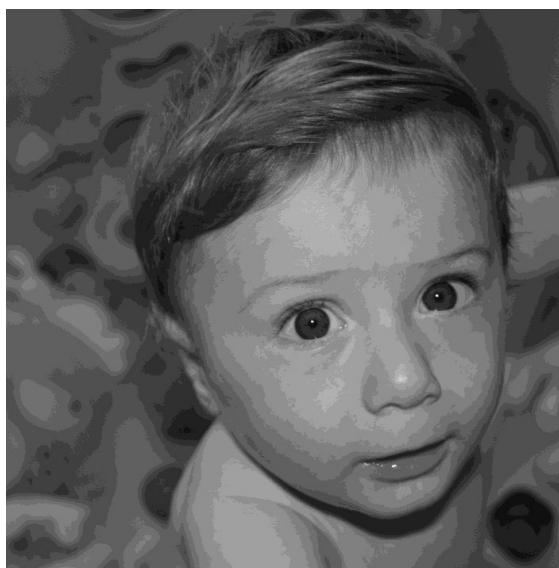


Quantization (2/3)

The impact of a different number of bits (i.e., number of intensity levels) can be easily visualized in a 2D image:



8 bits / pixel



4 bits / pixel



2 bits / pixel

Quantization (3/3)

We can also experience it in a musical song (*Help!* by The Beatles):



○ 16 bits/sample: 

○ 4 bits/sample: 

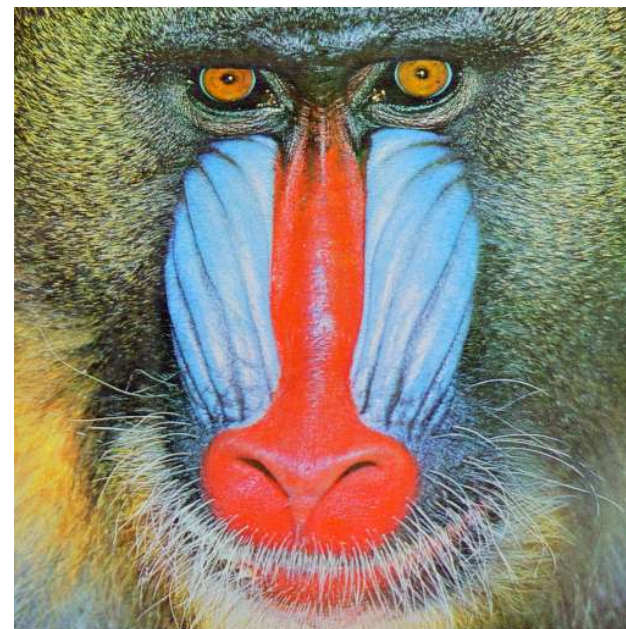
○ 2 bits/sample: 



Source coding

Source coding aims at data compression, involving encoding information to use **fewer bits** than the original representation:

- **Lossless compression** identifies and eliminates statistical redundancy
- **Lossy compression** identifies and removes unnecessary information



Examples of lossless compression

- **fixed-to-fixed code:** ASCII code
- **fixed-to-variable code:** Morse code
- **variable-to-fixed code:** Lempel-Ziv-Welch algorithm



An example of lossless compression: The ASCII code

dec	hex	oct	char	dec	hex	oct	char	dec	hex	oct	char	dec	hex	oct	char
0	0	000	NULL	32	20	040	space	64	40	100	@	96	60	140	`
1	1	001	SOH	33	21	041	!	65	41	101	A	97	61	141	a
2	2	002	STX	34	22	042	"	66	42	102	B	98	62	142	b
3	3	003	ETX	35	23	043	#	67	43	103	C	99	63	143	c
4	4	004	EOT	36	24	044	\$	68	44	104	D	100	64	144	d
5	5	005	ENQ	37	25	045	%	69	45	105	E	101	65	145	e
6	6	006	ACK	38	26	046	&	70	46	106	F	102	66	146	f
7	7	007	BEL	39	27	047	'	71	47	107	G	103	67	147	g
8	8	010	BS	40	28	050	(72	48	110	H	104	68	150	h
9	9	011	TAB	41	29	051)	73	49	111	I	105	69	151	i
10	a	012	LF	42	2a	052	*	74	4a	112	J	106	6a	152	j
11	b	013	VT	43	2b	053	+	75	4b	113	K	107	6b	153	k
12	c	014	FF	44	2c	054	,	76	4c	114	L	108	6c	154	l
13	d	015	CR	45	2d	055	-	77	4d	115	M	109	6d	155	m
14	e	016	SO	46	2e	056	.	78	4e	116	N	110	6e	156	n
15	f	017	SI	47	2f	057	/	79	4f	117	O	111	6f	157	o
16	10	020	DLE	48	30	060	0	80	50	120	P	112	70	160	p
17	11	021	DC1	49	31	061	1	81	51	121	Q	113	71	161	q
18	12	022	DC2	50	32	062	2	82	52	122	R	114	72	162	r
19	13	023	DC3	51	33	063	3	83	53	123	S	115	73	163	s
20	14	024	DC4	52	34	064	4	84	54	124	T	116	74	164	t
21	15	025	NAK	53	35	065	5	85	55	125	U	117	75	165	u
22	16	026	SYN	54	36	066	6	86	56	126	V	118	76	166	v
23	17	027	ETB	55	37	067	7	87	57	127	W	119	77	167	w
24	18	030	CAN	56	38	070	8	88	58	130	X	120	78	170	x
25	19	031	EM	57	39	071	9	89	59	131	Y	121	79	171	y
26	1a	032	SUB	58	3a	072	:	90	5a	132	Z	122	7a	172	z
27	1b	033	ESC	59	3b	073	;	91	5b	133	[123	7b	173	{
28	1c	034	FS	60	3c	074	<	92	5c	134	\	124	7c	174	
29	1d	035	GS	61	3d	075	=	93	5d	135]	125	7d	175	}
30	1e	036	RS	62	3e	076	>	94	5e	136	^	126	7e	176	~
31	1f	037	US	63	3f	077	?	95	5f	137	_	127	7f	177	DEL

An example of lossless compression: The Morse code

International Morse Code

1. The length of a dot is one unit.
2. A dash is three units.
3. The space between parts of the same letter is one unit.
4. The space between letters is three units.
5. The space between words is seven units.

A	• —	U	• • —
B	— • • •	V	• • • —
C	— • — •	W	• — —
D	— • •	X	— • • —
E	•	Y	— • — —
F	• • — •	Z	— — • •
G	— — •		
H	• • • •		
I	• •		
J	• — — —	1	• — — — —
K	— • — —	2	• • — — —
L	• — • •	3	• • • — —
M	— — •	4	• • • • —
N	— •	5	• • • • •
O	— — — —	6	— • • • •
P	• — — — •	7	— — • • •
Q	— — • — —	8	— — — • •
R	• — • •	9	— — — — •
S	• • •	0	— — — — —
T	—		

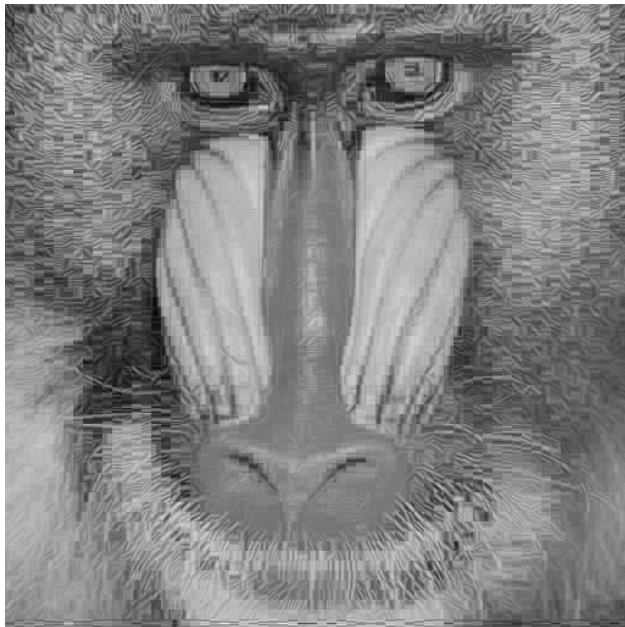
The Lempel-Ziv-Welch (LZW) algorithm

- Lempel and Ziv patented the algorithm in 1978 as **LZ78**
- Welch further **improved** the algorithm in 1984
- easy and universal implementation, widely used for **zip** (and its variants) and **GIF** formats
- the original LZW algorithm encodes sequences as **fixed-length 12-bit sequences**

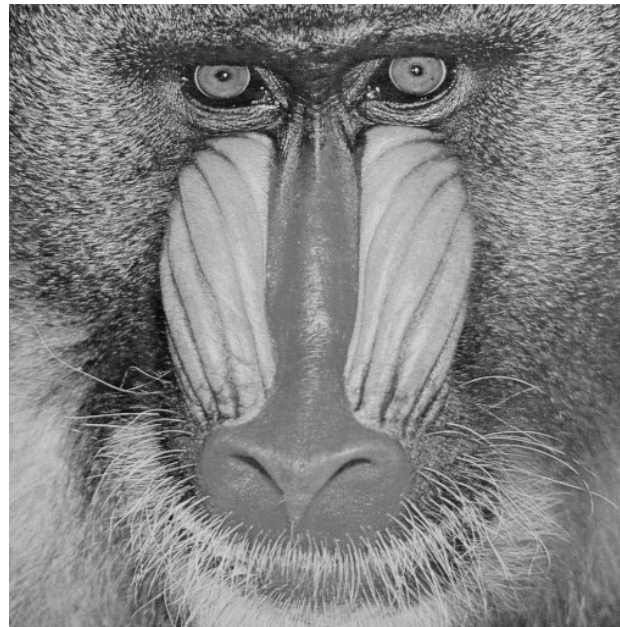


An example of lossy compression: image coding

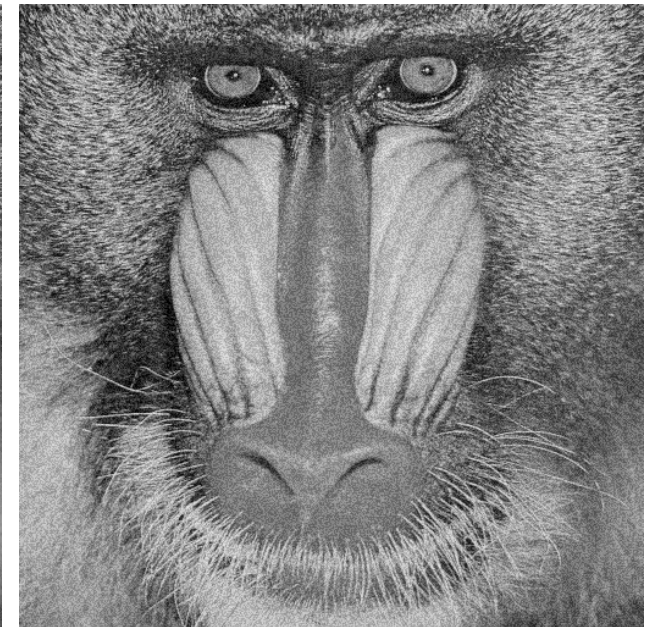
Image coding adopts a **lossy compression**, which is based on the specific properties of the **human vision**



altered #1

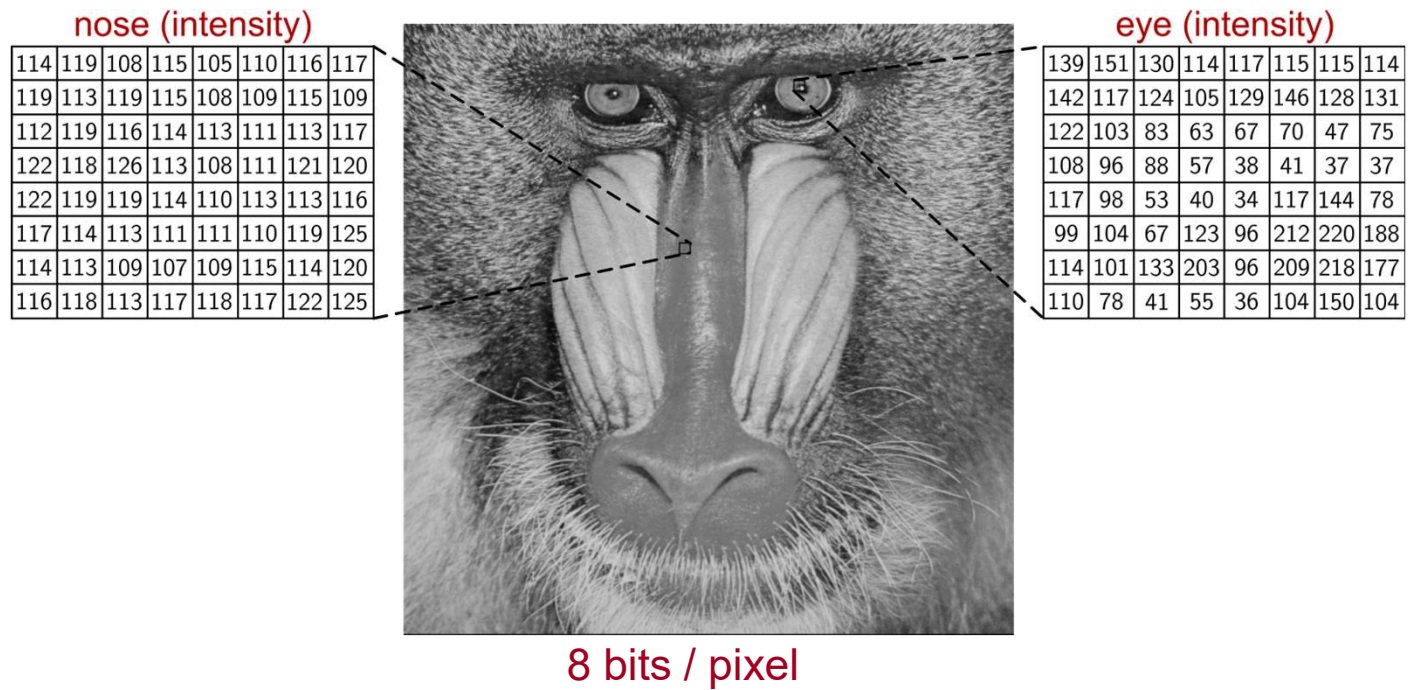


original



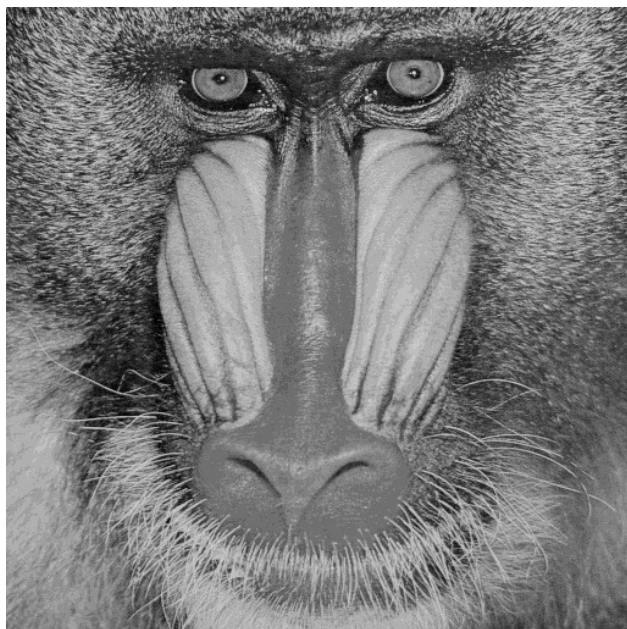
altered #2

Image representation

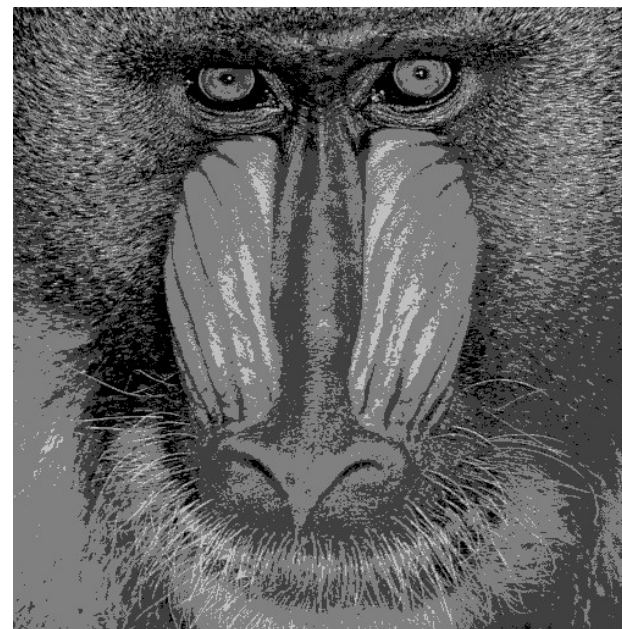


Quantization in the space domain

Raw quantization:



4 bits / pixel

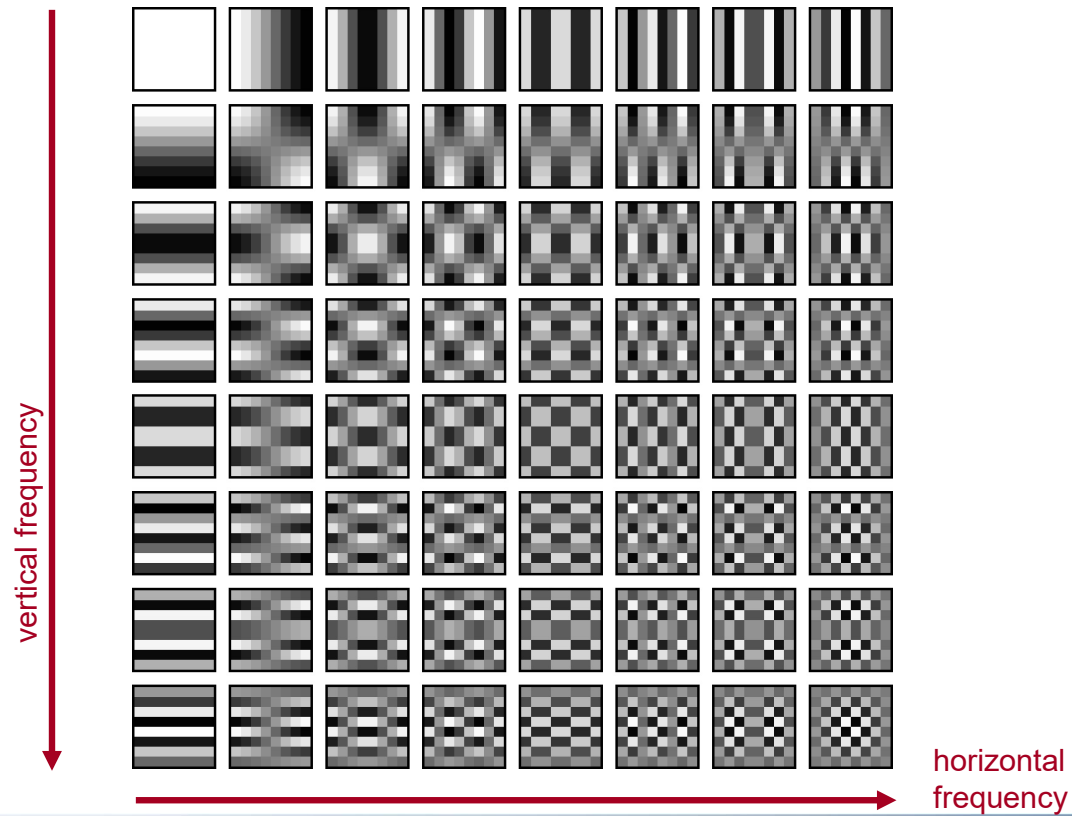


2 bits / pixel



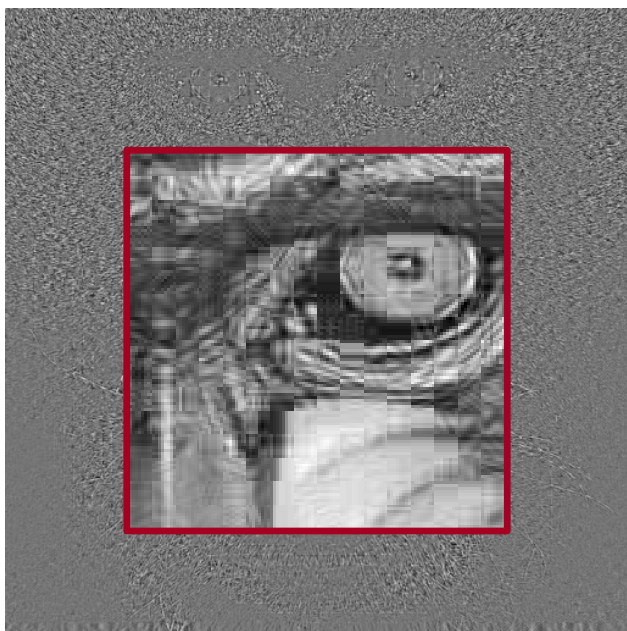
Discrete cosine transform (DCT) (1/3)

Contribution of DCT coefficients to the appearance of the 8×8 pixel block:



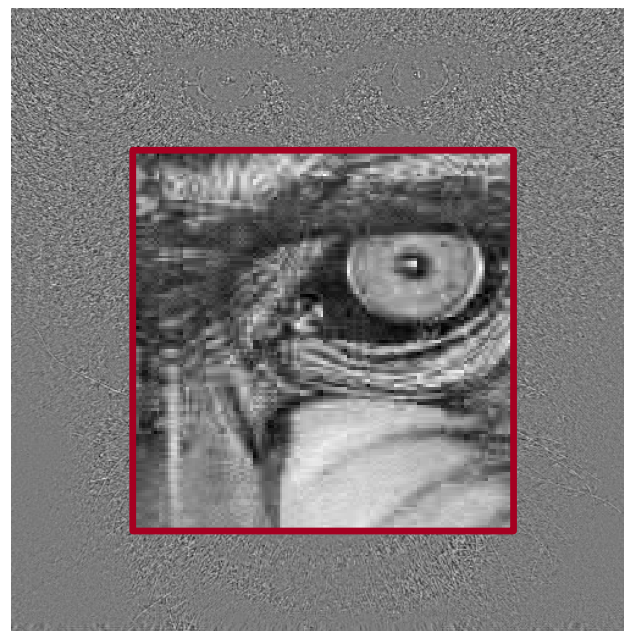
Discrete cosine transform (DCT) (2/3)

DFT



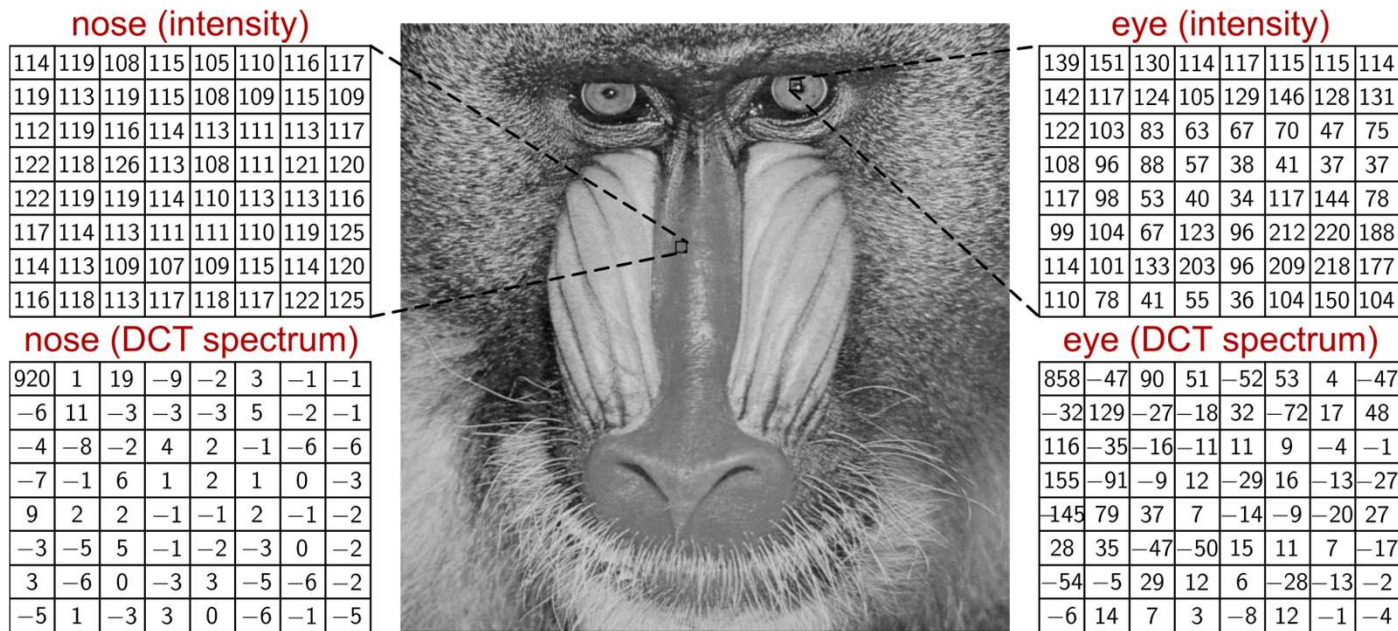
vs.

DCT



Discrete cosine transform (DCT) (3/3)

Image analysis using DCT:



Quantization: space vs. frequency (1/3)

Quantization tables:

1	1	1	2	4	8	16	32
1	1	2	2	4	8	16	32
1	2	4	4	8	16	32	64
2	2	4	8	16	32	32	64
4	4	8	16	16	32	64	128
8	8	16	32	32	128	128	256
16	16	32	32	64	128	256	256
32	32	64	64	128	256	256	256

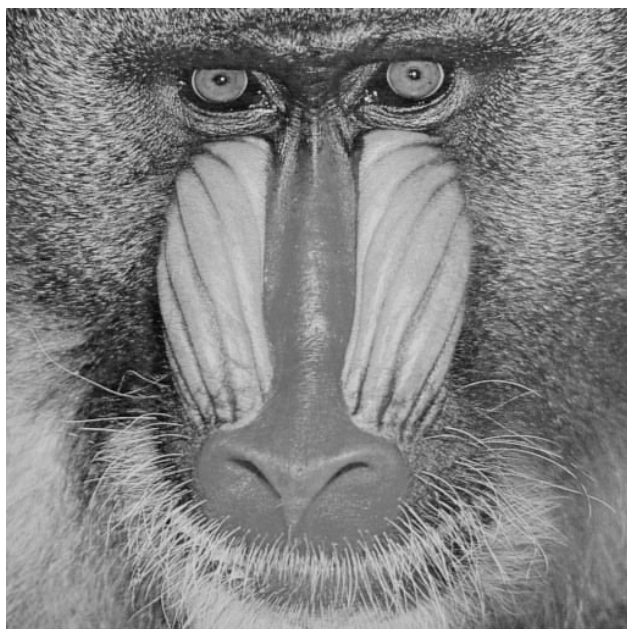
low compression

1	2	4	8	16	16	32	64
2	2	4	8	16	128	256	256
4	4	8	16	64	256	256	256
8	8	16	64	256	256	256	256
16	16	64	256	256	256	256	256
16	128	256	256	256	256	256	256
32	256	256	256	256	256	256	256
64	256	256	256	256	256	256	256

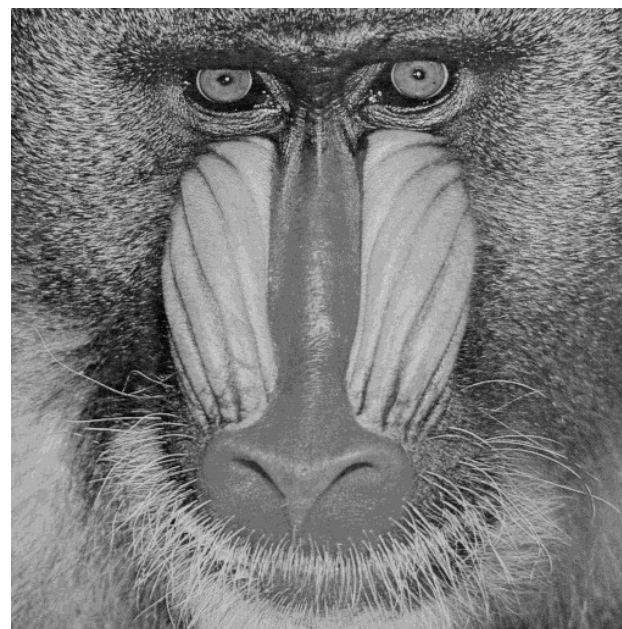
high compression

Quantization: space vs. frequency (2/3)

50% original file size



DCT-based quantization

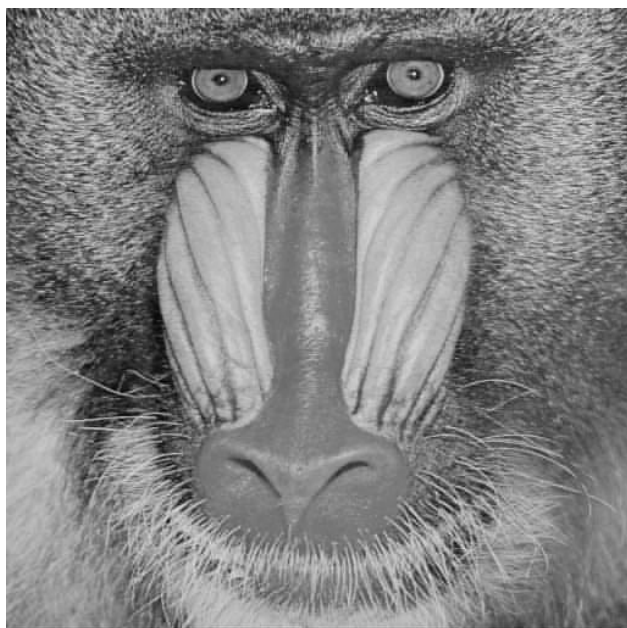


raw quantization

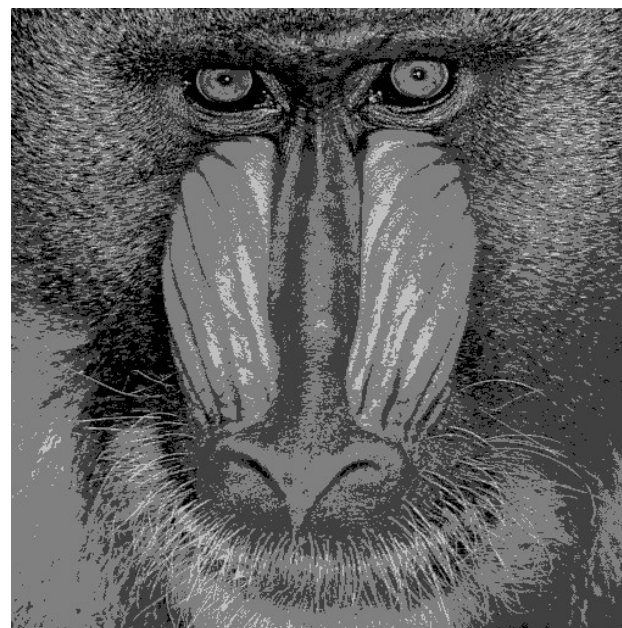


Quantization: space vs. frequency (3/3)

25% original file size



DCT-based quantization



raw quantization



The joint picture expert group (JPEG) algorithm

JPEG encoding scheme:



JPEG decoding scheme:



Quantization in the frequency domain

Quantization matrix (with zig-zag scanning):

16	11	10	16	24	40	51	61
12	12	14	19	26	58	60	55
14	13	16	24	40	57	69	56
14	17	22	29	51	87	80	62
18	22	37	56	68	109	103	77
24	35	55	64	81	104	113	92
49	64	78	87	103	121	120	101
72	92	95	98	112	100	103	99

Examples of compressed images (1/4)



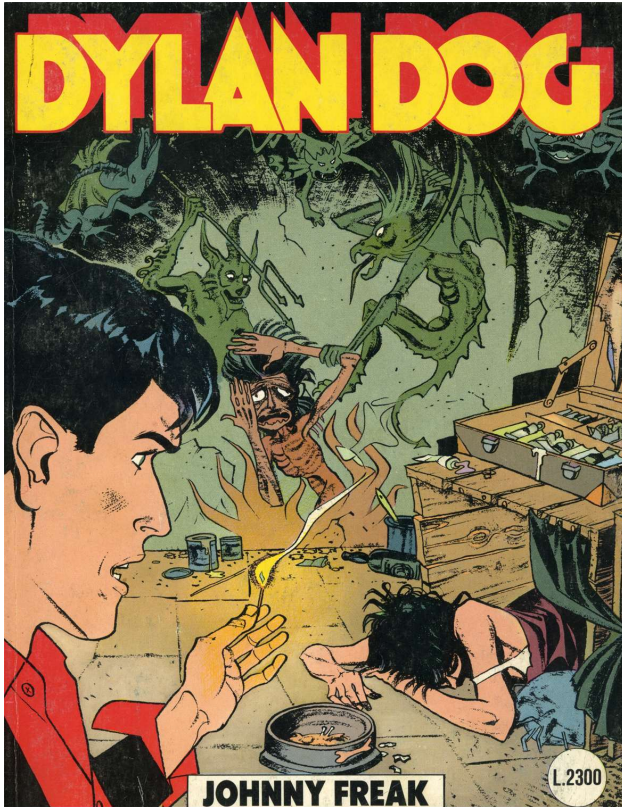
original image



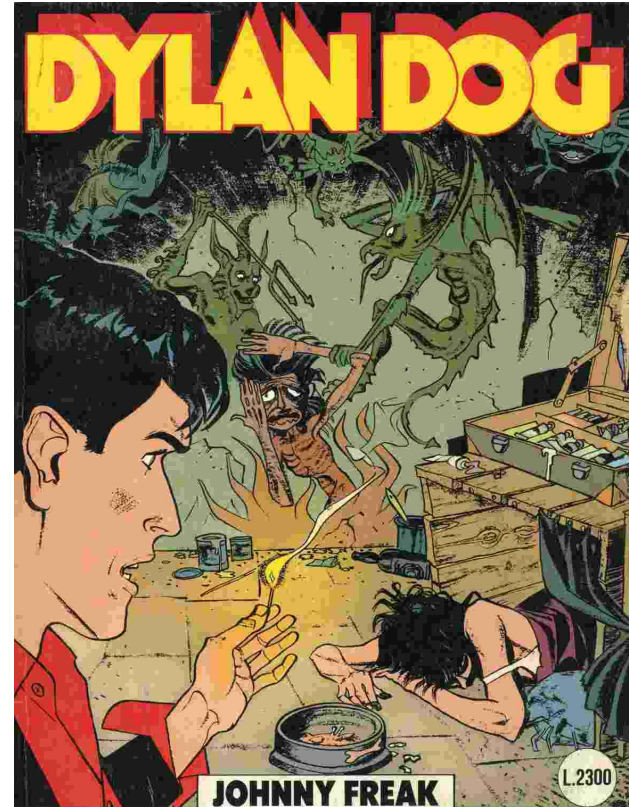
compressed image (ratio 1:10)



Examples of compressed images (2/4)



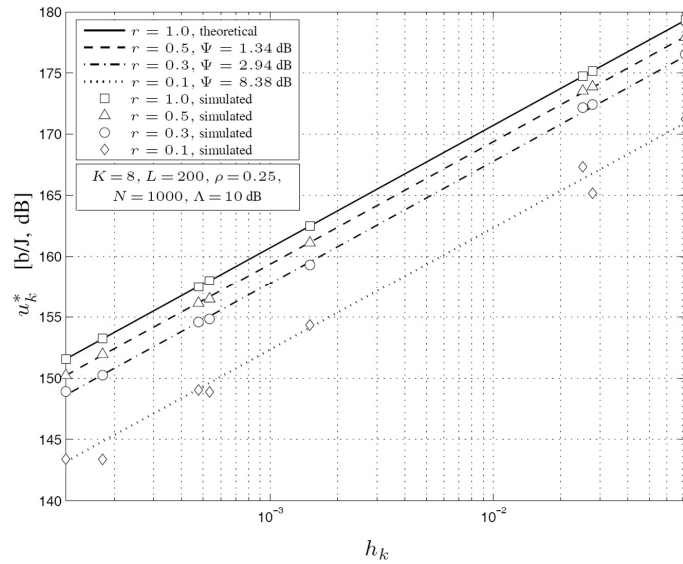
original image



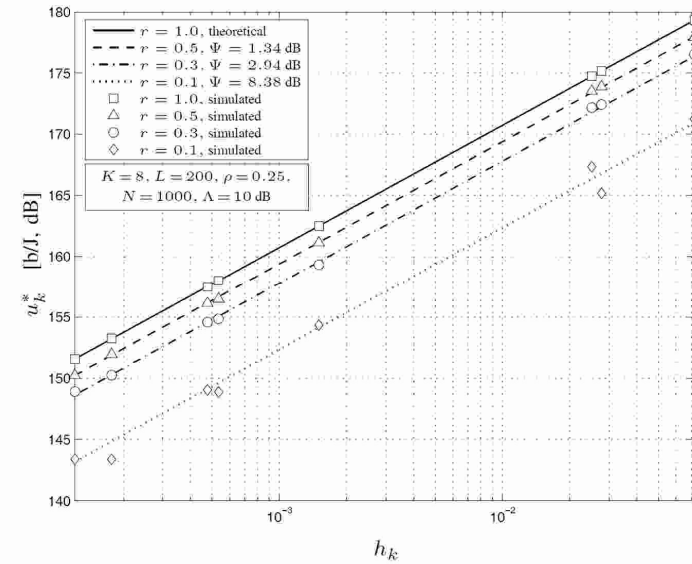
compressed image (ratio 1:10)



Examples of compressed images (3/4)



original image



compressed image (ratio 1:10)



Examples of compressed images (4/4)



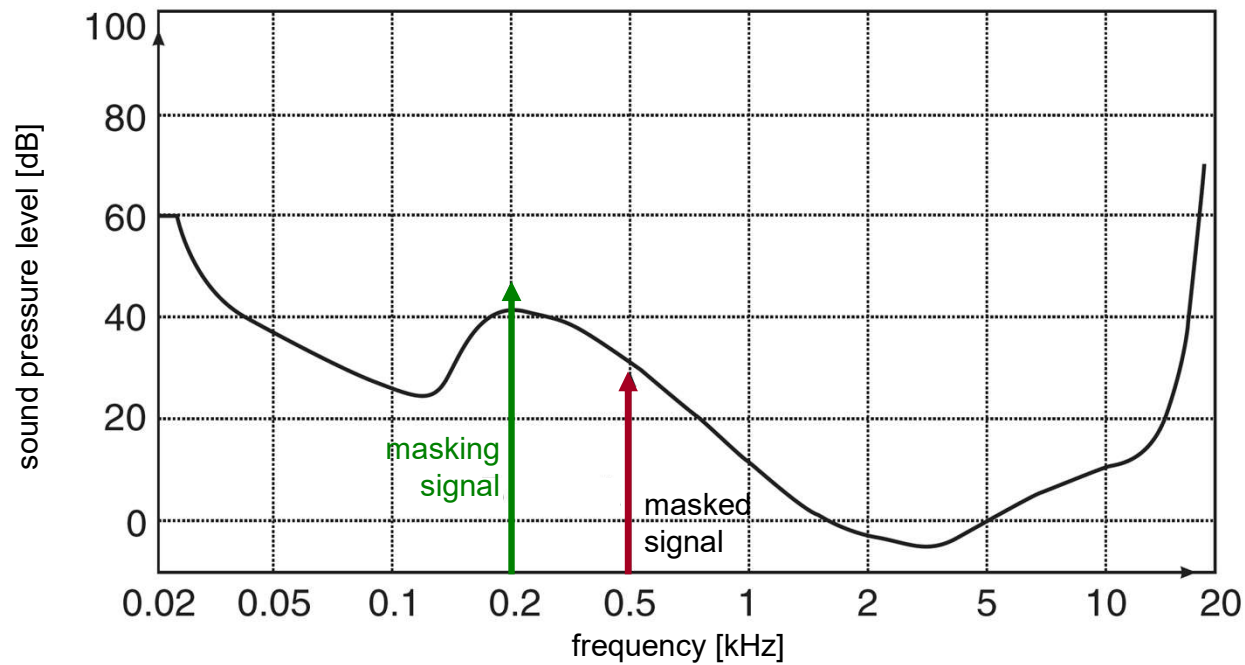
2.66 MB



7.02 MB




Basics of audio coding (1/2)

Similarly, audio coding adopts a lossy compression, again based on the **psycho-acoustic model**



Basics of audio coding (2/2)

Audio coding, like image coding, is based on the **semantics** of the source:

- Uncompressed, CD-quality audio (1.41 Mb/s): 
- Compressed, MPEG-1/2 audio layer III (MP3) audio (32 kb/s): 
- Compressed using JPEG algorithm (32 kb/s): 

Why do we need compressed videos?

high-definition video (HD):

- component resolution (R, G, B): 8 bits / component
- color image composition: 3 components / pixel
- resolution: 1920 × 1080 pixels / frame
- image refresh rate: 60 frames / s

$$R_b = (8 \cdot 3 \cdot 1920 \cdot 1080 \cdot 60) \text{ b/s} \approx 2.99 \text{ Gb/s}$$

ultra-high-definition video (UHD, aka 4k):

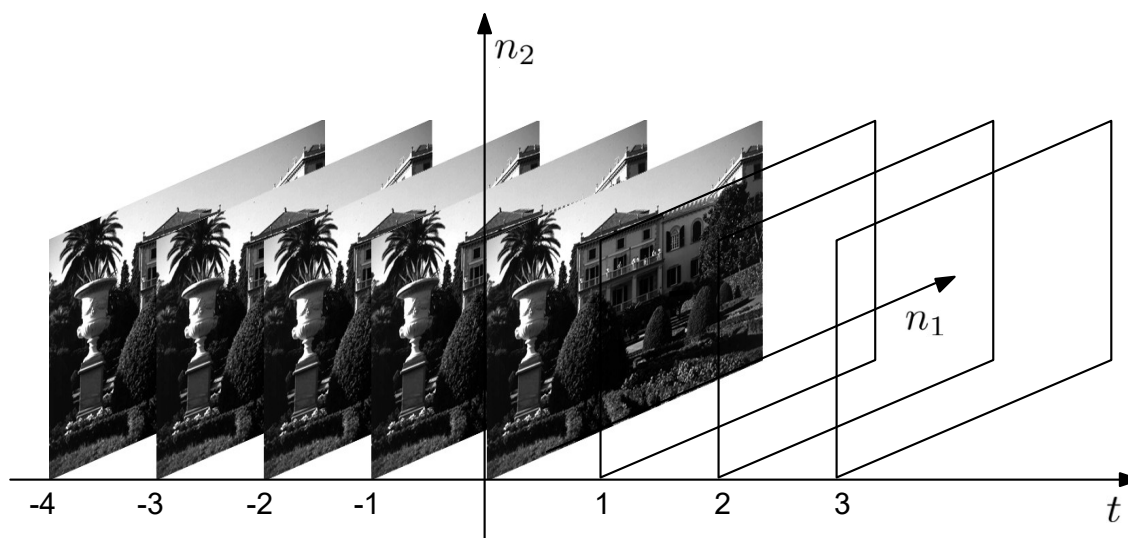
- 3840 × 2160 pixels / frame, using 120 f/s refresh rate and 48 bits per pixel

$$R_b = (16 \cdot 3 \cdot 3840 \cdot 2160 \cdot 120) \text{ b/s} \approx 47.78 \text{ Gb/s}$$

Principles of video coding

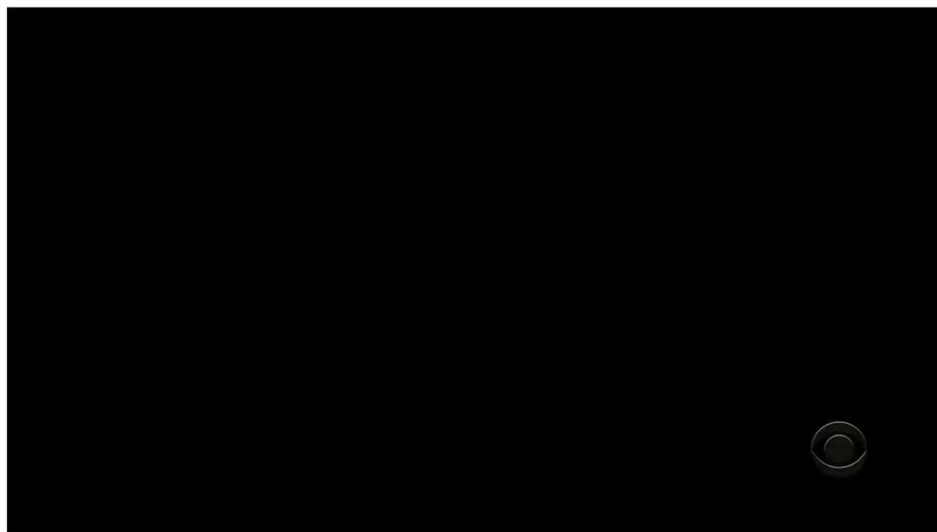
We can compress a video stream, based on:

- **spatial correlation**, using the same principles exploited in image compressing
- **temporal correlation**, using time memory across successive frames



Examples of videos

poorly time-correlated video

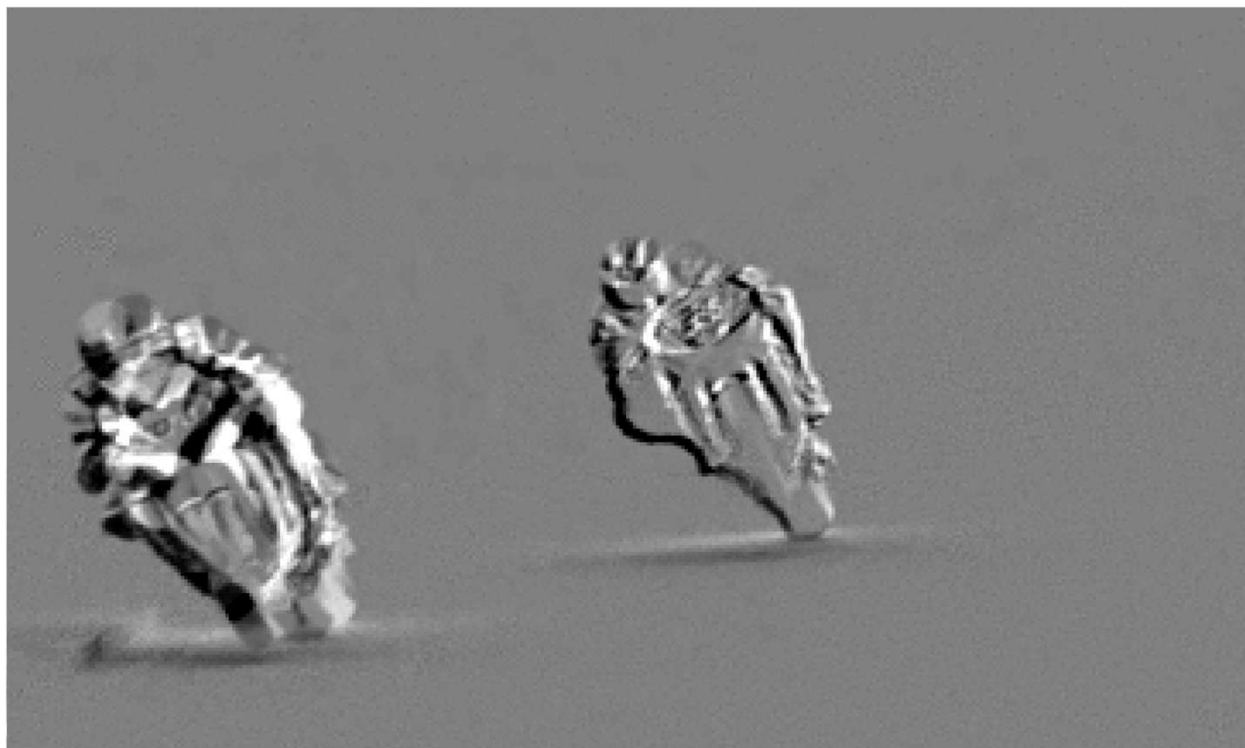


highly time-correlated video



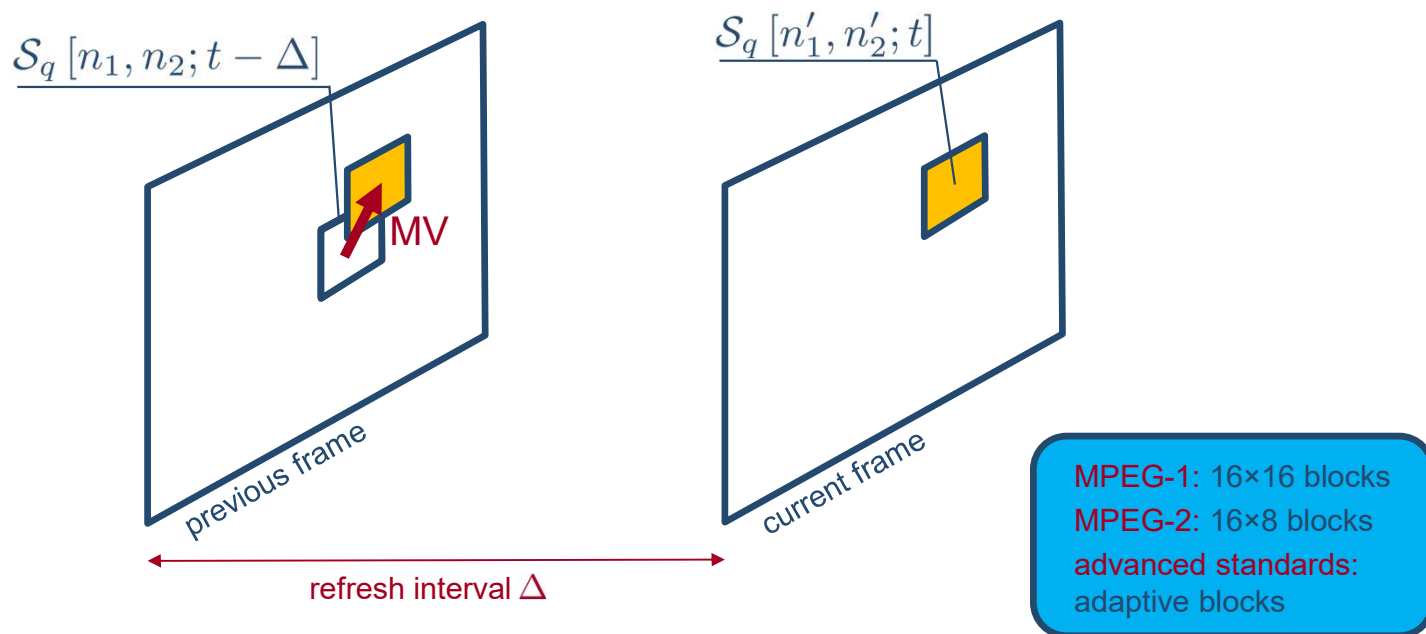
Time correlation

$$S[n_1, n_2; t] - S[n_1, n_2; t - \Delta]$$



Motion prediction (1/3)

Effective video compression techniques rely on **motion prediction** based on **motion vectors (MVs)**:



Motion prediction (2/3)

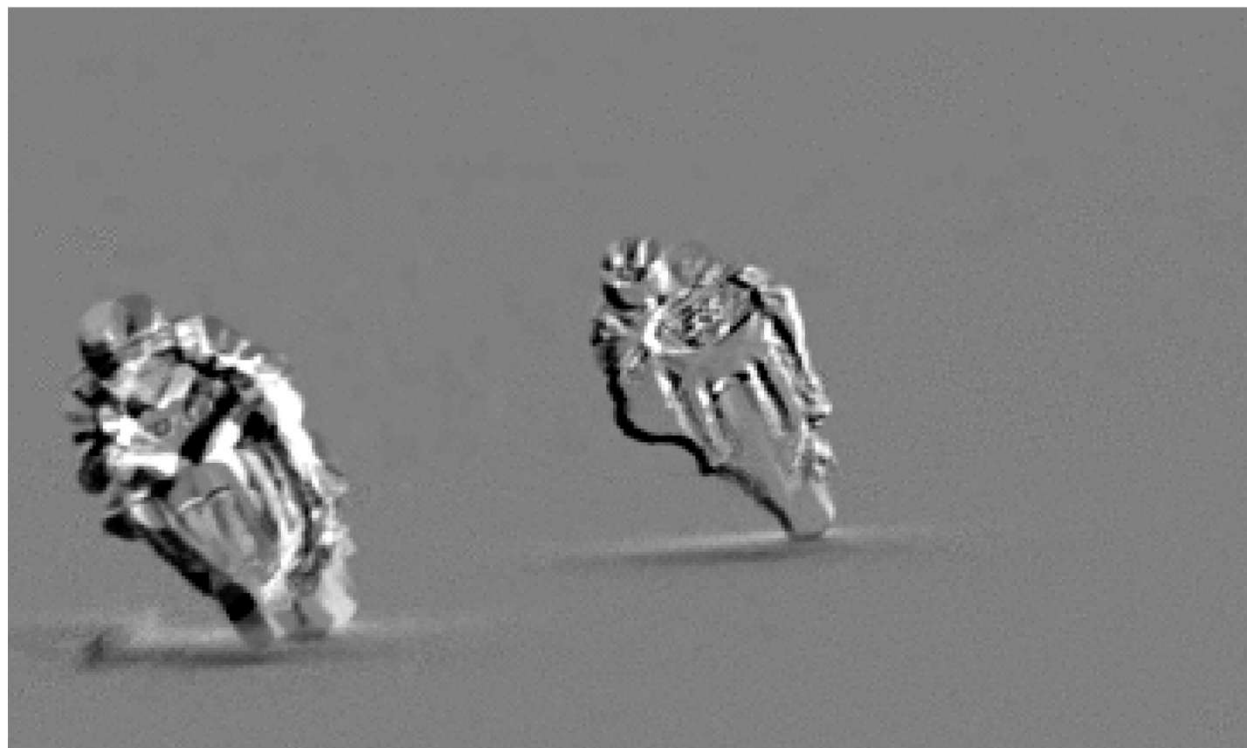


Motion prediction (3/3)



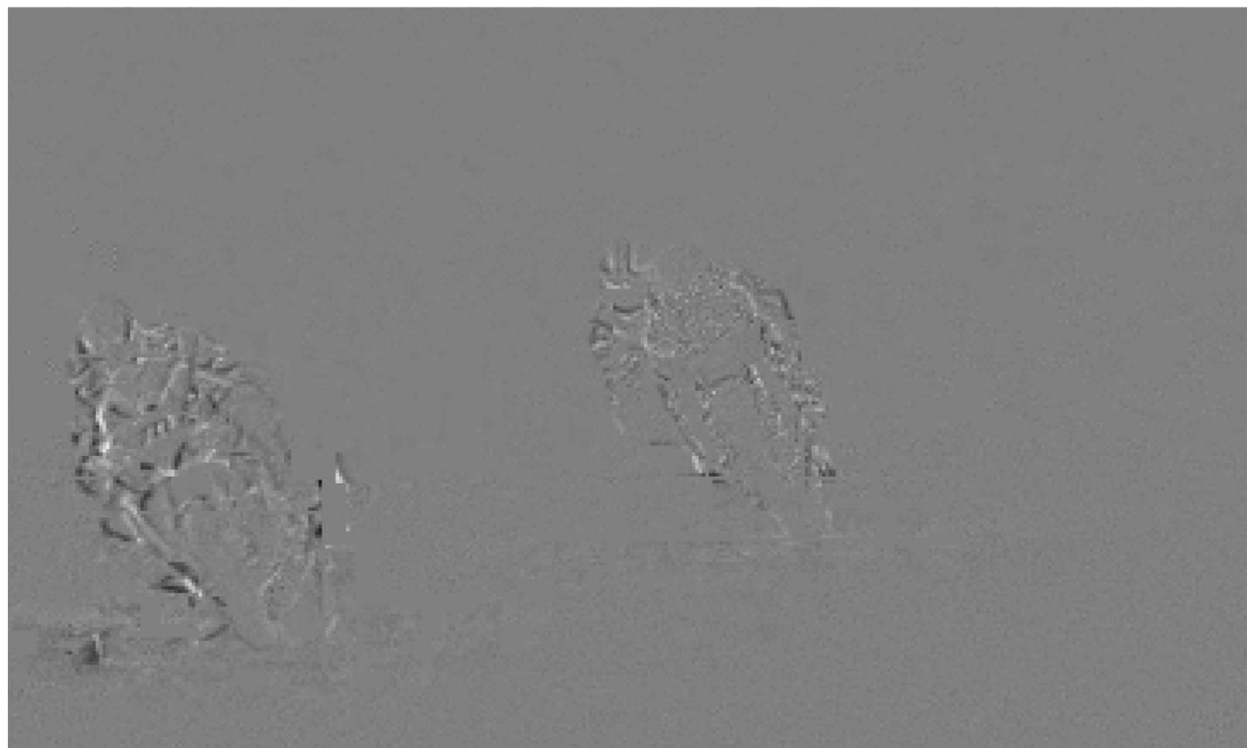
Motion compensation (1/2)

$$\mathcal{S}[n_1, n_2; t] - \mathcal{S}[n_1, n_2; t - \Delta] \quad (\text{without MC})$$



Motion compensation (2/2)

$$\mathcal{S}[n_1, n_2; t] - \hat{\mathcal{S}}[n_1, n_2; t] \quad (\text{with MC})$$

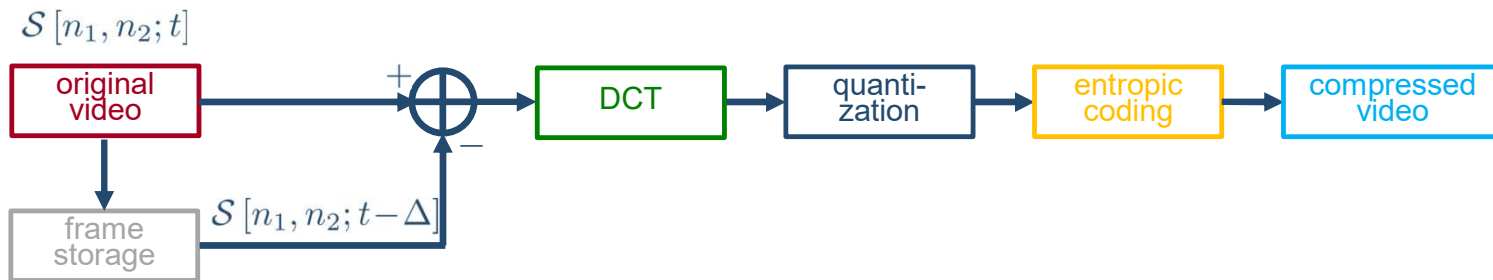


Motion picture expert group (MPEG) scheme (1/3)

MPEG encoding scheme without time correlation:

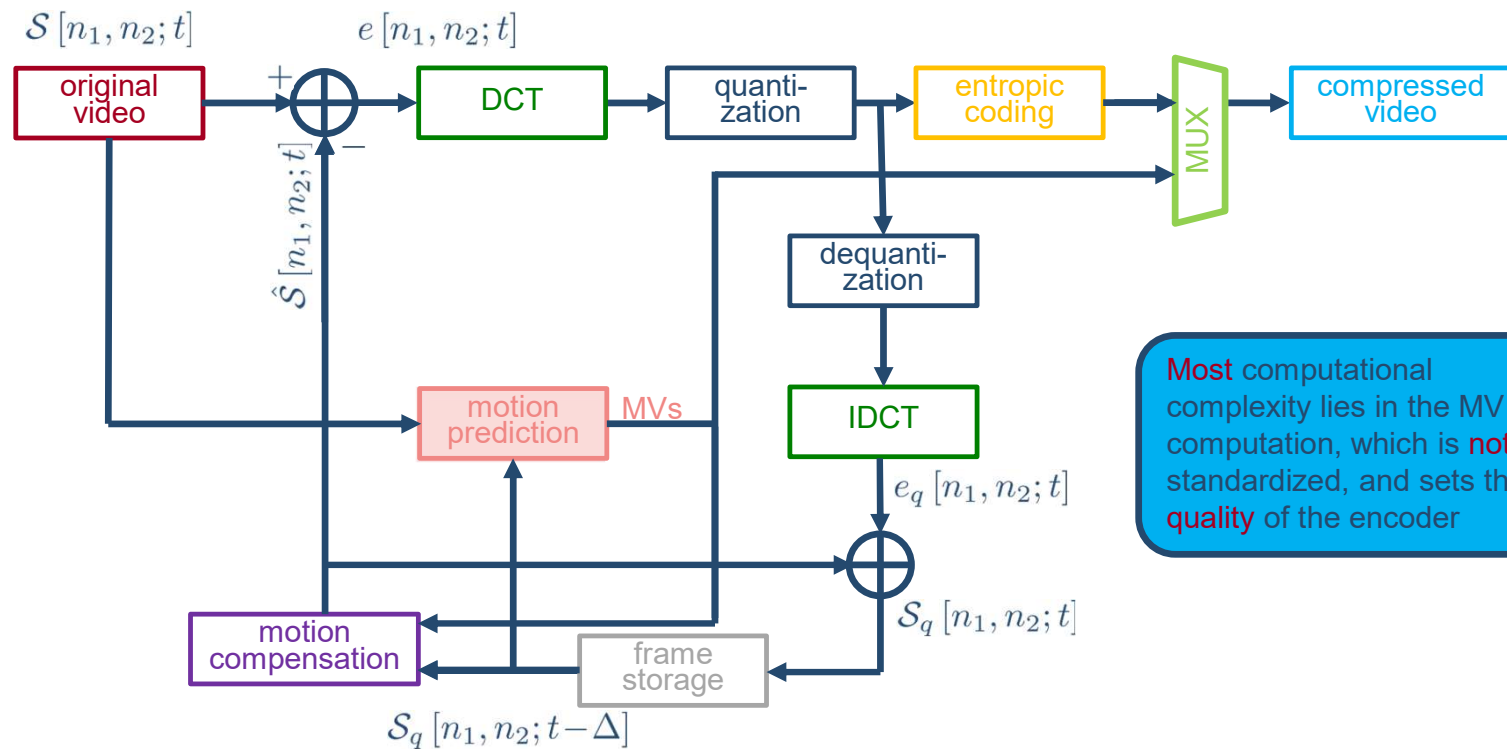


MPEG encoding scheme without motion compensation (MC):



Motion picture expert group (MPEG) scheme (2/3)

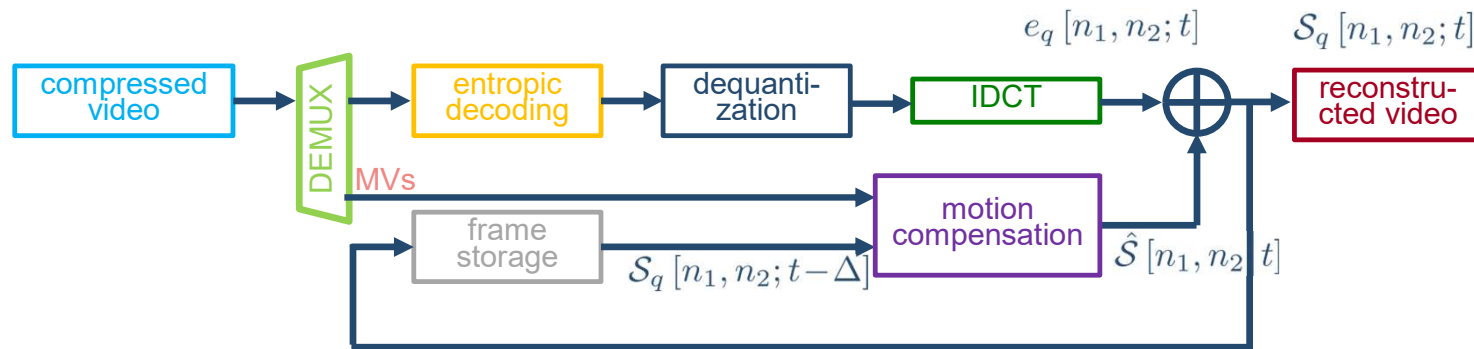
MPEG encoding scheme with MC:



Most computational complexity lies in the MV computation, which is **not** standardized, and sets the **quality** of the encoder

Motion picture expert group (MPEG) scheme (3/3)

MPEG decoding scheme:



- the MPEG encoder implements **locally** a decoder, in order to control the deviation between the two streams
- since there is **no** motion prediction at the decoder, it can be implemented with a **low-complexity architecture**

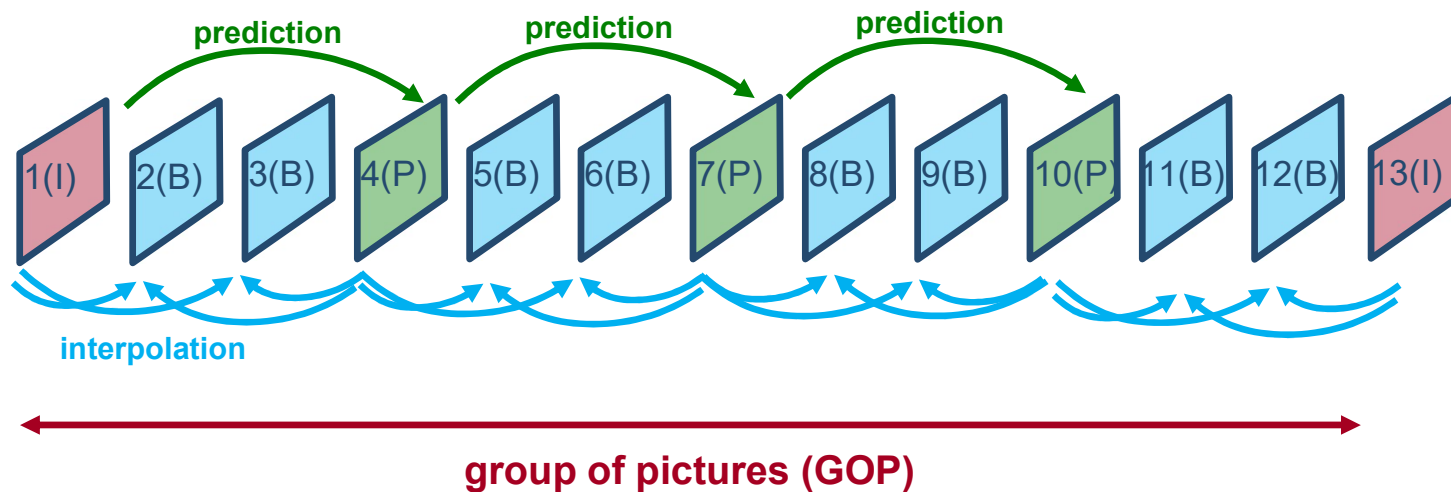
Group of pictures (GOP) (1/3)

Additional compression can be achieved by arranging the frames into:

- **I (intra)** pictures, coded without reference to other pictures, similarly to JPEG, also used for random access – *low compression*
- **P (predicted)** pictures, coded from preceding I or P frames, using MC – *medium compression*
- **B (bi-directionally predicted)** pictures, coded by bi-directional interpolation between I and/or P frames which precedes and follows them – *high compression*

Group of pictures (GOP) (2/3)

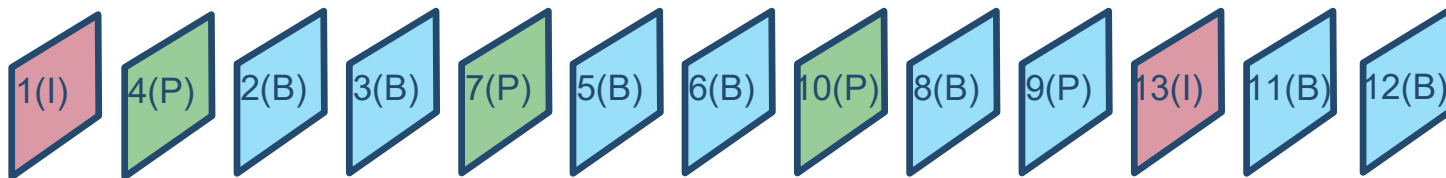
Concatenation of frames in the video stream:



In this example, the GOP is composed by 12 frames, with 3 frames between two successive P pictures

Group of pictures (GOP) (3/3)

To enable a correct decoding, the sequence of encoded frames is:



Picture re-ordering is needed at both the encoding and the decoding side (the latter needs to gather the information on the frame type based on the metadata included in the encoded stream)

Examples of MPEG-2 compressed videos (1/3)



6 MB/s



4 MB/s



1.5 MB/s



Examples of MPEG-2 compressed videos (2/3)



6 MB/s



4 MB/s



1.5 MB/s



Examples of MPEG-2 compressed videos (3/3)



6 MB/s



4 MB/s



1.5 MB/s



Evolution of video compression standards (1/4)

The **MPEG-2 standard** (a.k.a. H.222/H.262) was designed to target standard definition (SD) used for DVD videos (first release: 1996)

With the increasing demand for additional quality, other standards have been deployed:

- **advanced video coding (AVC)**, also referred to as H.264 or MPEG-4 Part 10 (first release: 2004), targets high definition (HD), thanks to adaptive macro-blocks, more effective entropic coding and lossy compression techniques
- **high efficiency video coding (HEVC)**, also known as H.265 and MPEG-H Part 2 (first release: 2013), targets ultra-high-definition (UHD), thanks to improved MV prediction and motion compensation



Evolution of video compression standards (2/4)

MPEG-2: 3.54 MB



Evolution of video compression standards (3/4)

AVC: 1.19 MB



Evolution of video compression standards (4/4)

HEVC: 1.04 MB





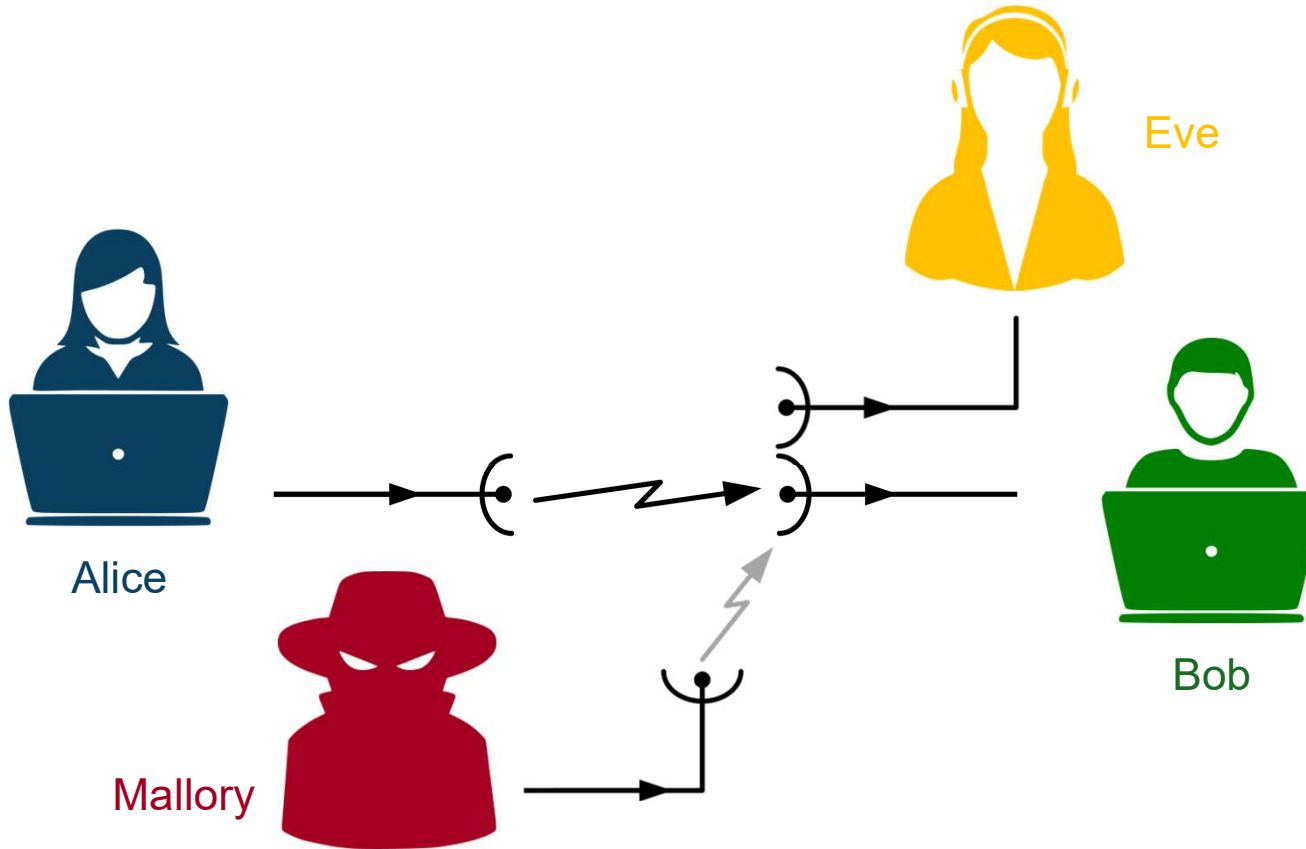
Encryption

Features of encrypted communications

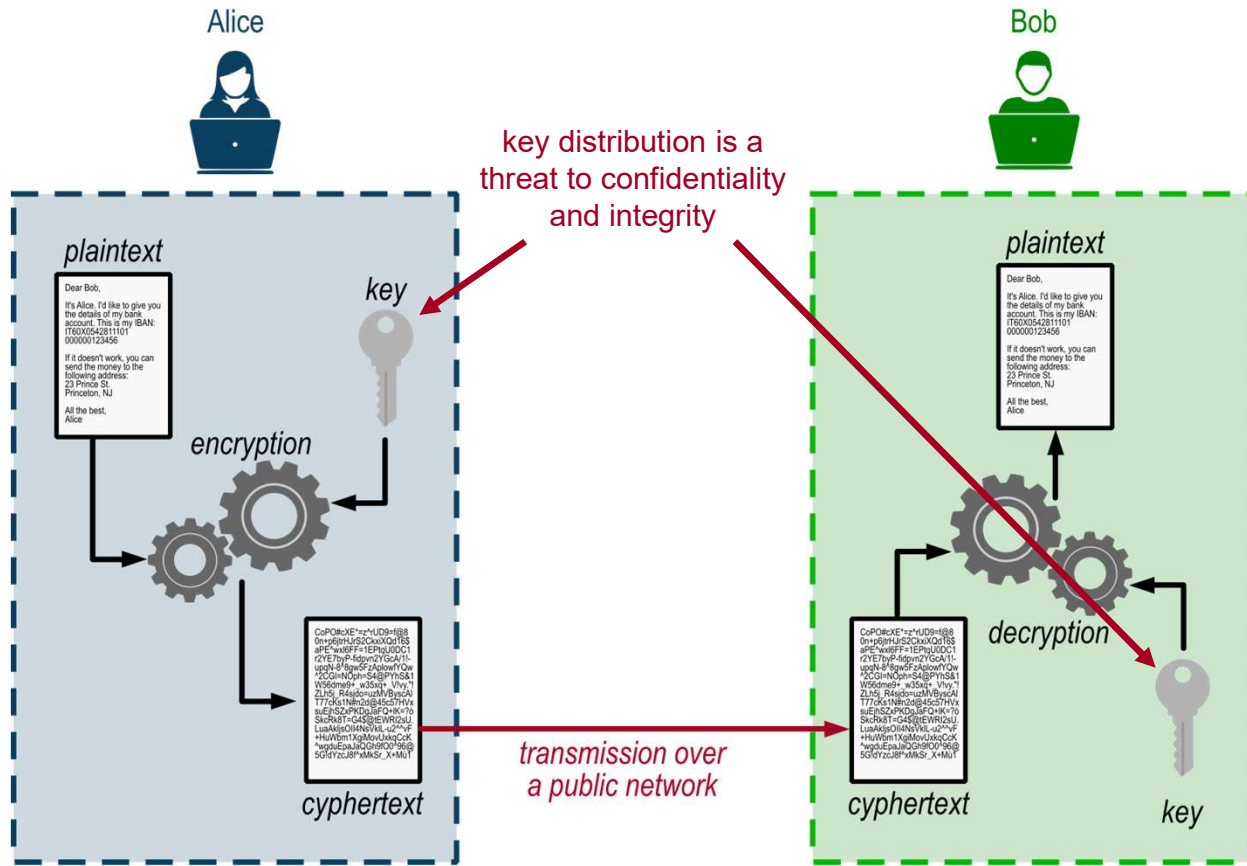
- **Confidentiality:** third-party cannot read exchanged data
attacks: eavesdropping, sniffing
- **Integrity:** third-party cannot change exchanged data
attacks: man-in-the-middle
- **Authentication:** each party is sure who is really communicating with
attacks: masquerading, spoofing, traffic generation
- **Availability:** time the system is in a functioning condition
attacks: denial of service (DoS), distributed DoS (DDoS)



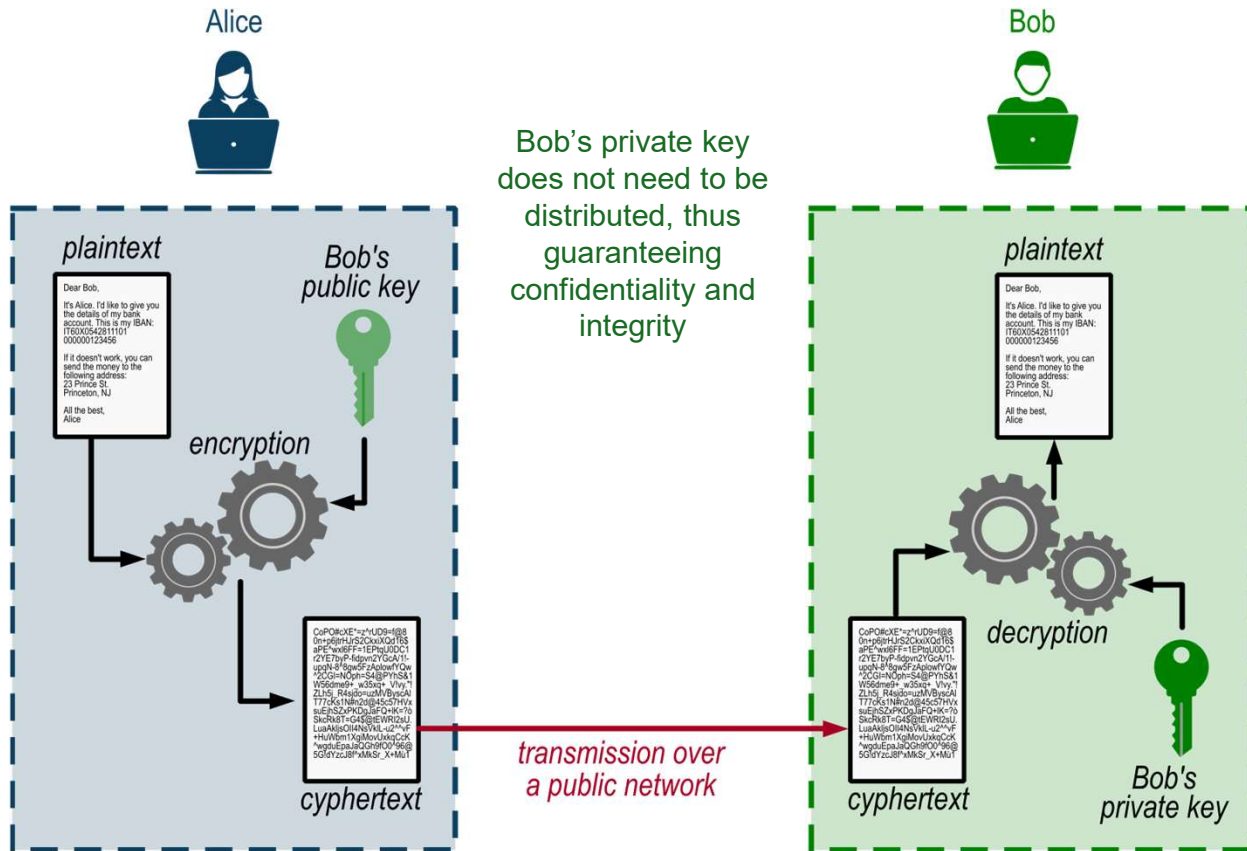
Players in a cybersecurity scenario



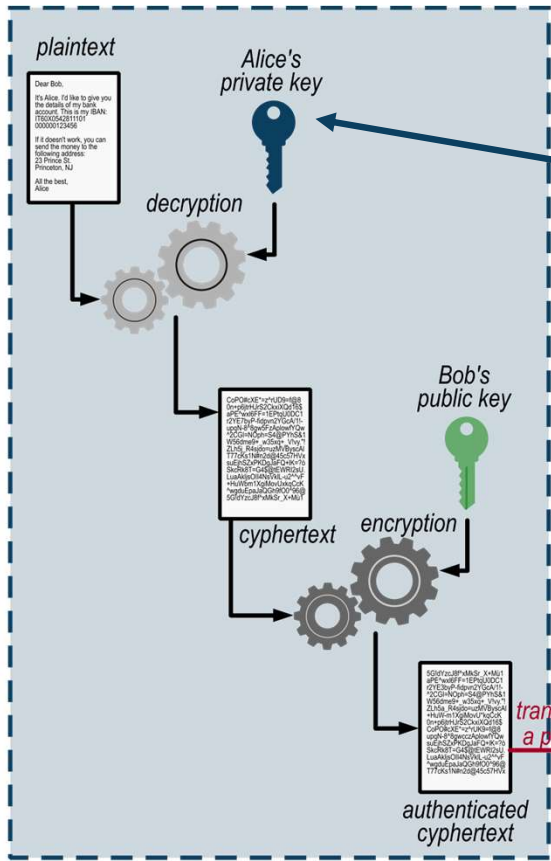
Encryption using a secret (symmetric) key



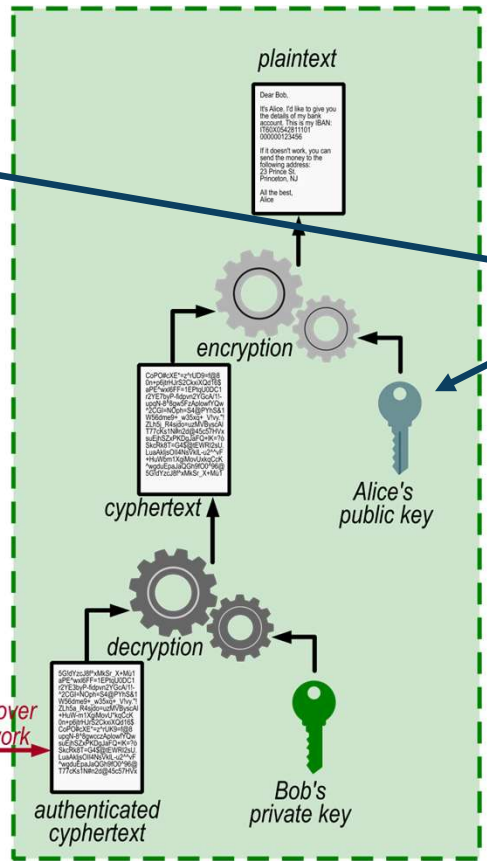
Encryption using a public (asymmetric) key



Adding authentication using a private key



transmission over a public network



encrypting the plaintext with Alice's private key guarantees authenticity to the message



Channel coding

General principles (1/5)

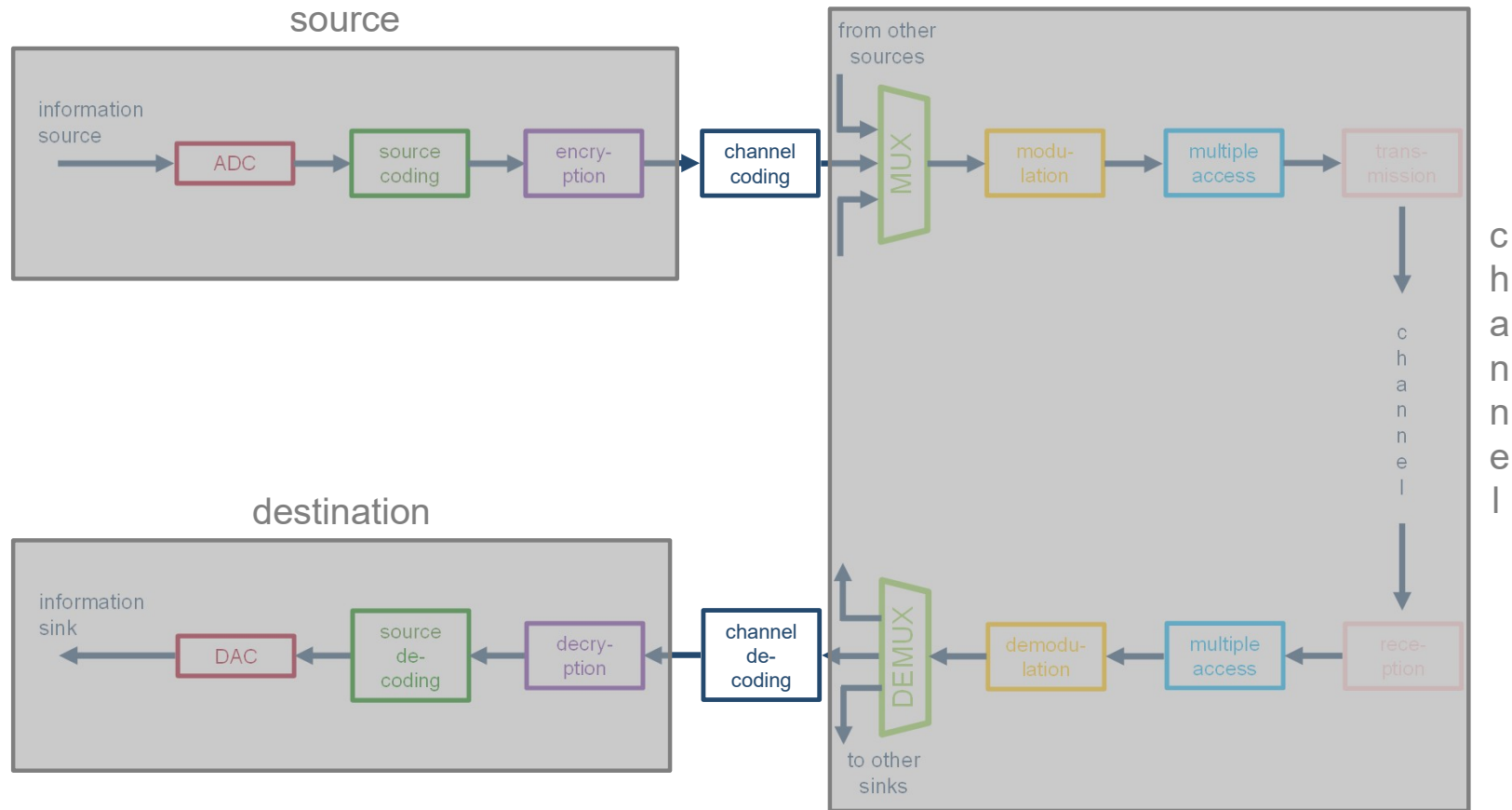
Channel coding attempts to do the same: it gives the **channel-encoded** message a particular structure, such that **bit errors** introduced by signal propagation through the error-prone channel can be **detected** (and potentially **corrected**) at the receive side

Two ways of recovering the packets:

- **forward error correction (FEC)**
- **automatic repeat request (ARQ)**

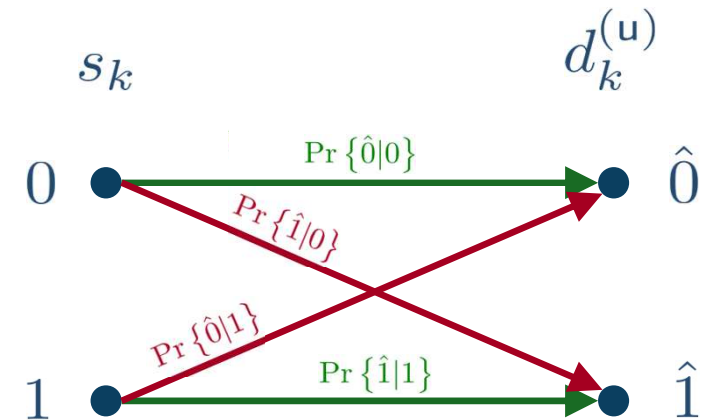


General principles (2/5)



General principles (3/5)

Let us suppose we do **not** use channel coding:

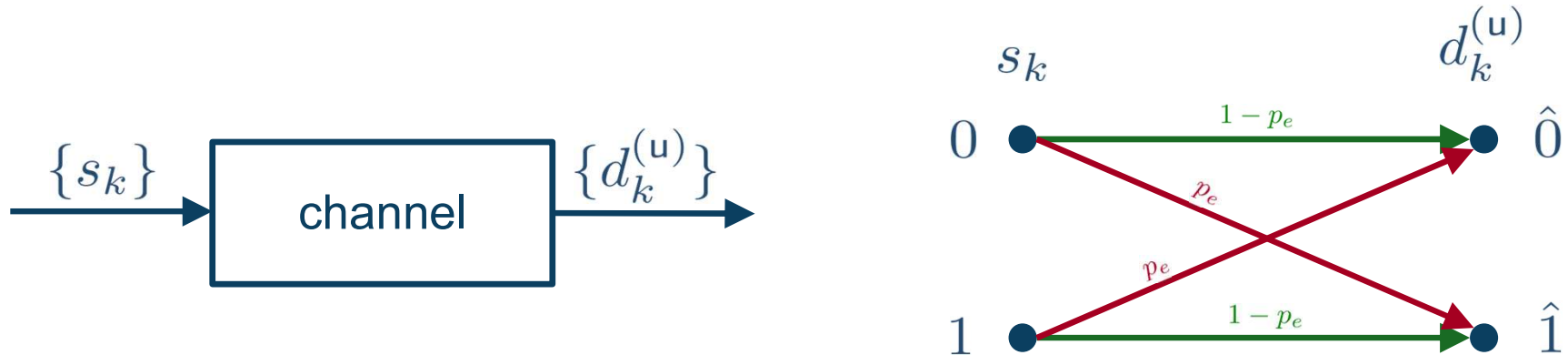


The quantities $\Pr\{\hat{1}|0\}$ and $\Pr\{\hat{0}|1\}$ are the probabilities that a source bit is flipped by the channel, i.e., the **probabilities of errors**

In practical systems, the probability of error can be measured in terms of **bit error rate (BER)**

General principles (4/5)

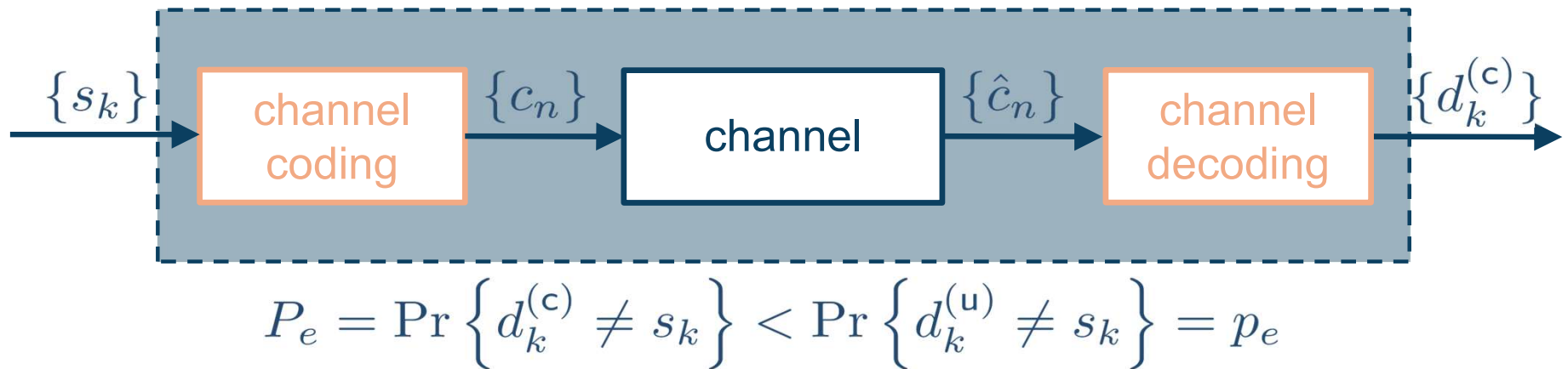
A customary assumption is to consider $\Pr \{\hat{1}|0\} = \Pr \{\hat{0}|1\} = p_e$, in the so-called **binary symmetric channel (BSC)**:



Other channel models exist (e.g., the **Z-channel** that mimics an optical-fiber connection)

General principles (5/5)

Our goal is to introduce a **channel coding** stage such that the **end-to-end error probability** P_e is (much) lower than the bit-error probability p_e introduced by the BSC:



Channel coding for dummies: Repetition coding (1/4)

The simplest way to make the communication more “robust”, against **bit flipping** introduced by the channel, is to use the **repetition code** scheme: for each source bit, we send N copies

Example: $N=5$

$$s_k = 0 \Rightarrow \mathbf{c} = [0, 0, 0, 0, 0]$$

$$s_k = 1 \Rightarrow \mathbf{c} = [1, 1, 1, 1, 1]$$

At the receiver, we can apply a decision strategy based on a **majority rule**:

- If at least $(N+1)/2$ received coded bits are 0, we set $d_k^{(c)} = \hat{0}$, and $d_k^{(c)} = \hat{1}$ otherwise

Channel coding for dummies: Repetition coding (2/4)

What is the detection and correction **performance** of such approach?

$$P_e = \Pr \left\{ \frac{N+1}{2} \text{ errors} \right\} + \Pr \left\{ \frac{N+3}{2} \text{ errors} \right\} + \dots + \Pr \{ N \text{ errors} \}$$

Assuming that bit-flipping errors introduced by the channel are **independent** events,

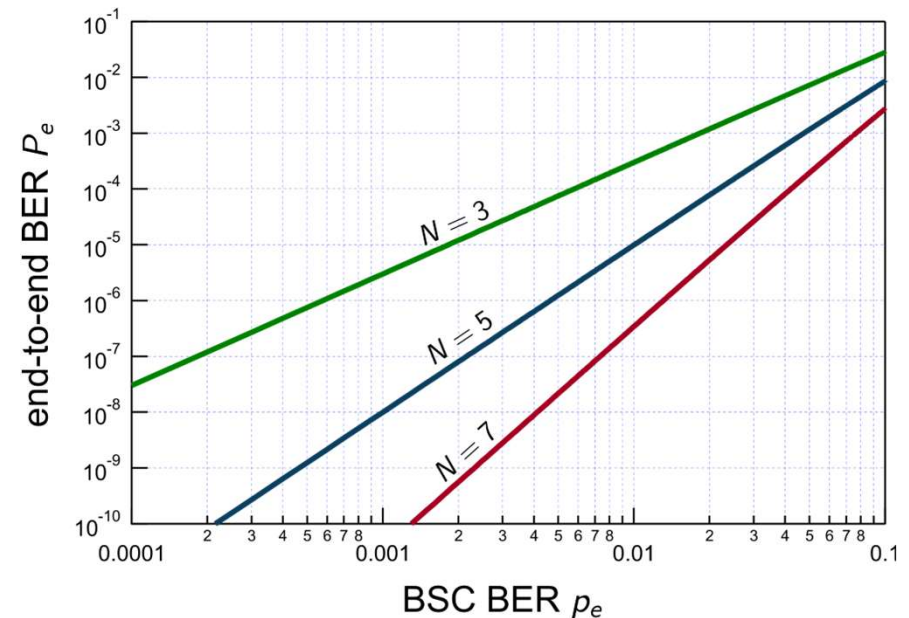
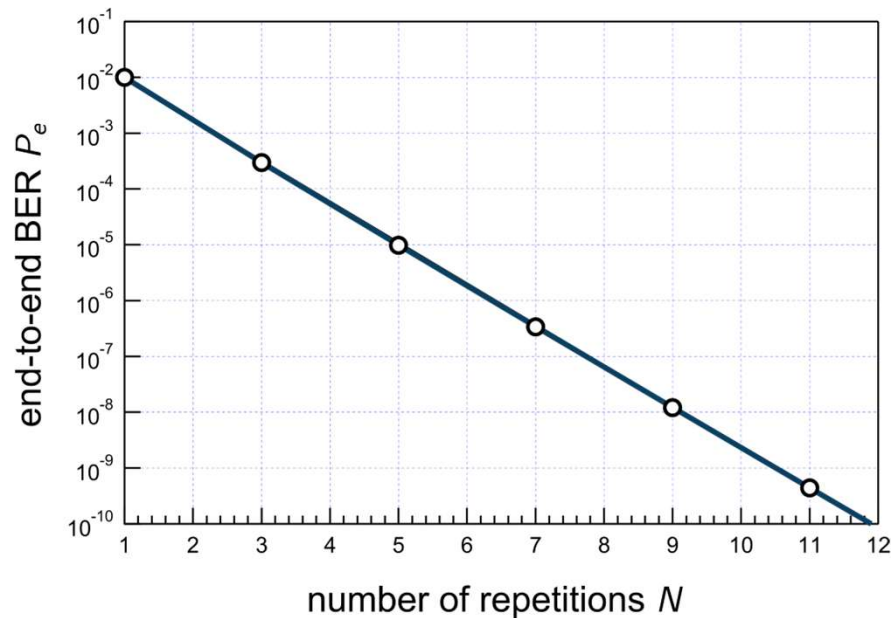
$$\Pr \{ n \text{ errors} \} = \binom{N}{n} p_e^n \cdot (1 - p_e)^{N-n} = \frac{N!}{n!(N-n)!} p_e^n \cdot (1 - p_e)^{N-n}$$

$$P_e = \sum_{n=\frac{N+1}{2}}^N \binom{N}{n} p_e^n \cdot (1 - p_e)^{N-n} \approx \binom{N}{(N+1)/2} p_e^{(N+1)/2} \cdot (1 - p_e)^{(N-1)/2}$$

Channel coding for dummies: Repetition coding (3/4)

What is the detection and correction **performance** of such approach?

$$P_e \approx \binom{N}{(N+1)/2} p_e^{(N+1)/2} \cdot (1 - p_e)^{(N-1)/2}$$



Channel coding for dummies: Repetition coding (4/4)

What is the **drawback**? For each source bit, we are sending N **coded bits**!

We are **increasing** the amount of resources required for the transmission by a **factor N**

In channel coding, an important figure of merit is the **coding rate r** :

$$r = \frac{K}{N} \leq 1$$

number of source bits at the input of the channel encoder

number of coded bits at the output of the channel encoder

- the higher r (the closer to 1), the lower the amount of resources requested (i.e., the redundancy introduced) ✓
- the higher r , the lower the protection and the error detection/correction capabilities of the encoder ✗

For the repetition code, $r = 1/N$ (that decreases as N increases)

Parity check codes (1/3)

A way to improve the **efficiency** of the channel encoder (i.e., increasing r for a given performance P_e , or, equivalently, decreasing P_e for a given r) is through the use of **2D parity check codes**, based on the XOR operation (row by row, and column by column):

A	B	$A \oplus B$
0	0	0
0	1	1
1	0	1
1	1	0

$$r = \frac{K}{N} = \frac{K}{(\sqrt{K}+1)^2} = \frac{16}{25}$$

coding rate

Example: $K=16$

$$s = [0111001011101001]$$

step 1: sort the bits into a $\sqrt{K} \times \sqrt{K}$ matrix

0	1	1	1	1
0	0	1	0	1
1	1	1	0	1
1	0	0	1	0
0	0	1	0	1

step 2: add parity bits

step 3: sort the matrix into a $(\sqrt{K}+1)^2$ -element vector

$$c = [0111001011101001001010111]$$

Parity check codes (2/3)

How does error detection and correction work?

0	1	1	1	1
0	0	1	0	1
1	1	1	0	1
1	0	0	0	0
0	0	1	0	1

case 1:

case 2:

case 3:

What is the detection and correction **performance** of the 2D parity check code?

$$P_e \approx \frac{K(\sqrt{K} - 1)^2}{4} p_e^4$$

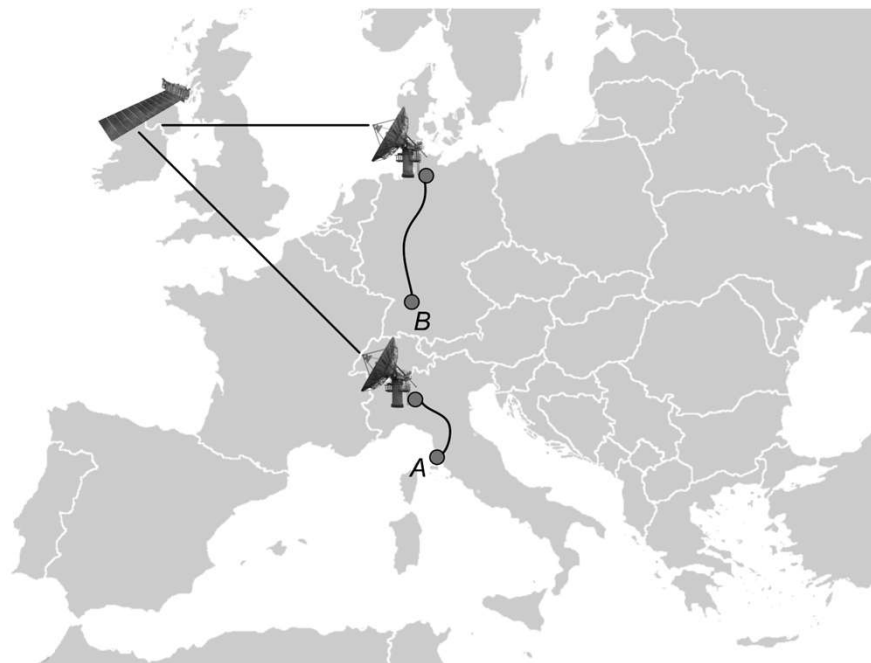
With $K=16$ and $p_e=10^{-2}$, P_e is **comparable** with a repetition code with $N=7$, but with a coding rate $r = 16/25 \approx 4.5 \cdot 1/7$

Parity check codes (3/3)

Parity check codes are used in both **broadcast** (e.g., satellite communications) and **unicast** (e.g., email) communications.

FEC is best suited for broadcast services, where a return channel is typically not available

ARQ mechanisms are better suited for unicast services



Linear block codes (1/2)

Linear block codes are a generalization of the parity check codes

Error detection and correction can be performed using a **syndrome** vector, which can be derived from the **generation** matrix, and requires linear operations

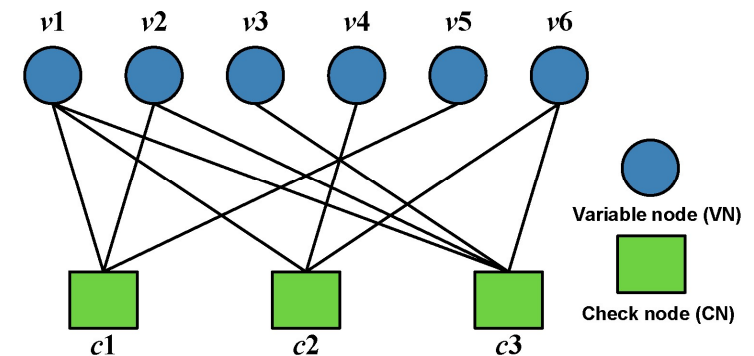
Notable examples are:

- **Reed-Solomon** (RS) codes, e.g. used in satellite digital video broadcasting (DVB-S) services
- **low-density parity check** (LDPC) codes



Linear block codes (2/2)

- LDPC codes are linear block codes characterized by **sparse parity check matrices**
- Invented by Gallager in 1960, but re-proposed by MacKay and Neal in 1995, when technology of **iterative decoding** was mature enough
- Particularly performing with **large block lengths** (e.g., 64,800 bits)
- LDPC codes yield **quasi-error-free (QEF) reception** even in poor link conditions

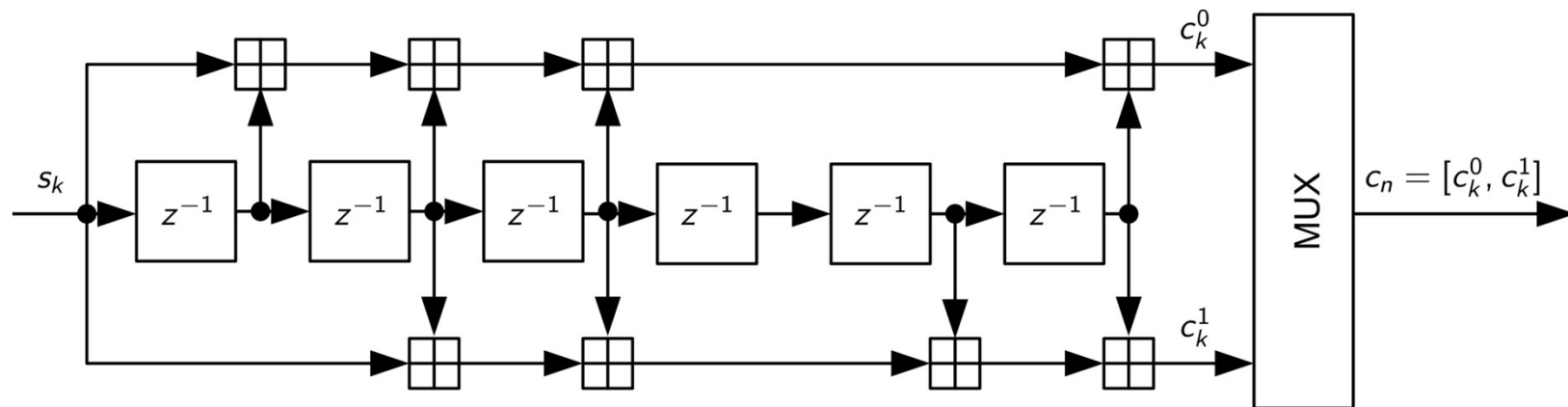


Convolutional codes (1/4)

Convolutional codes introduce correlation between source bits, by using a feedforward architecture

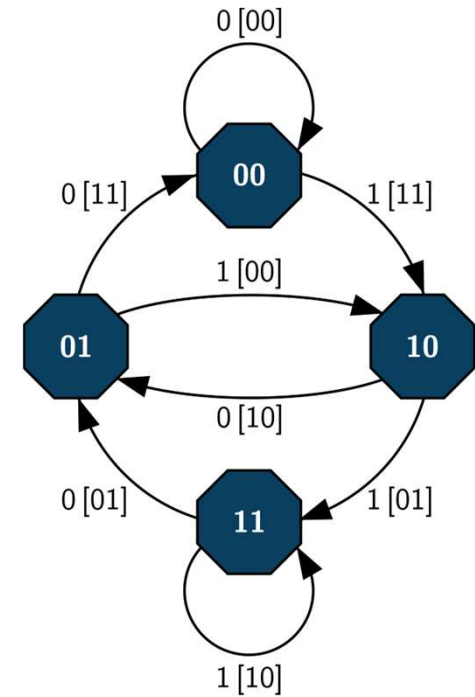
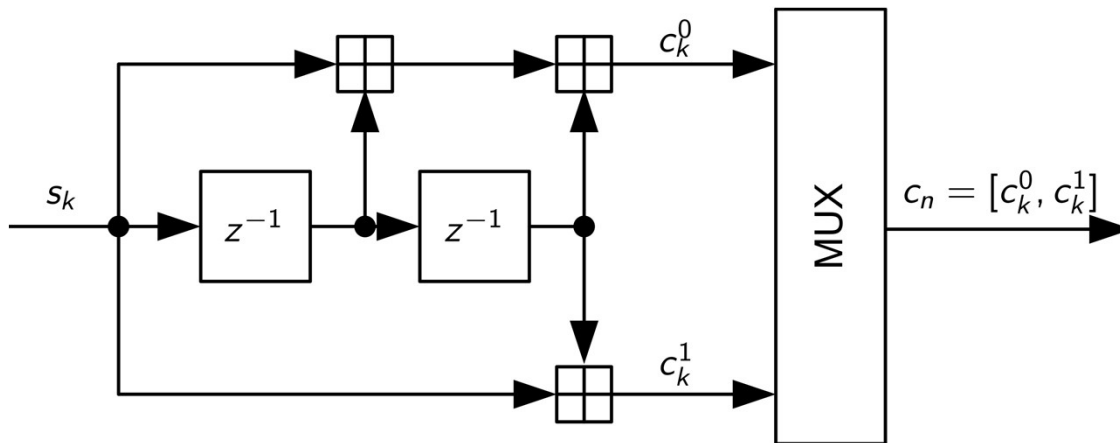
Notable examples:

- convolutional code with rate $r=1/2$, used in WiFi, GPS/Galileo, and DVB-T
- Turbo codes



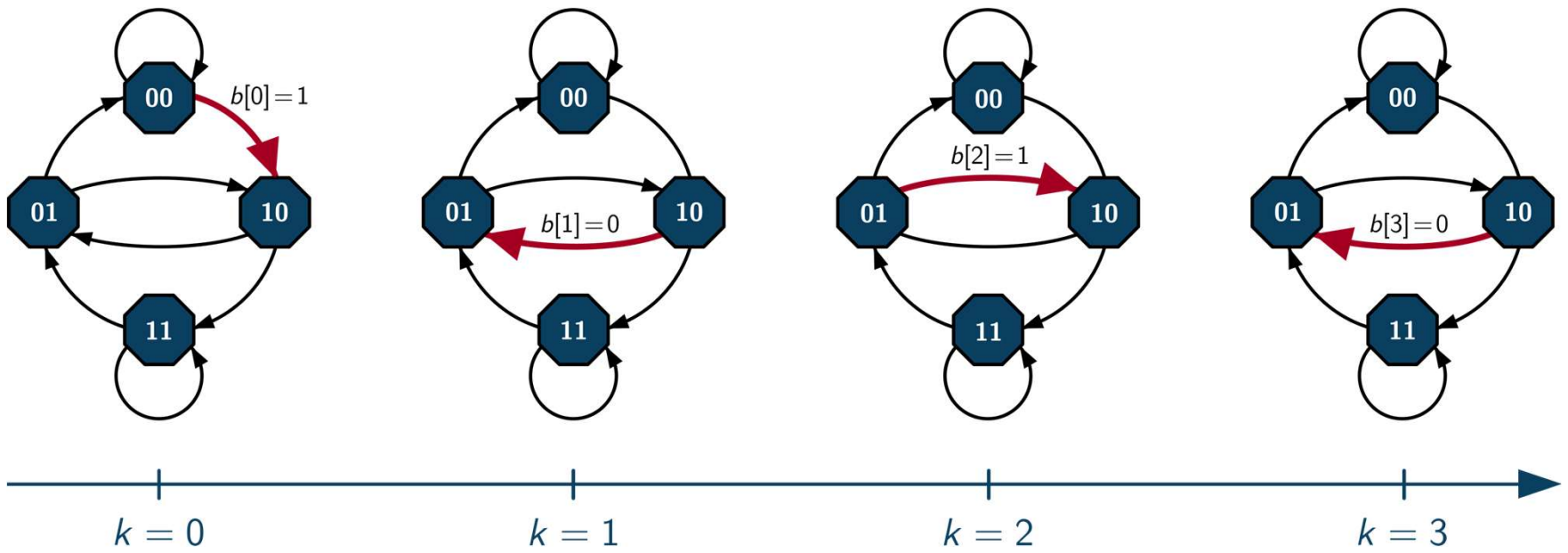
Convolutional codes (2/4)

From the **encoder structure**, we can derive the corresponding **finite-state machine**:



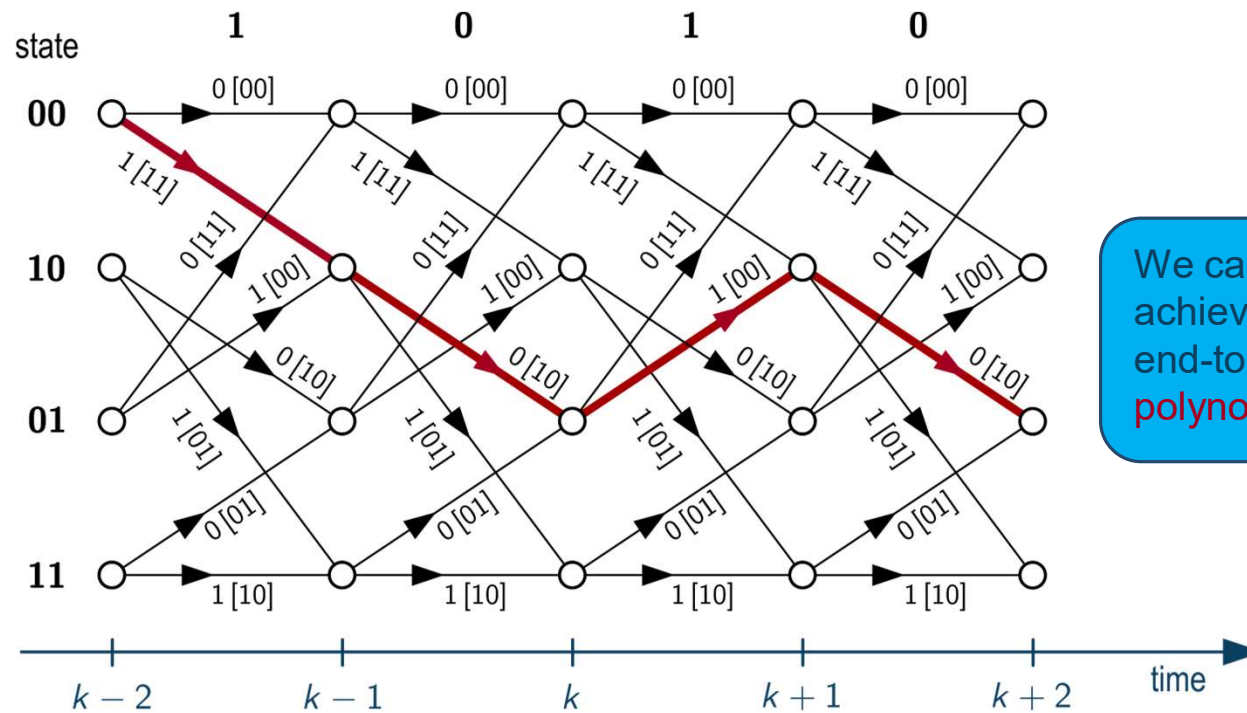
Convolutional codes (3/4)

Suppose the input bit sequence is $\mathbf{s} = [1\ 0\ 1\ 0]$:



Convolutional codes (4/4)

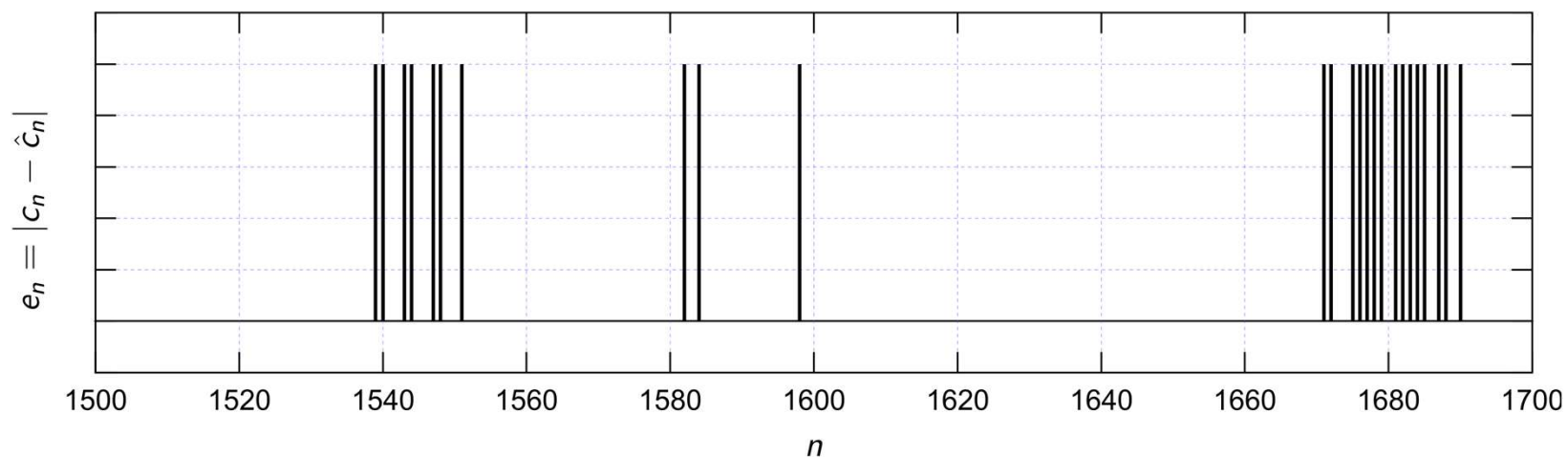
A more convenient representation is the **trellis diagram**, which unfolds the state transitions through time:



We can use the **Viterbi algorithm** to achieve **exponentially decreasing** end-to-end error probability P_e with **polynomial-time** decoding complexity

Interleaving (1/3)

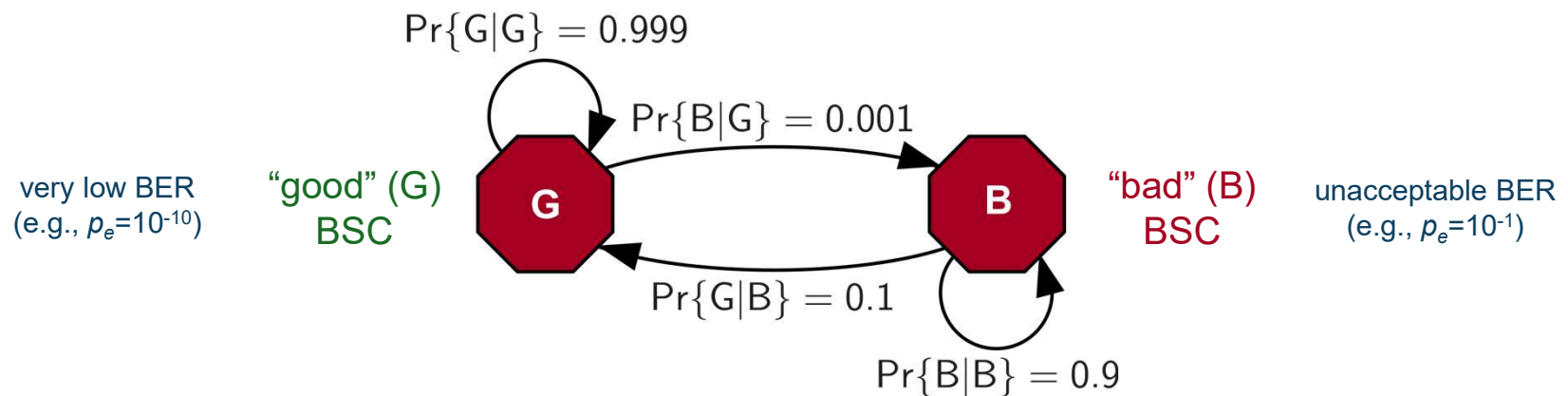
In many scenarios, the channel **cannot** be modeled as a BSC, due to the presence of **error bursts** (e.g., due to the sudden changes in the propagation environment)



Interleaving (2/3)

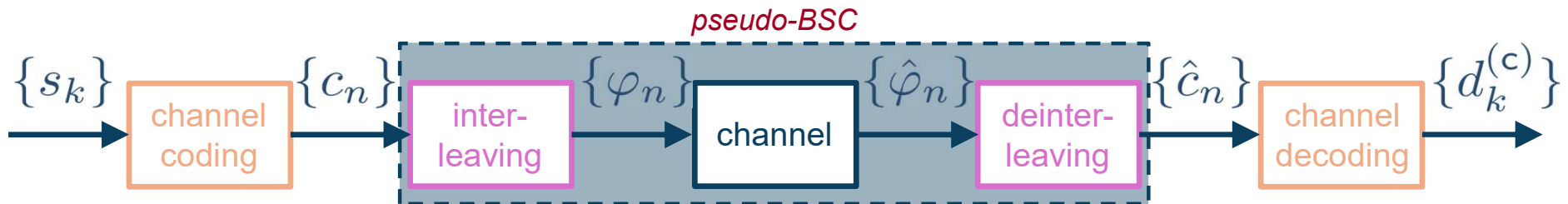
In many scenarios, the channel **cannot** be modeled as a BSC, due to the presence of **error bursts** (e.g., due to the sudden changes in the propagation environment)

This situation can be modeled as a **two-state** finite machine:



Interleaving (3/3)

To cope with error bursts, we can equip the channel encoder with an **interleaver**, which **scrambles** the outputs of the encoder so as to **decorrelate** the impact of the “bad” BSC:



Example: interleaving a block with length $N=16$

$$\mathbf{c} = [1011011100100110]$$

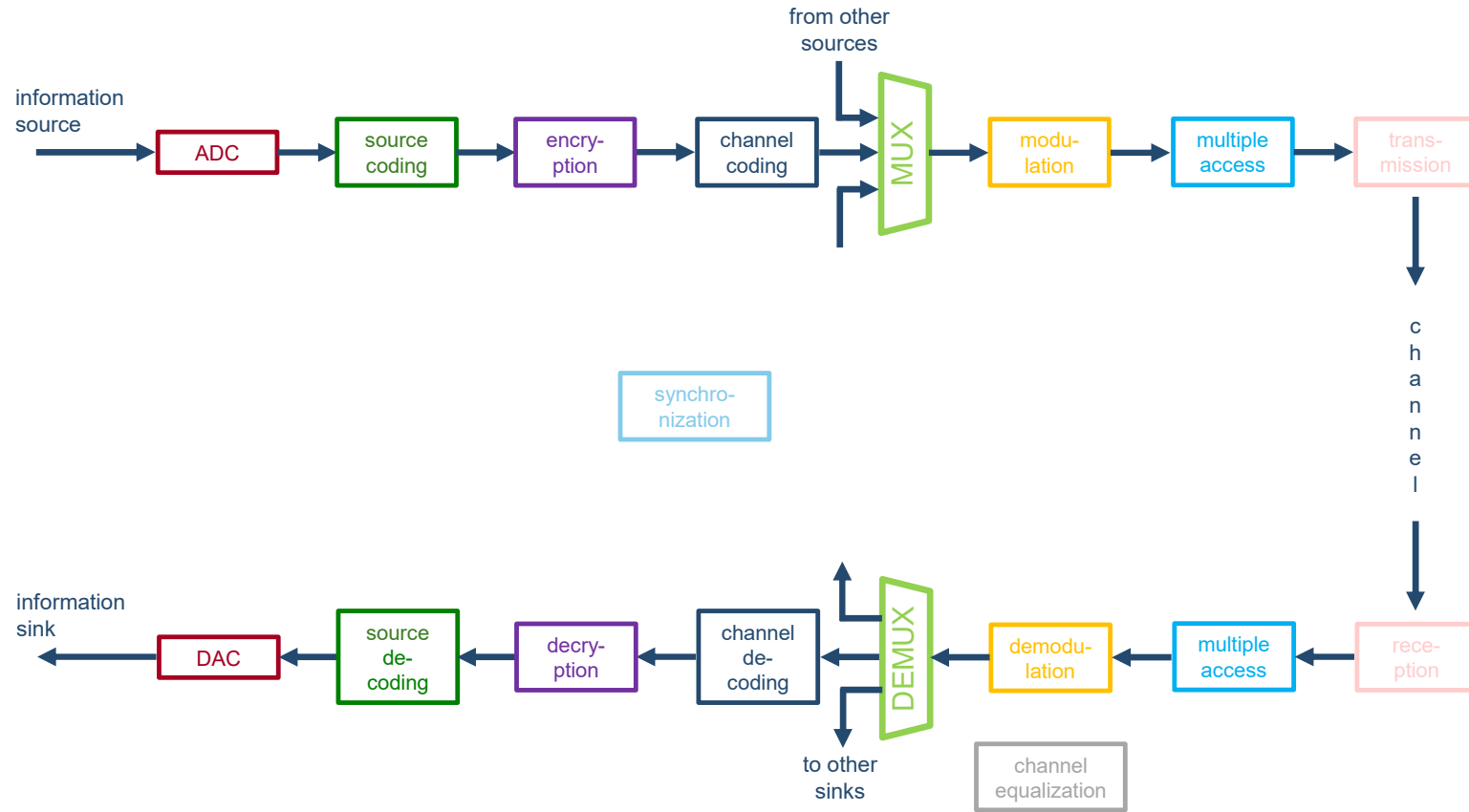
$$\varphi = [1000010111111100]$$

step 1: sort \mathbf{c} in a 4×4 matrix by rows

step 2: populate φ by reading the 4×4 matrix by columns

$c_0=1$	$c_1=0$	$c_2=1$	$c_3=1$
$c_4=0$	$c_5=1$	$c_6=1$	$c_7=1$
$c_8=0$	$c_9=0$	$c_{10}=1$	$c_{11}=0$
$c_{12}=0$	$c_{13}=1$	$c_{14}=1$	$c_{15}=0$

Elements of a digital communication system

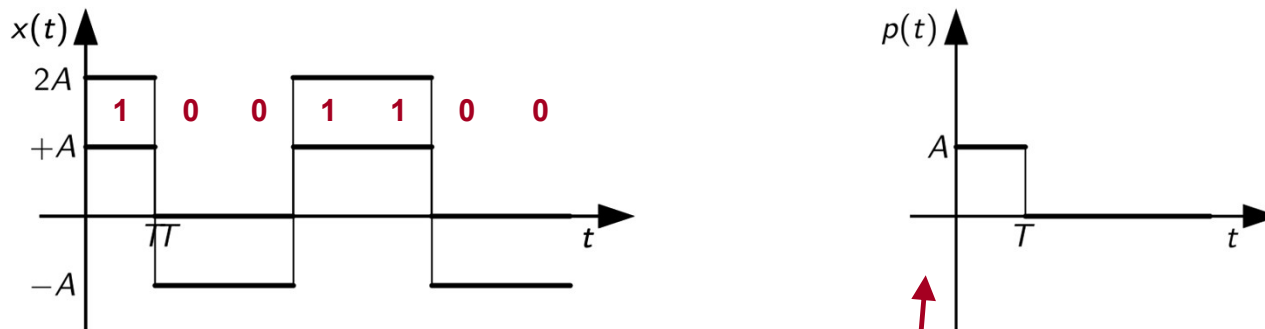




Modulation

Pulse shaping (1/3)

We need to **adapt** our sequence of bits into a signal which is suitable to be transmitted over a **physical medium** (air in wireless systems, a cable in wired systems)



symmetric NRZ
signal:

$$x(t) = \sum_{k=-\infty}^{+\infty} (2b_k - 1) p(t - kT)$$

shaping pulse

For convenience, let us use a **symmetric** NRZ modulation

Pulse shaping (2/3)

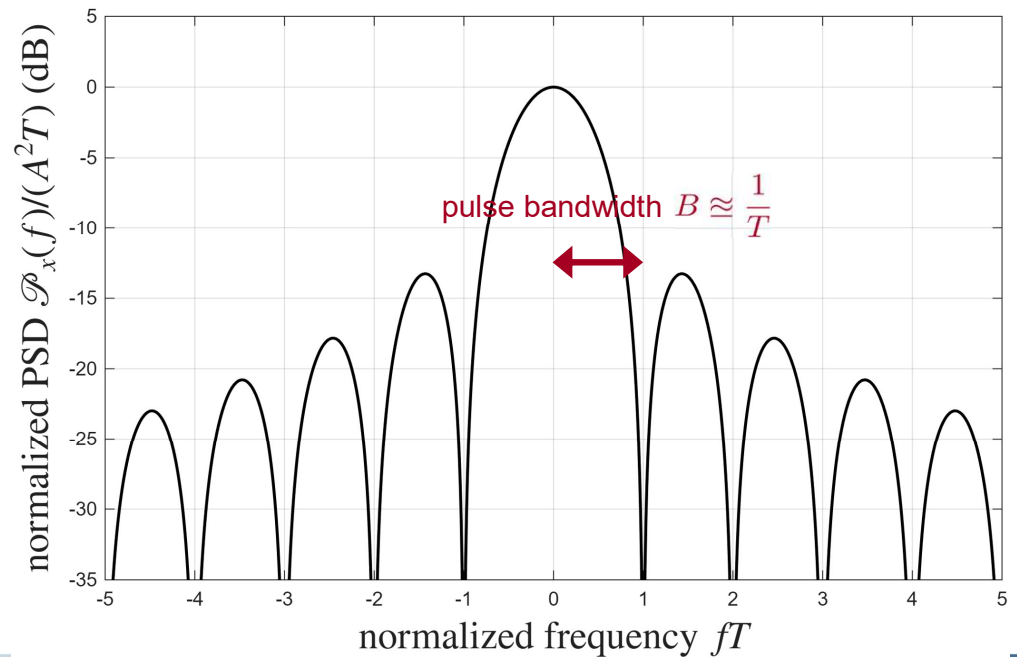
What is the (physical) bandwidth of a symmetric NRZ signal?

Let us consider the power spectral density (PSD) of $x(t)$:

$$\begin{aligned} \mathcal{P}_x(f) &= \frac{A^2}{T} |P(f)|^2 \\ &= A^2 T \operatorname{sinc}^2(fT) \end{aligned}$$

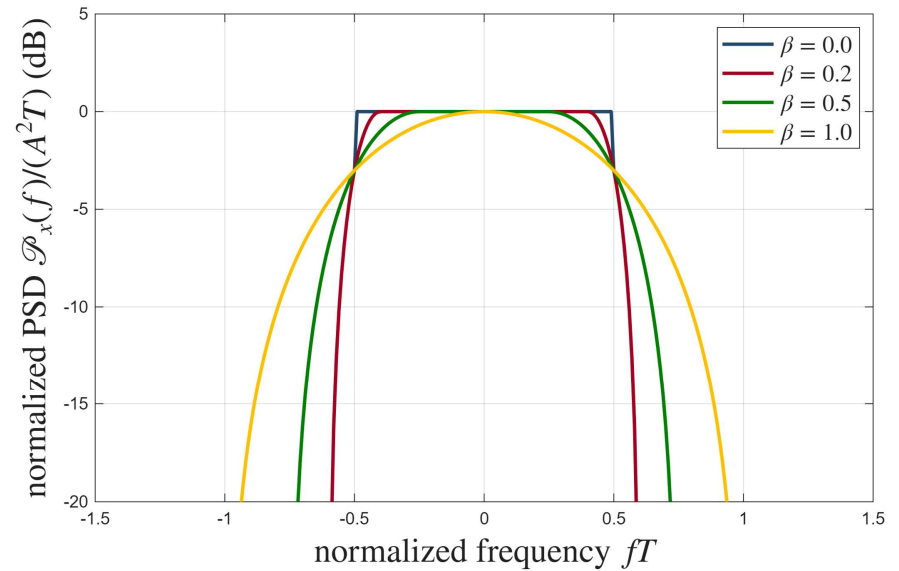
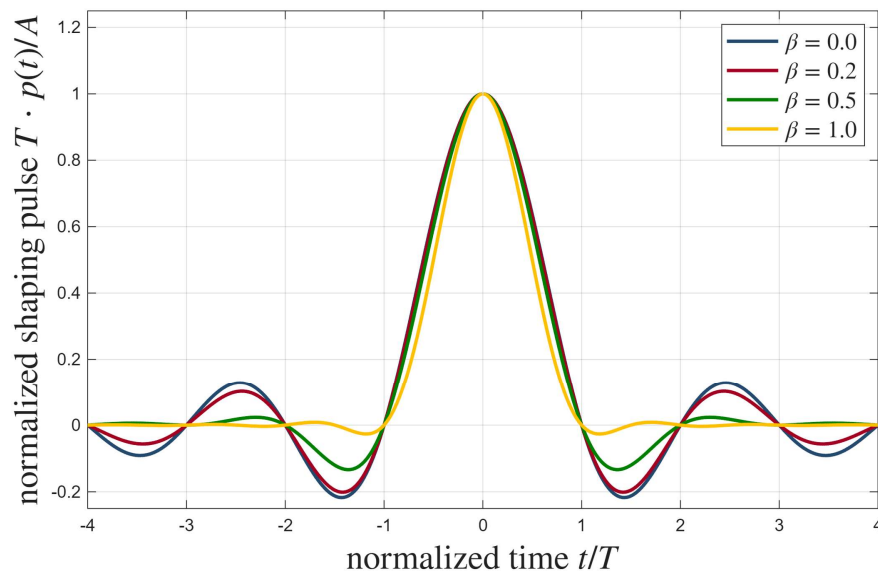
$$\text{pulse bandwidth } B \approx \frac{1}{T} = R = R_b$$

symbol rate bitrate



Pulse shaping (3/3)

Similar considerations can be drawn using other pulse formats, e.g, the **square-root raised cosine (SRRC)** with rolloff factor β :



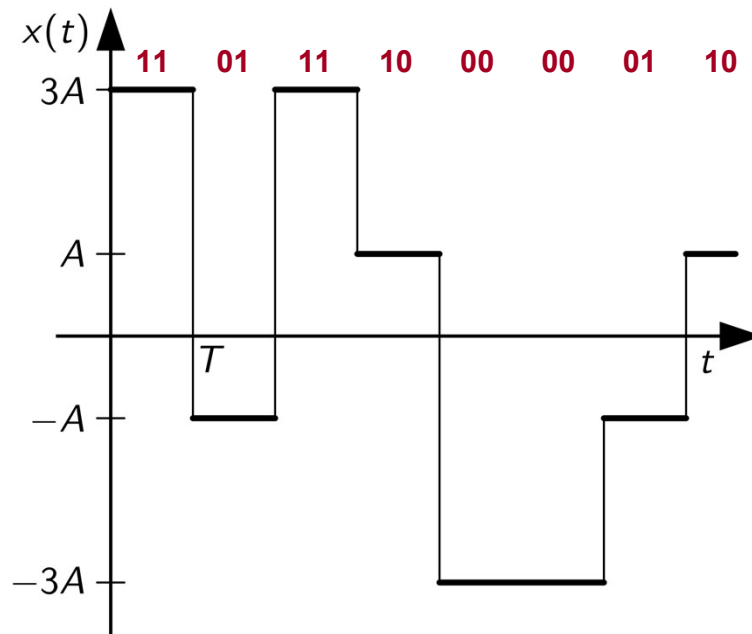
$$B \propto \frac{1}{T} = R \neq R_b$$

this is **NOT** true in generale!



Multilevel (baseband) modulations (1/2)

To improve the spectral efficiency R_b/B , we can map **more** bits into a single symbol:



the bitrate is now **twice** the symbol rate:

$$R_b = 2R = 2 \cdot \frac{1}{T} \approx 2B$$

$$T_b = \frac{1}{R_b} = \frac{T}{2}$$

Multilevel (baseband) modulations (2/2)

In general, when using an **M -level mapping** (i.e., when using $N_b = \log_2 M$ bits per symbol), we have

$$R_b = \log_2 M \cdot R = N_b \cdot R \approx N_b \cdot B$$

The spectral efficiency becomes

$$\eta_s \triangleq \frac{R_b}{B} \approx N_b \quad [\text{b/s/Hz}]$$

This is particularly relevant in **wireless communications**, where the frequency spectrum is **scarce**!



Carrier modulation (1/4)

Why do we need to modulate?

- baseband is **not sustainable**, in terms of physical feasibility of the components: e.g., the antenna size needs to have the **same order of magnitude** of the signal wavelength λ (typical size: $\lambda/2$)
- bandpass yields additional benefits, e.g., in terms of **multiple access**

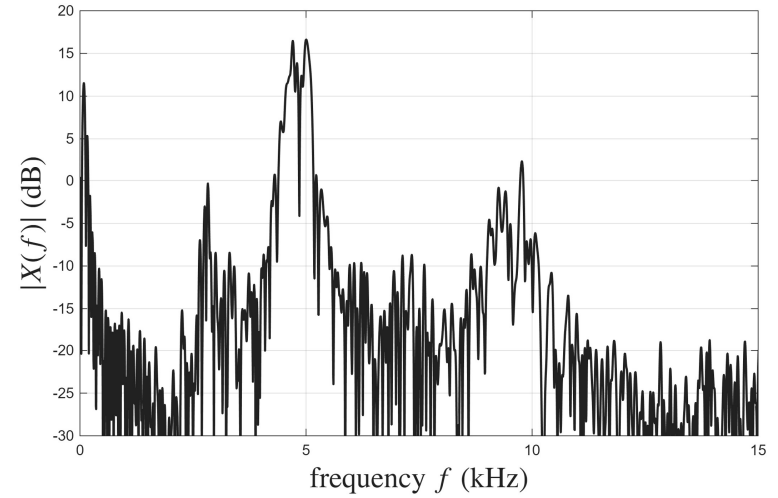


Carrier modulation (2/4)

Signal wavelength:

$$\lambda = \frac{c}{f}$$

speed of light, $3 \cdot 10^8$ m/s
frequency



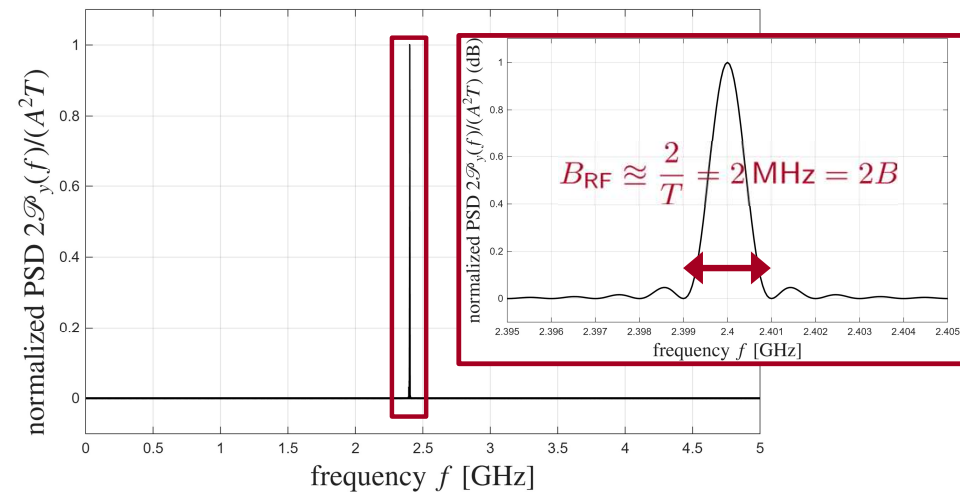
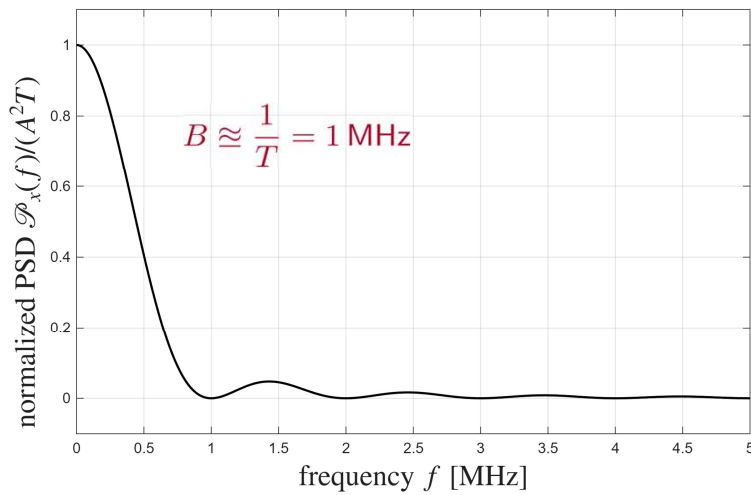
Wireless radio spectrum:



Carrier modulation (3/4)

$$x(t) = \sum_{k=-\infty}^{+\infty} (2b_k - 1) p(t - kT), \quad T = 1 \mu s$$

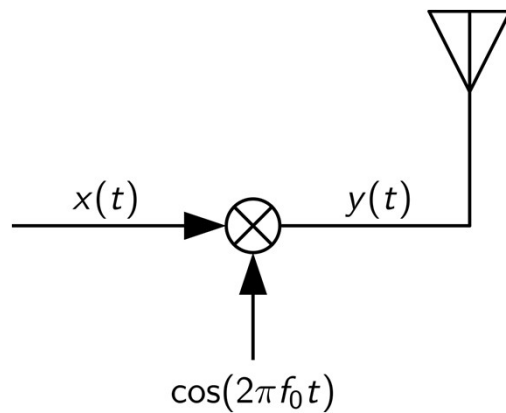
$$y(t) = x(t) \cos(2\pi f_0 t), \quad f_0 = 2.4 \text{ GHz}$$



Modulation theorem: $x(t) \cos(2\pi f_0 t) \Leftrightarrow \frac{X(f - f_0) + X(f + f_0)}{2}$

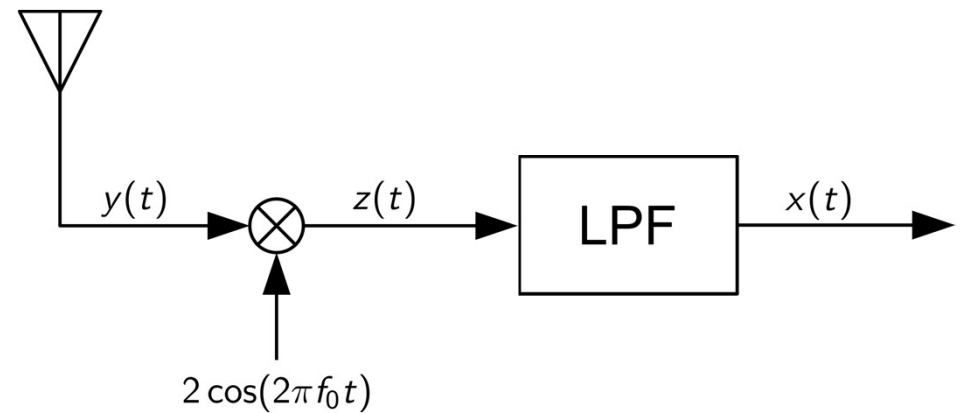
Carrier modulation (4/4)

How can we demodulate the signal $x(t)$?



$$y(t) = x(t) \cos(2\pi f_0 t)$$

$$2 \cos^2(\alpha) = 1 + \cos(2\alpha)$$



$$z(t) = y(t) 2 \cos(2\pi f_0 t) = 2x(t) \cos^2(2\pi f_0 t)$$

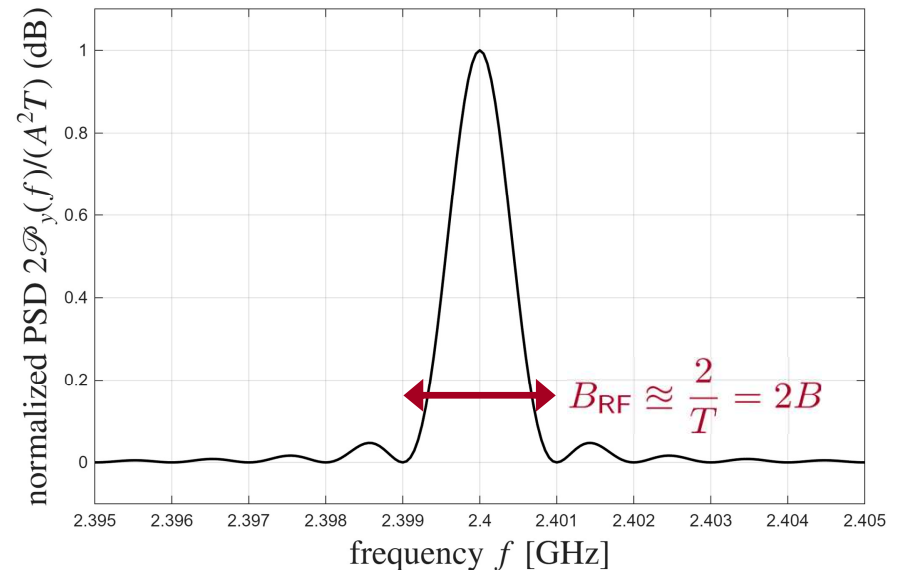
$$= x(t) + x(t) \cos [2\pi(2f_0)t]$$

I/Q modulation (1/4)

Modulation is the **key** to transmit a signal via radio frequency (RF) but... when moving to the RF, we **decrease** our spectral efficiency by a **factor 2**:

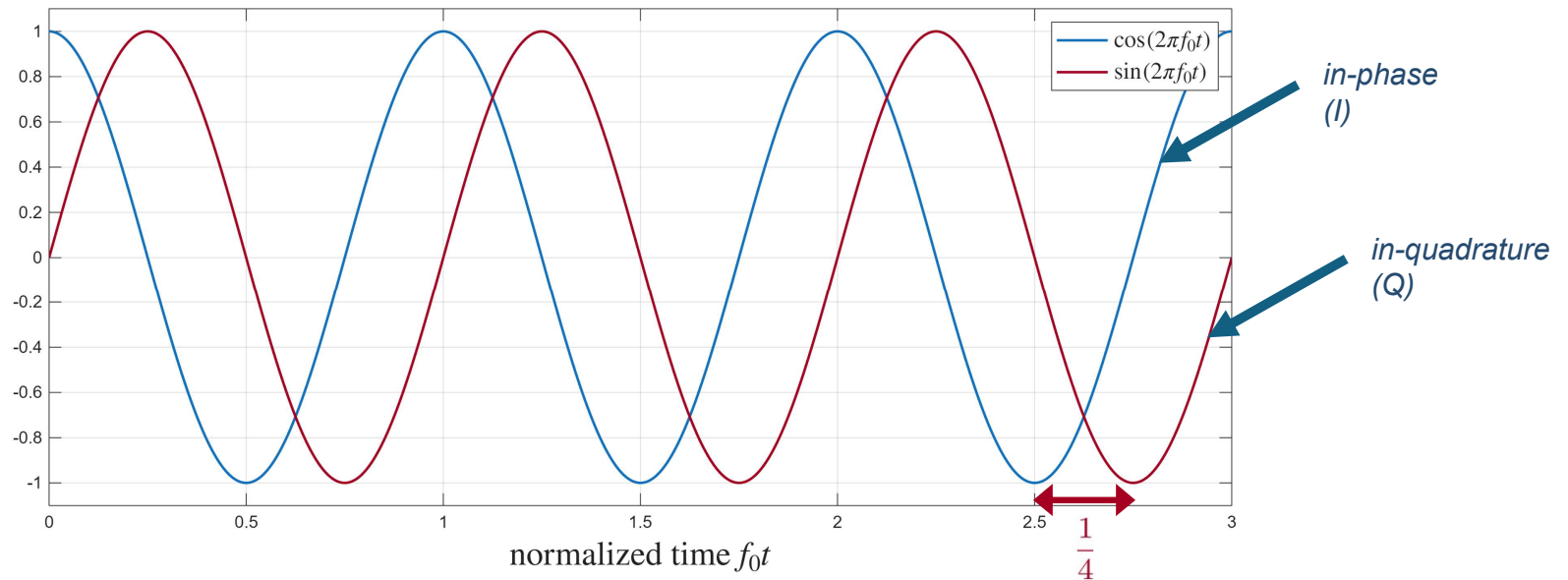
$$\eta_s \triangleq \frac{R_b}{B_{RF}} \approx \frac{N_b}{2} \quad [\text{b/s/Hz}]$$

How can we **improve** η_s , while exploiting the intuition of **multiple** bits per symbol?



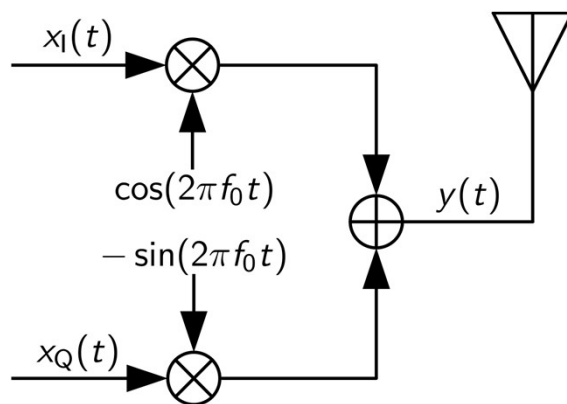
I/Q modulation (2/4)

Let us multiplex two streams on the same carrier, by leveraging two **orthogonal** waveforms:



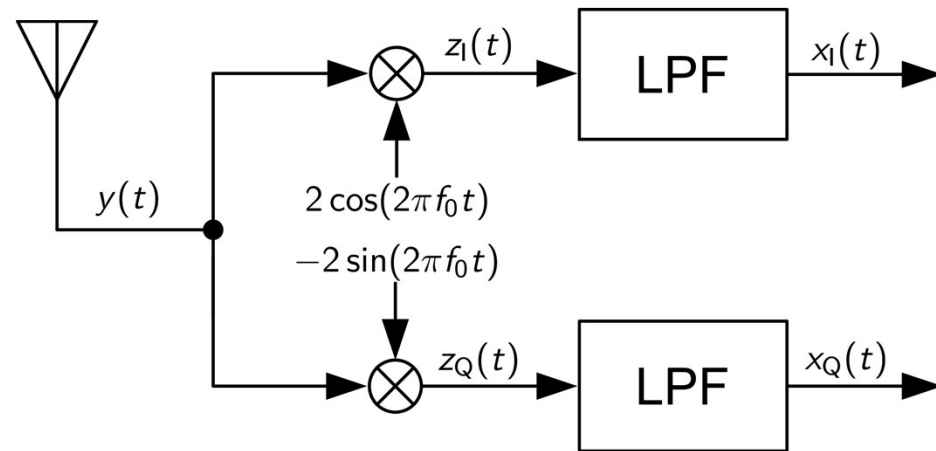
I/Q modulation (3/4)

Let us feed the modulator with two **independent** streams, each with bitrate R_b :



$$y(t) = x_I(t) \cos(2\pi f_0 t) - x_Q(t) \sin(2\pi f_0 t)$$

$$\begin{aligned} 2 \cos^2(\alpha) &= 1 + \cos(2\alpha) \\ 2 \sin^2(\alpha) &= 1 - \cos(2\alpha) \\ 2 \sin(\alpha) \cos(\alpha) &= \sin(2\alpha) \end{aligned}$$

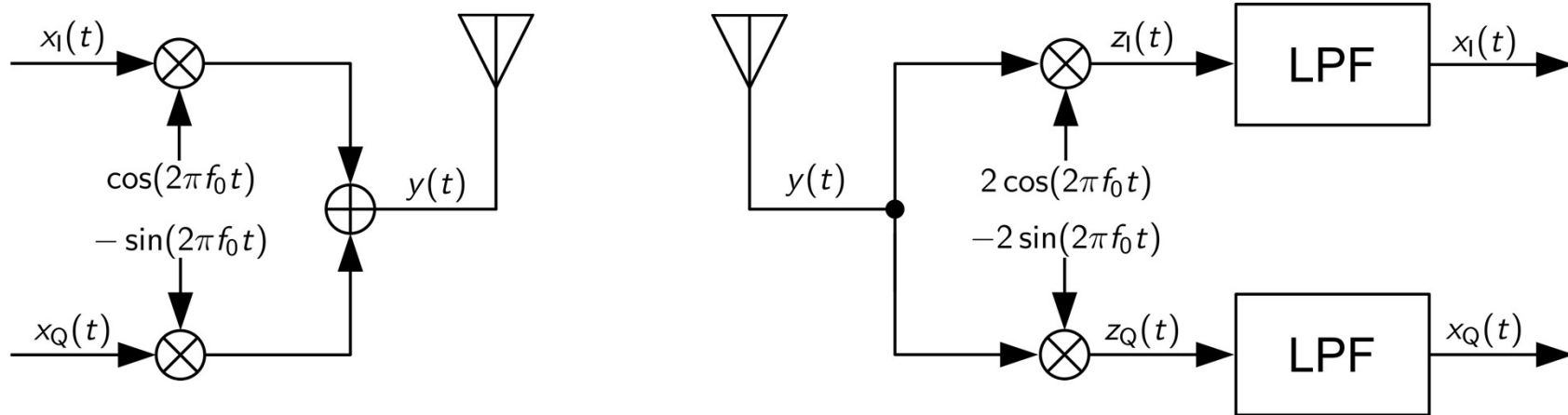


$$\begin{aligned} z_I(t) &= y(t) 2 \cos(2\pi f_0 t) = 2x_I(t) \cos^2(2\pi f_0 t) - 2x_Q(t) \sin(2\pi f_0 t) \cos(2\pi f_0 t) \\ &= x_I(t) + x_I(t) \cos [2\pi(2f_0)t] - x_Q(t) \sin [2\pi(2f_0)t] \end{aligned}$$

$$\begin{aligned} z_Q(t) &= -y(t) 2 \sin(2\pi f_0 t) = 2x_Q(t) \sin^2(2\pi f_0 t) - 2x_I(t) \sin(2\pi f_0 t) \cos(2\pi f_0 t) \\ &= x_Q(t) - x_Q(t) \cos [2\pi(2f_0)t] - x_I(t) \sin [2\pi(2f_0)t] \end{aligned}$$

I/Q modulation (4/4)

Let us feed the modulator with two **independent** streams, each with bitrate R_b :



$$\eta_s \triangleq \frac{R_{b,I} + R_{b,Q}}{B_{RF}} = \frac{2R_b}{2B} \approx N_b \quad [\text{b/s/Hz}]$$

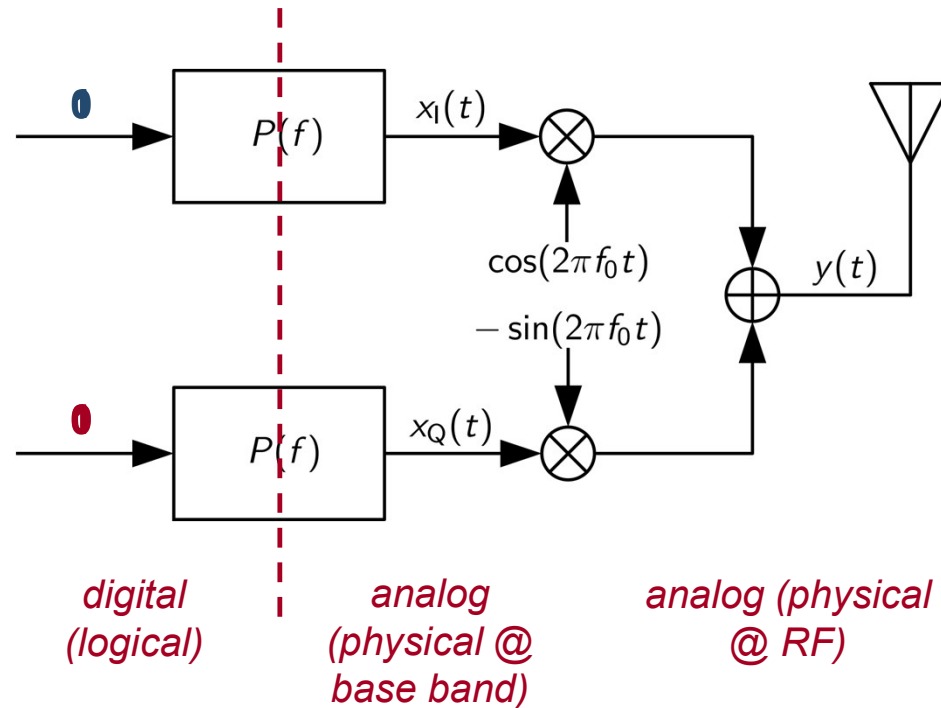
PSK and QAM constellations (1/5)

To cast one **single binary stream** into the I/Q scheme, for instance we can assign **odd bits** to the I branch and **even bits** to the Q branch:

01101110101100...

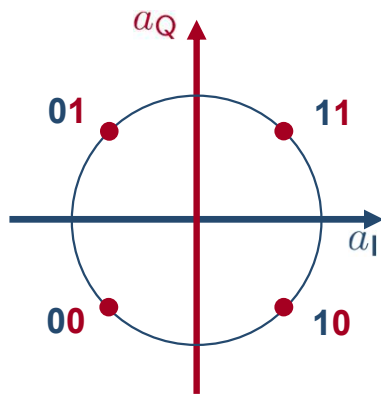
$$x_I(t) = \sum_{\ell=-\infty}^{+\infty} (2b_{2\ell} - 1) p(t - \ell T)$$

$$x_Q(t) = \sum_{\ell=-\infty}^{+\infty} (2b_{2\ell+1} - 1) p(t - \ell T)$$

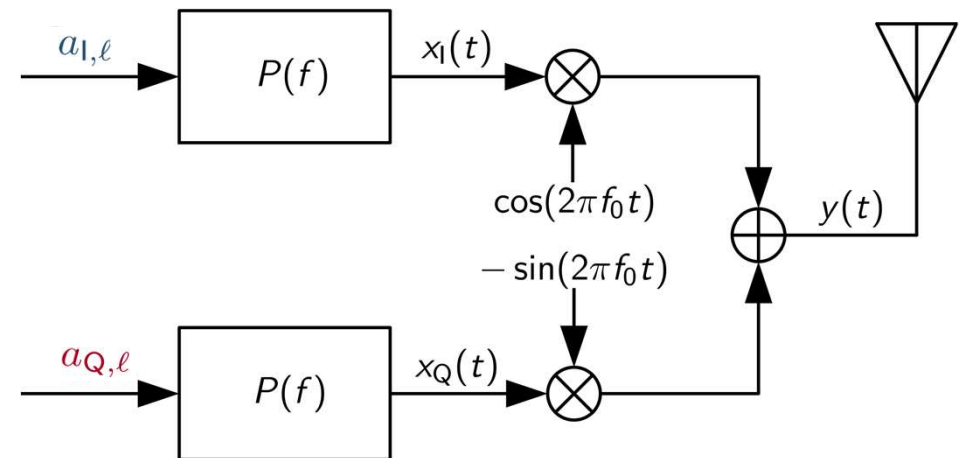


PSK and QAM constellations (2/5)

This is equivalent to **map** the input bits in complex symbols over the I/Q plane:



$b_{2\ell}$	$b_{2\ell+1}$	$a_{1,\ell}$	$a_{Q,\ell}$
00		-1	-1
01		-1	+1
10		+1	-1
11		+1	+1



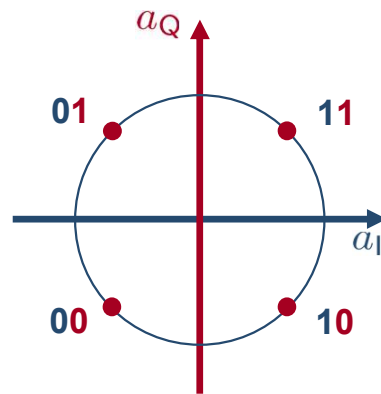
$$x_1(t) = \sum_{\ell=-\infty}^{+\infty} (2b_{2\ell} - 1) p(t - \ell T) = \sum_{\ell=-\infty}^{+\infty} a_{1,\ell} p(t - \ell T)$$

$$x_Q(t) = \sum_{\ell=-\infty}^{+\infty} (2b_{2\ell+1} - 1) p(t - \ell T) = \sum_{\ell=-\infty}^{+\infty} a_{Q,\ell} p(t - \ell T)$$

With this scheme, we can send $N_b = \log_2 4 = 2$ bits per symbol, thus achieving $\eta_s = 2$ b/s/Hz

PSK and QAM constellations (3/5)

This scheme goes under the name of **quaternary phase shift keying (QPSK)**:



$b_{2e} b_{2e+1}$	$a_{I,e}$	$a_{Q,e}$
00	-1	-1
01	-1	+1
10	+1	-1
11	+1	+1

Question: Can we generalize to an arbitrary number of bits (including odd N_b 's)?

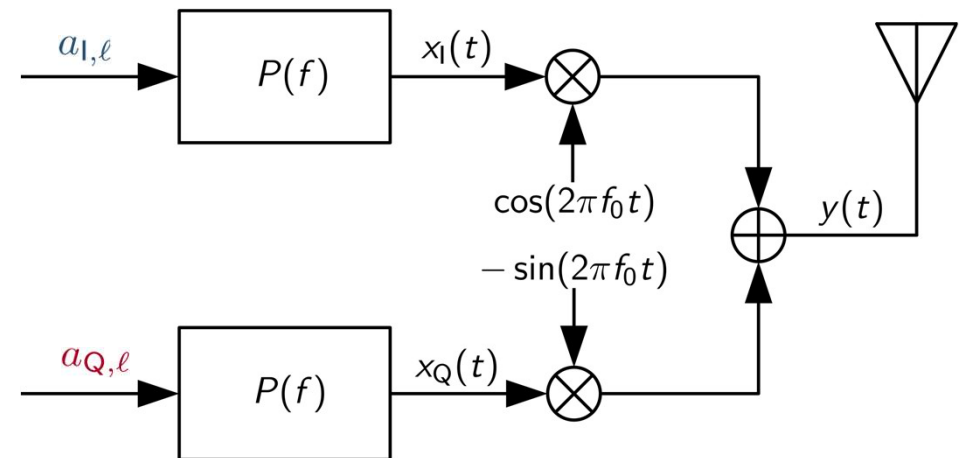
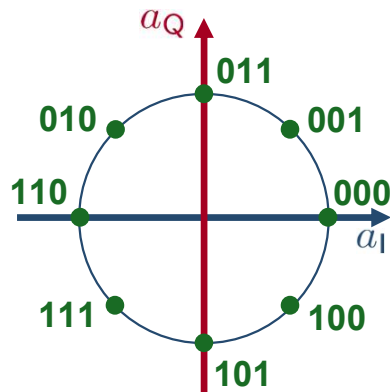
Answer: Yes, using phase shift keying (PSK) and quadrature amplitude modulation (QAM) constellations!

PSK and QAM constellations (4/5)

Important: The I/Q modulator block diagram remains the same!

$M=8$ ($N_b=3$)

→ 8-PSK:



b_{2e}	b_{2e+1}	$a_{1,e}$	$a_{Q,e}$	b_{2e}	b_{2e+1}	$a_{1,e}$	$a_{Q,e}$
0	0	+1	0	1	0	$+1/\sqrt{2}$	$-1/\sqrt{2}$
0	0	$+1/\sqrt{2}$	$+1/\sqrt{2}$	1	0	0	-1
0	1	$-1/\sqrt{2}$	$+1/\sqrt{2}$	1	1	-1	0
0	1	0	+1	1	1	$-1/\sqrt{2}$	$-1/\sqrt{2}$

$$x_1(t) = \sum_{l=-\infty}^{+\infty} a_{1,l} p(t - lT)$$

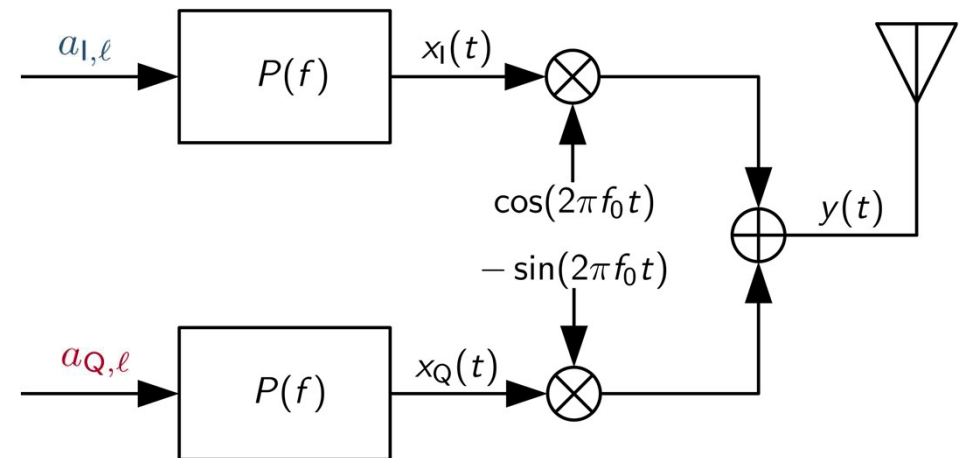
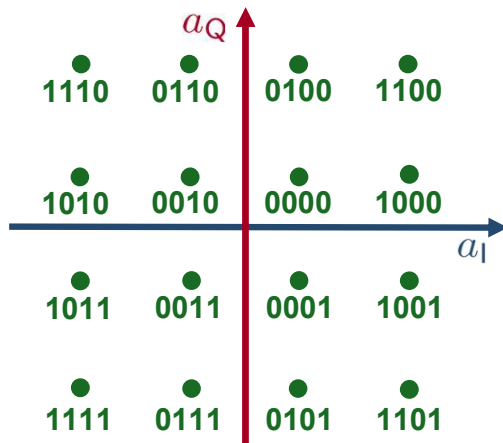
$$x_Q(t) = \sum_{l=-\infty}^{+\infty} a_{Q,l} p(t - lT)$$

PSK and QAM constellations (5/5)

Important: The I/Q modulator block diagram remains the same!

$M=16$ ($N_b=4$)

→ 16-QAM:

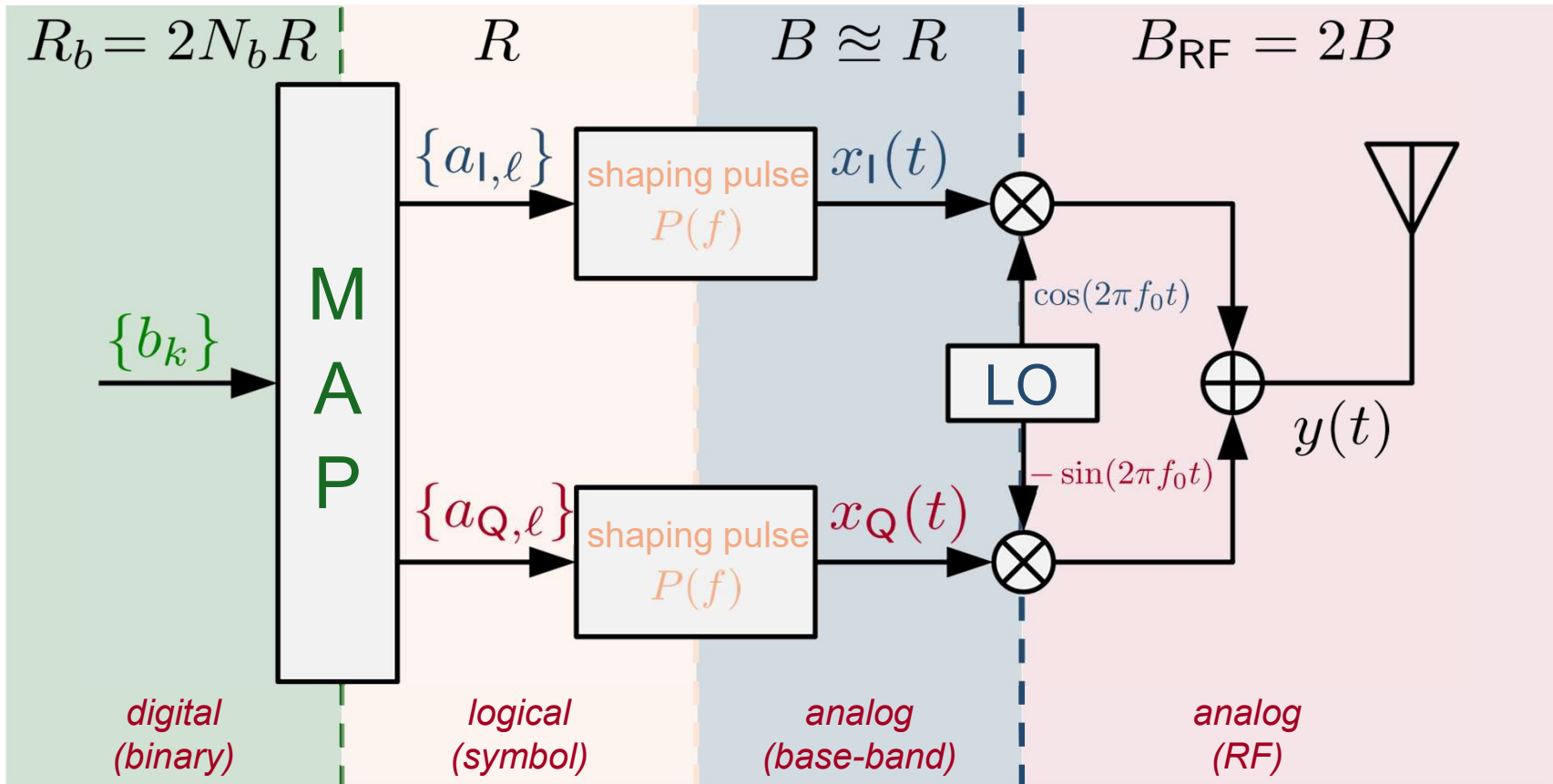


$$x_I(t) = \sum_{l=-\infty}^{+\infty} a_{I,l} p(t - lT)$$

$$x_Q(t) = \sum_{l=-\infty}^{+\infty} a_{Q,l} p(t - lT)$$

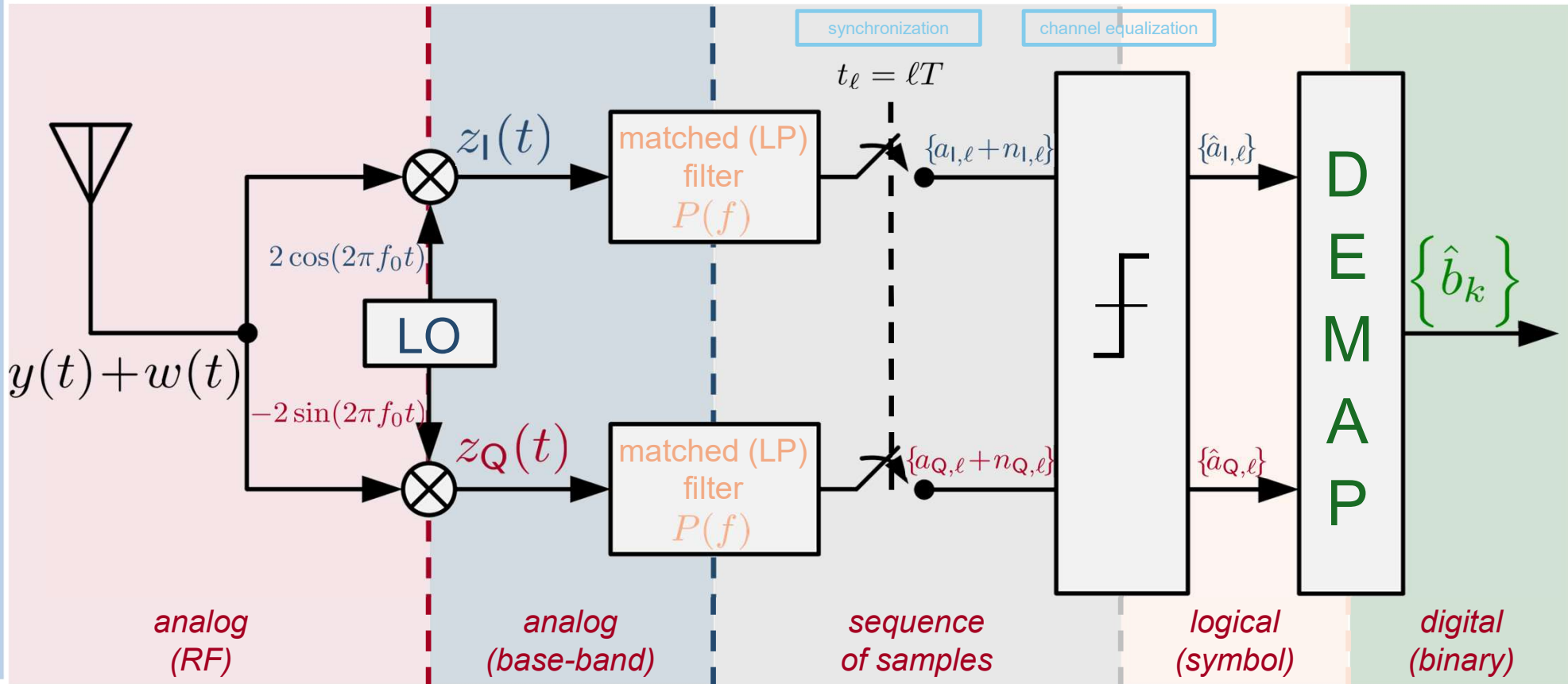
Exercise: Derive the mapping for the binary PSK (BPSK)

The I-Q modulator



Communication systems (25/26) M.Sc. Communications Eng.

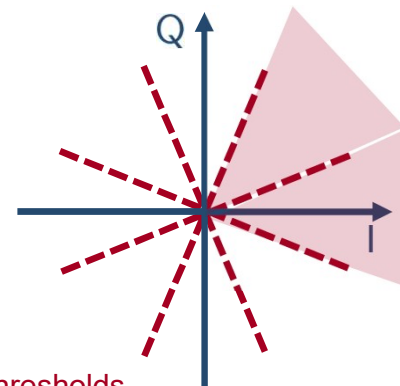
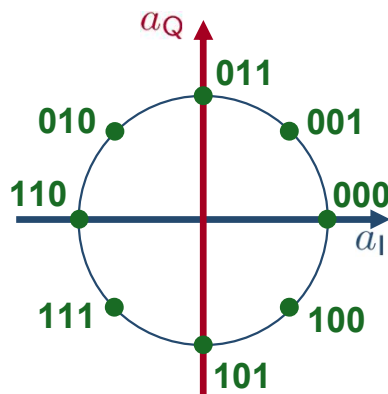
The I-Q demodulator (1/4)



Communication systems (25/26) M.Sc. Communications Eng.

The I-Q demodulator (2/4)

Example of **threshold-based detection**: let us suppose to use 8-PSK



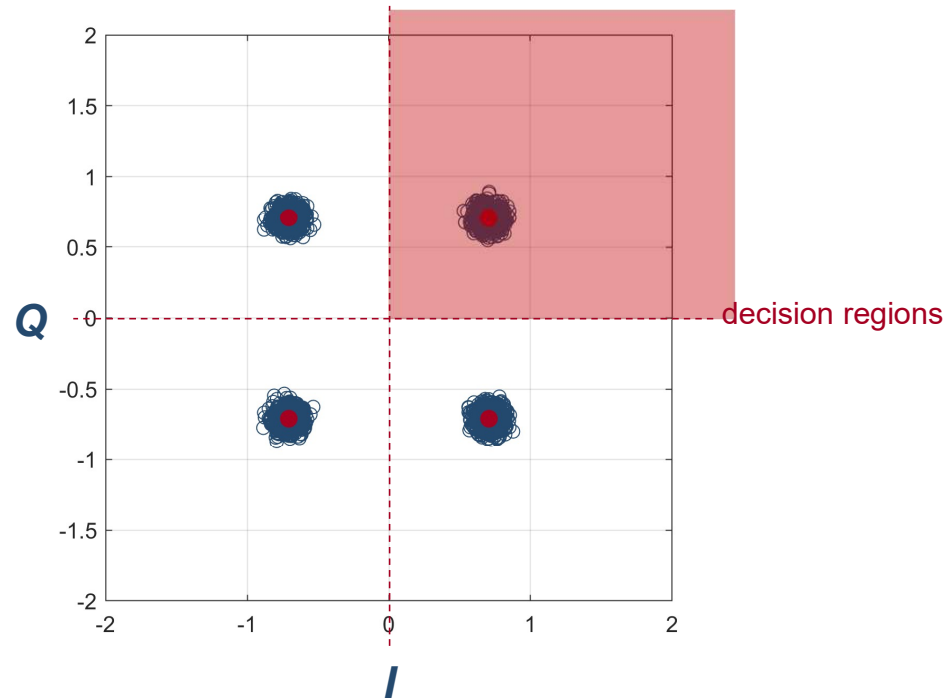
decision thresholds

any sample with coordinates $(a_{1,\ell} + n_{1,\ell}, a_{Q,\ell} + n_{Q,\ell})$ falling in this region gives the symbol $\hat{a}_{1,\ell} = 1/\sqrt{2}, \hat{a}_{Q,\ell} = 1/\sqrt{2}$
after de-mapping, we have **001**

any sample with coordinates $(a_{1,\ell} + n_{1,\ell}, a_{Q,\ell} + n_{Q,\ell})$ falling in this region gives the symbol $\hat{a}_{1,\ell} = 1, \hat{a}_{Q,\ell} = 0$
after de-mapping, we have **000**

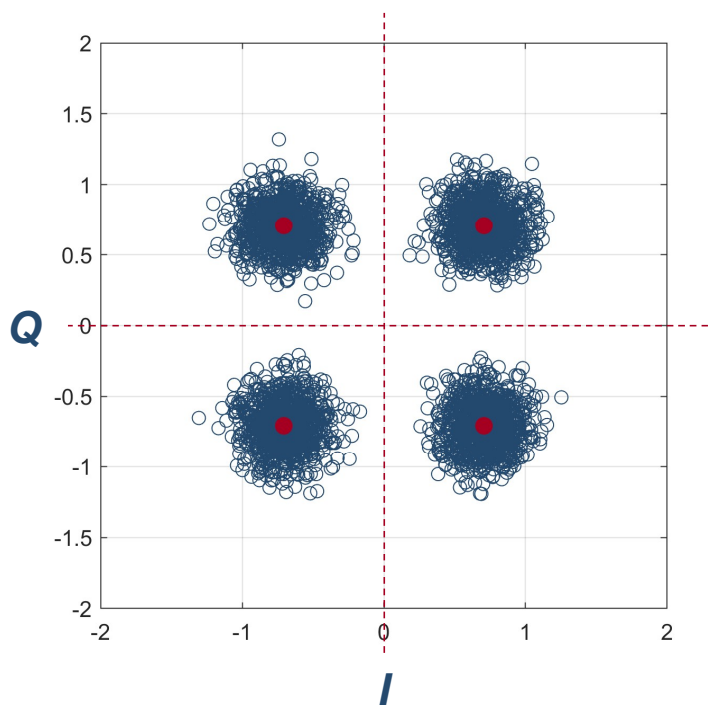
The I-Q demodulator (3/4)

What happens when using a QPSK modulation in a high signal-to-noise ratio (SNR) scenario?

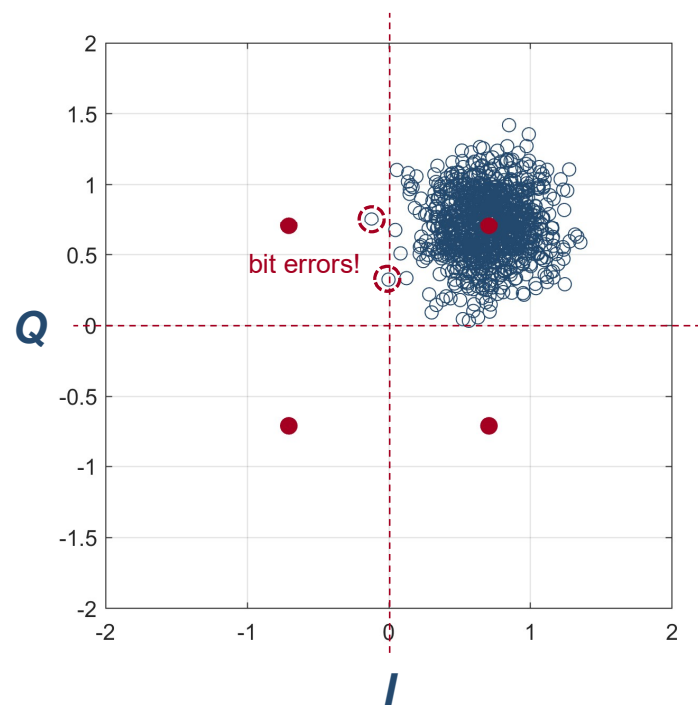


The I-Q demodulator (4/4)

medium-SNR scenario



low-SNR scenario



Impact of additive white Gaussian noise (AWGN) (1/5)

How can we **quantify** the impact of AWGN in the demodulation performance?

The main **figure of merit** becomes the signal-to-noise ratio (SNR), in the form of

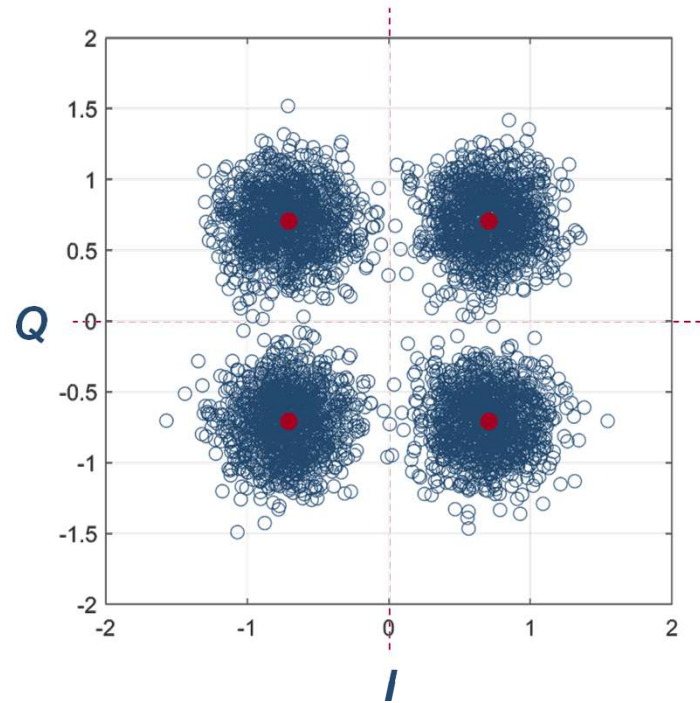
$$\frac{\text{energy per bit}}{\text{noise power spectral density}} = \frac{\text{useful signal power}}{\text{noise power}} \cdot \frac{\text{signal bandwidth}}{\text{bit rate}}$$

$$\frac{E_b}{N_0} = \frac{S}{N} \cdot \frac{B}{R_b}$$

The performance of a digital communication system can be assessed measuring the **bit error rate (BER)** – which occurs when $\hat{b}_k \neq b_k$ – and the **symbol error rate (SER)** – which occurs when $(\hat{a}_{I,e} + j\hat{a}_{Q,e}) \neq (a_{I,e} + ja_{Q,e})$

Impact of additive white Gaussian noise (AWGN) (2/5)

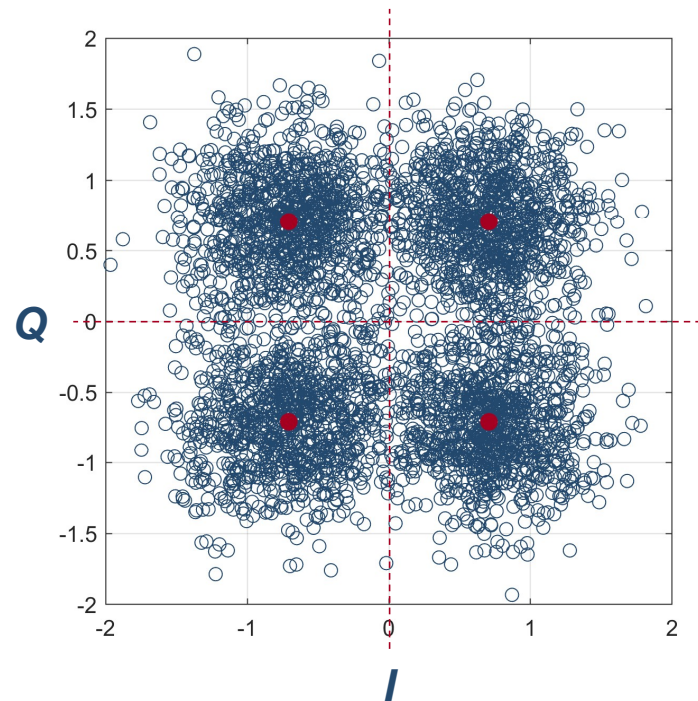
QPSK @
 $E_b/N_0 = 10\text{dB}$



Impact of additive white Gaussian noise (AWGN) (3/5)

The situation becomes dramatic when either **increasing the AWGN power...**

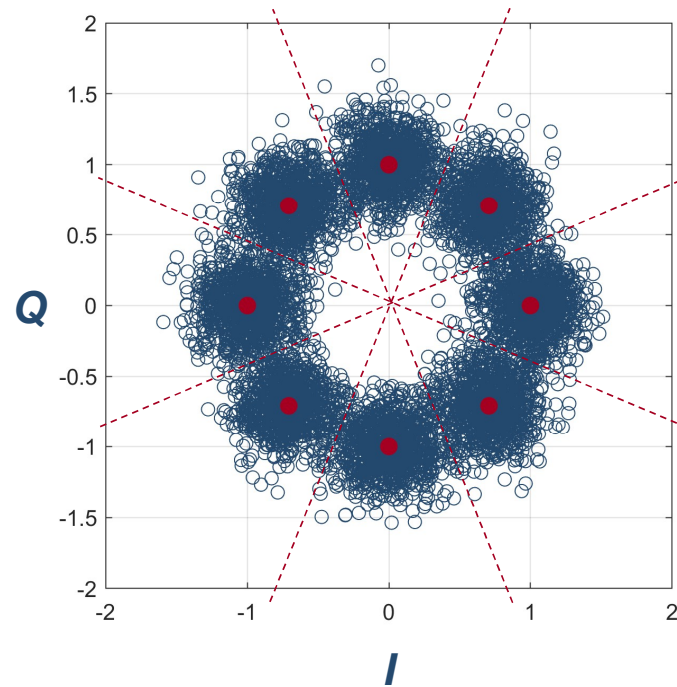
QPSK @
 $E_b/N_0 = 3$ dB



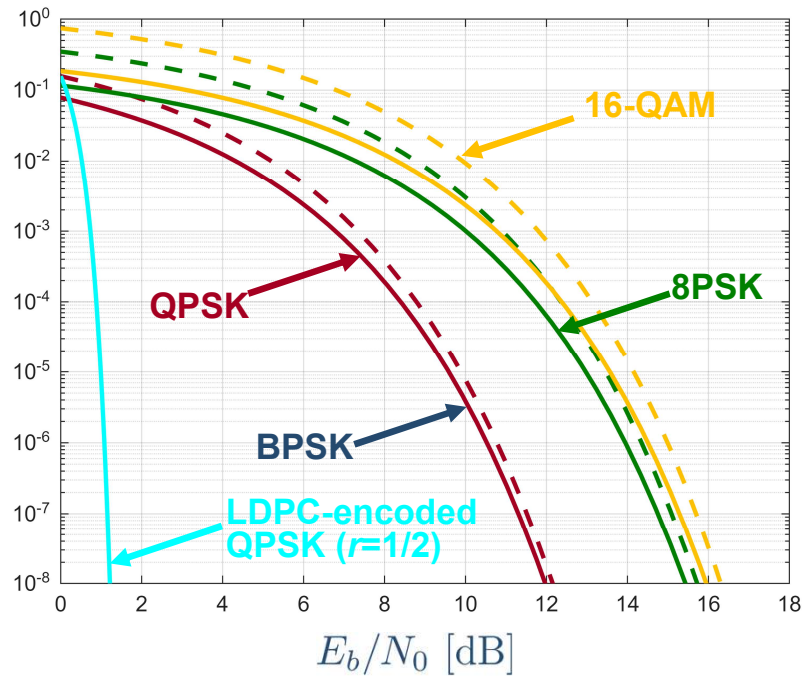
Impact of additive white Gaussian noise (AWGN) (4/5)

...or when increasing the modulation order

8PSK @
 $E_b/N_0 = 7$ dB



Performance with AWGN



— BER p_e
 - - - SER $\approx N_b p_e$

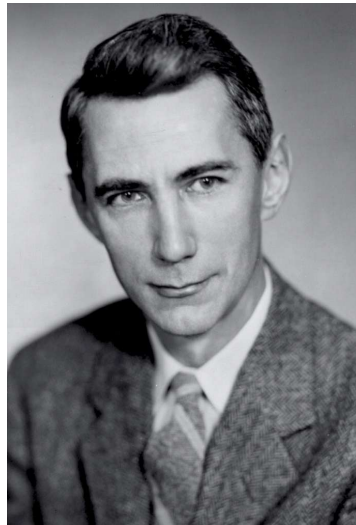


Shannon capacity (1/3)

How can we evaluate the performance of a system?

$$R_b \leq C = B \cdot \log_2 \left(1 + \frac{S}{N} \right) = B \cdot \log_2 \left(1 + \frac{E_b}{N_0} \cdot \frac{R_b}{B} \right)$$

↑
Shannon
capacity



Communication Theory of Secrecy Systems*

By C. E. SHANNON

1. INTRODUCTION AND SUMMARY

THE problems of cryptography and secrecy systems furnish an interesting application of communication theory. In this paper a theory of secrecy systems is developed. The approach is on a theoretical level and is intended to complement the treatment found in standard works on cryptography. There, a detailed study is made of the many standard types of codes and ciphers, and of the ways of breaking them. We will be more concerned with the general mathematical structure and properties of secrecy systems.

The treatment is limited in certain ways. First, there are three general types of secrecy system: (1) concealment systems, including such methods as invisible ink, concealing a message in an innocent text, or in a false covering cryptogram, or other methods in which the existence of the message is concealed from the enemy; (2) privacy systems, for example speech inversion, in which special equipment is required to recover the message; (3) "true" secrecy systems where the meaning of the message is concealed by cipher, code, etc., although its existence is not hidden, and the enemy is assumed to have any special equipment necessary to intercept and record the transmitted signal. We consider only the third type—concealment systems are primarily a psychological problem, and privacy systems a technological one.

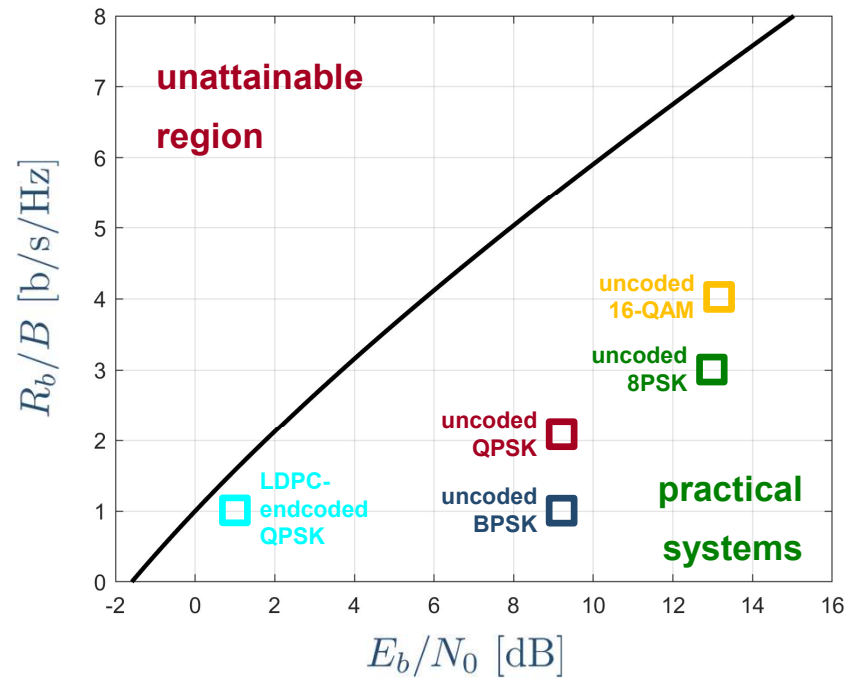
Secondly, the treatment is limited to the case of discrete information, where the message to be enciphered consists of a sequence of discrete symbols, each chosen from a finite set. These symbols may be letters in a language, words of a language, amplitude levels of a "quantized" speech or video signal, etc., but the main emphasis and thinking has been concerned with the case of letters.

The paper is divided into three parts. The main results will now be briefly summarized. The first part deals with the basic mathematical structure of secrecy systems. As in communication theory a language is considered to

*The material in this paper appeared originally in a confidential report "A Mathematical Theory of Cryptography" dated Sept. 1, 1945, which has now been declassified. Shannon, C. E., "A Mathematical Theory of Communications," *Bell System Technical Journal*, July 1948, p. 379; Oct. 1948, p. 623.

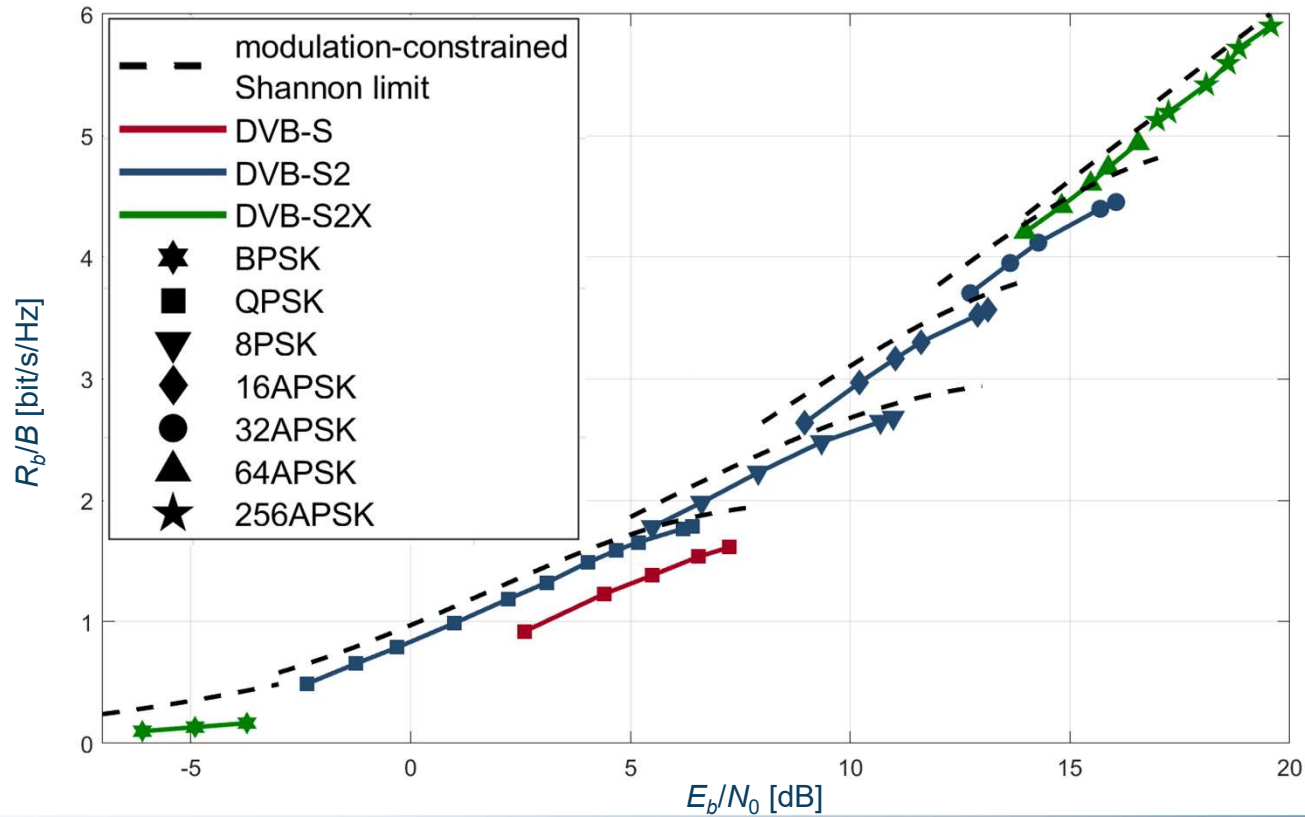
See, for example, H. F. Gauss, "Elementary Cryptanalysis," or M. Givierge, "Omnis de Cryptographia."

Shannon capacity (2/3)



Shannon capacity (3/3)

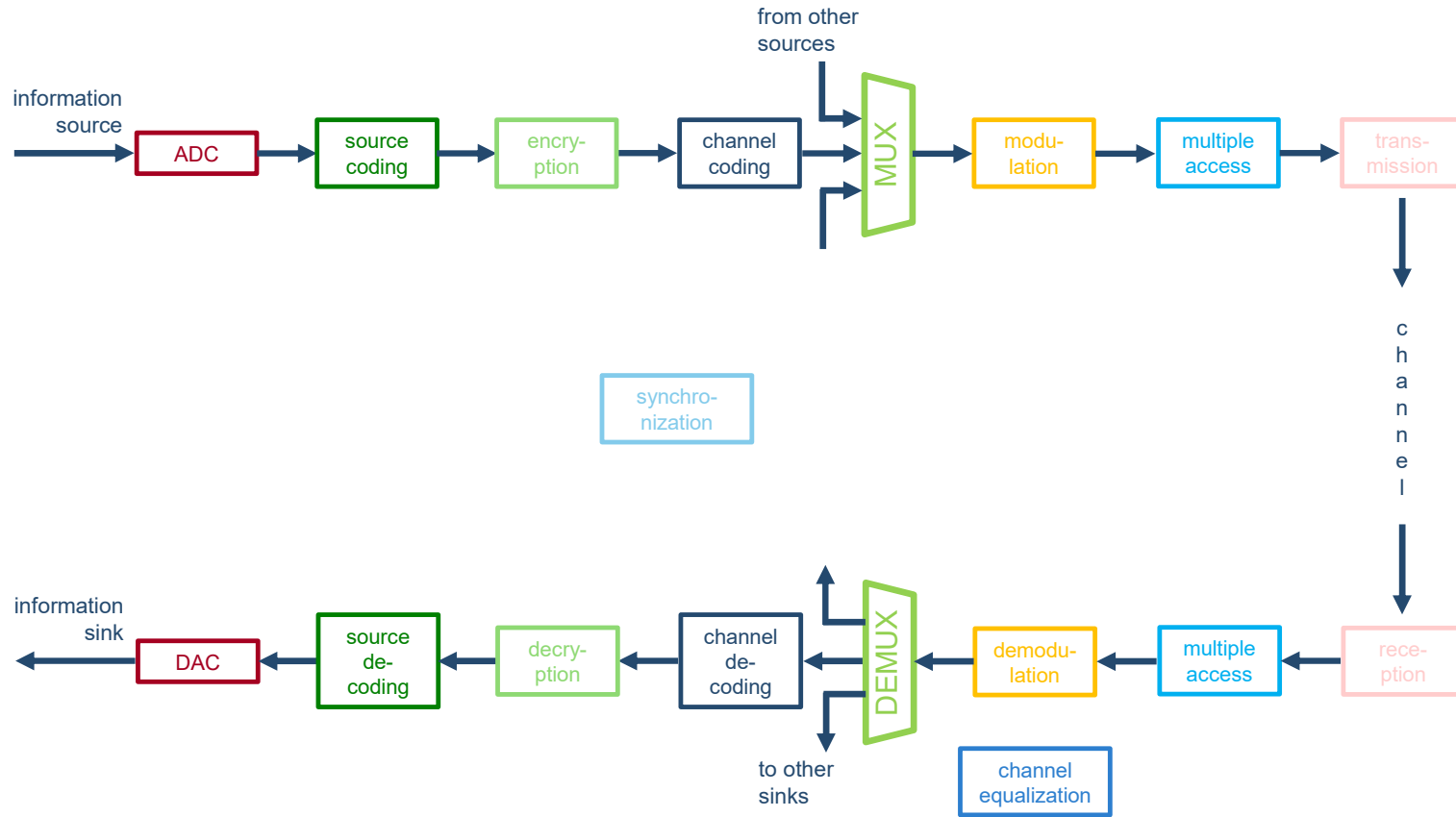
Example: adaptive coding and modulation used by satellite standards





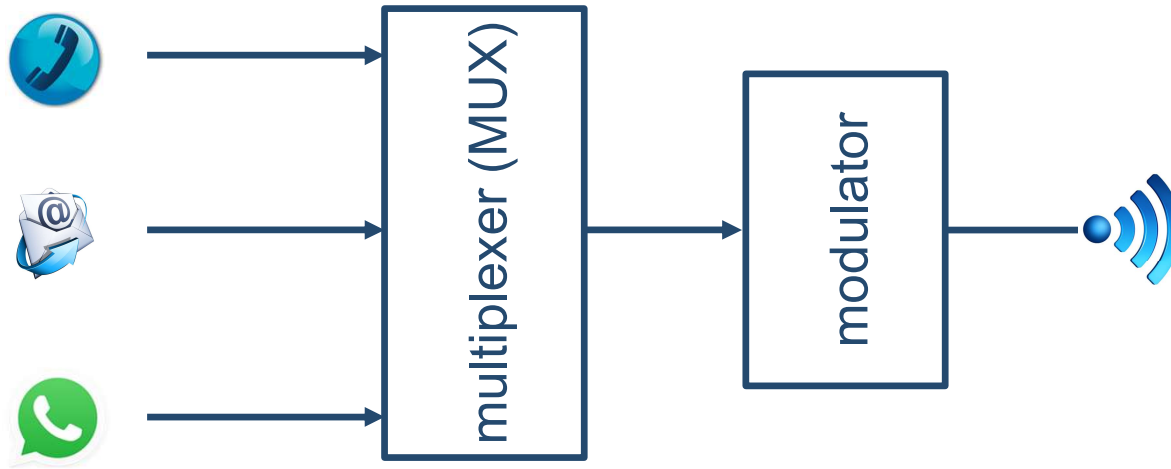
Multiplexing

Elements of a digital communication system



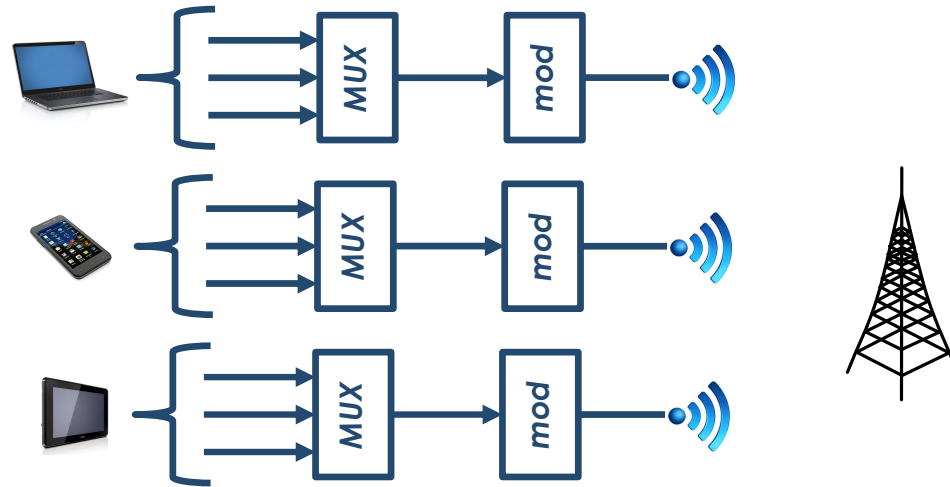
Multiplexing vs. multiple access (1/3)

Multiplexing: separating different flows at the same transmit side



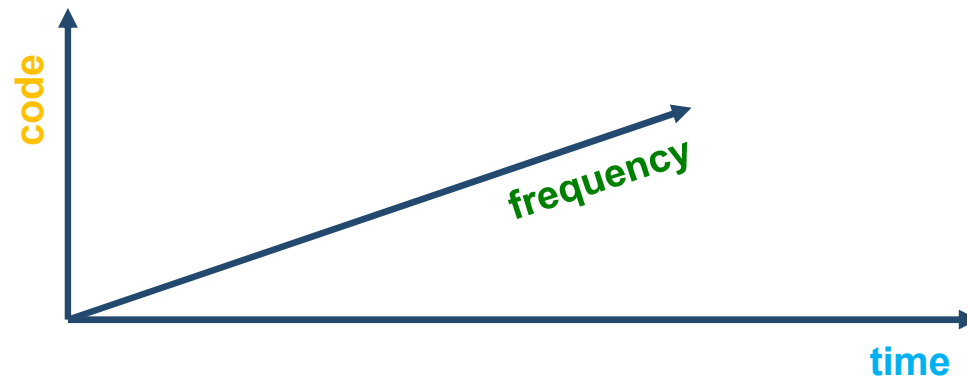
Multiplexing vs. multiple access (2/3)

Multiple access: separating different users at the receiver side



Multiplexing vs. multiple access (3/3)

We can exploit several **degrees of freedom**: frequency, time, space, codes, etc.

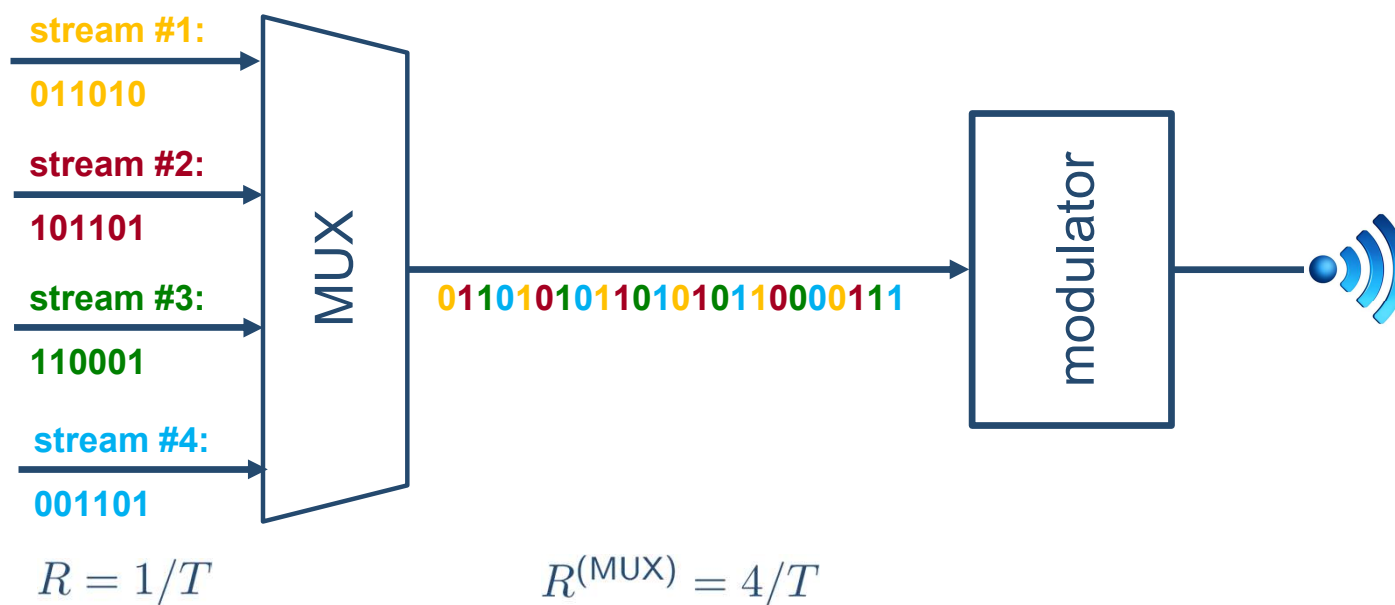


Time division multiplexing (TDM)



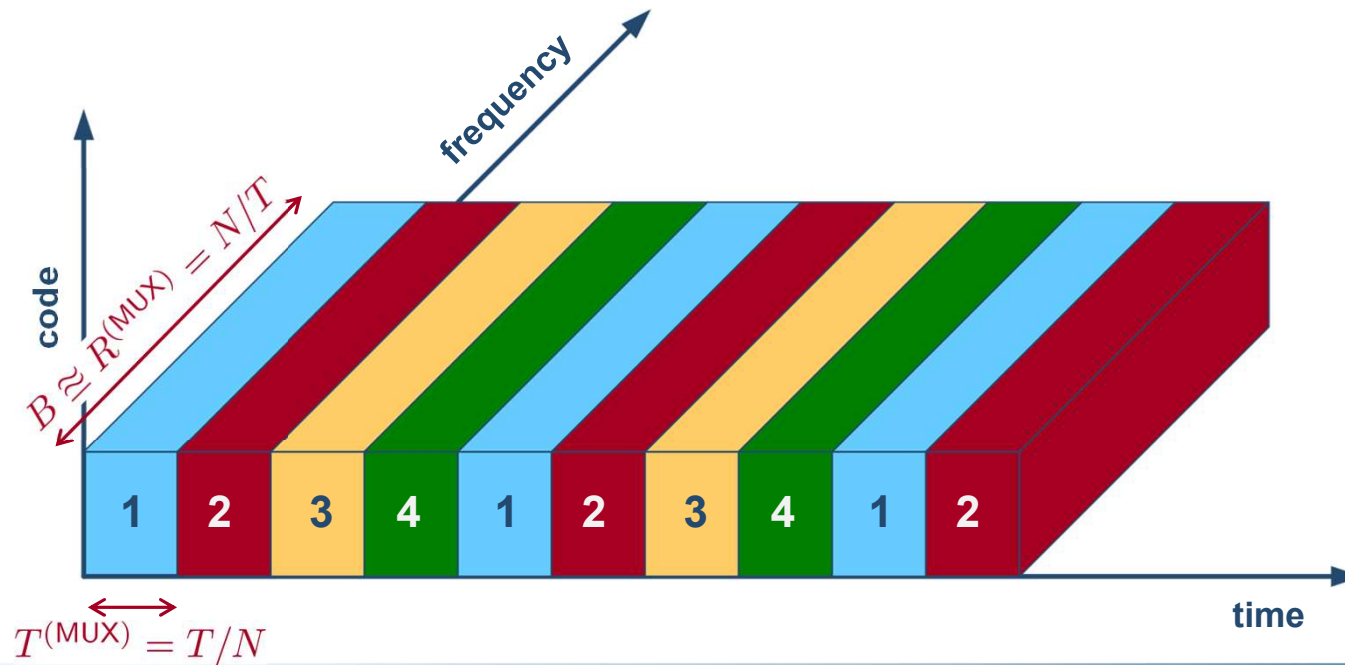
Time division multiplexing (TDM) (1/2)

In practice, TDM works as follows:



Time division multiplexing (TDM) (2/2)

Each stream makes use of the **whole** bandwidth using a **round robin** scheduling, with time slot duration $T^{(\text{MUX})} = T/N$:



Practical applications of TDM

- **E1 (Europe) & T1 (USA and Japan): byte-based TDM**
- NRZ binary signals, with $R = 64 \text{ kb/s}$ and $T = 15.625 \mu\text{s}$ are **grouped** byte by byte:
 $T_B = 8T = 125 \mu\text{s}$
- The E1 multiplex includes **$N=32$** streams (30: data plane, 2: control plane)
- The TDM signal shows $R^{(\text{MUX})} = N \cdot R = 2.048 \text{ Mb/s}$ and $T^{(\text{MUX})} = T/N \simeq 0.49 \mu\text{s}$
(for a **re-clocked** byte time $\simeq 3.9 \mu\text{s}$)

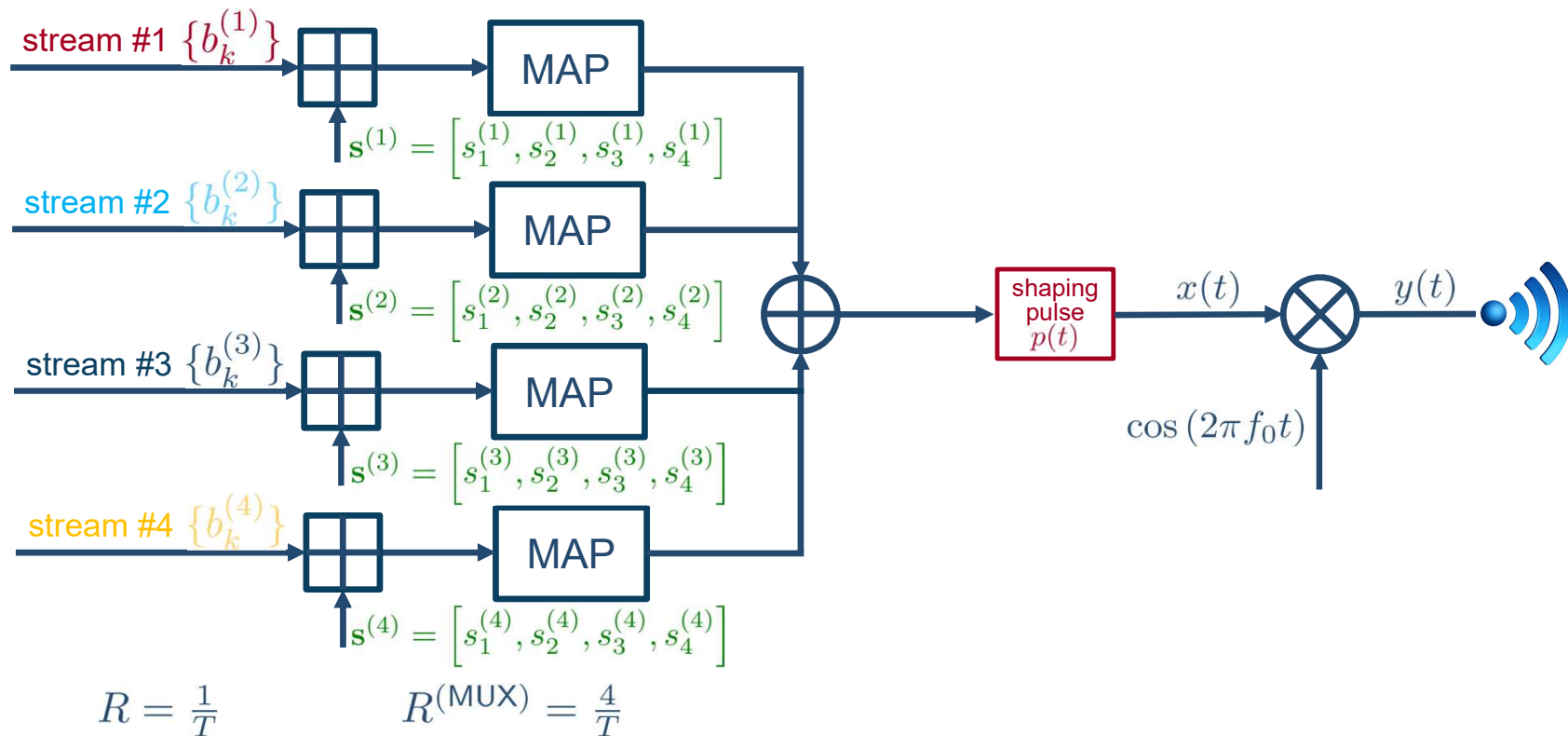


Code division multiplexing (CDM)



Code division multiplexing (CDM) (1/4)

In practice, CDM works as follows:

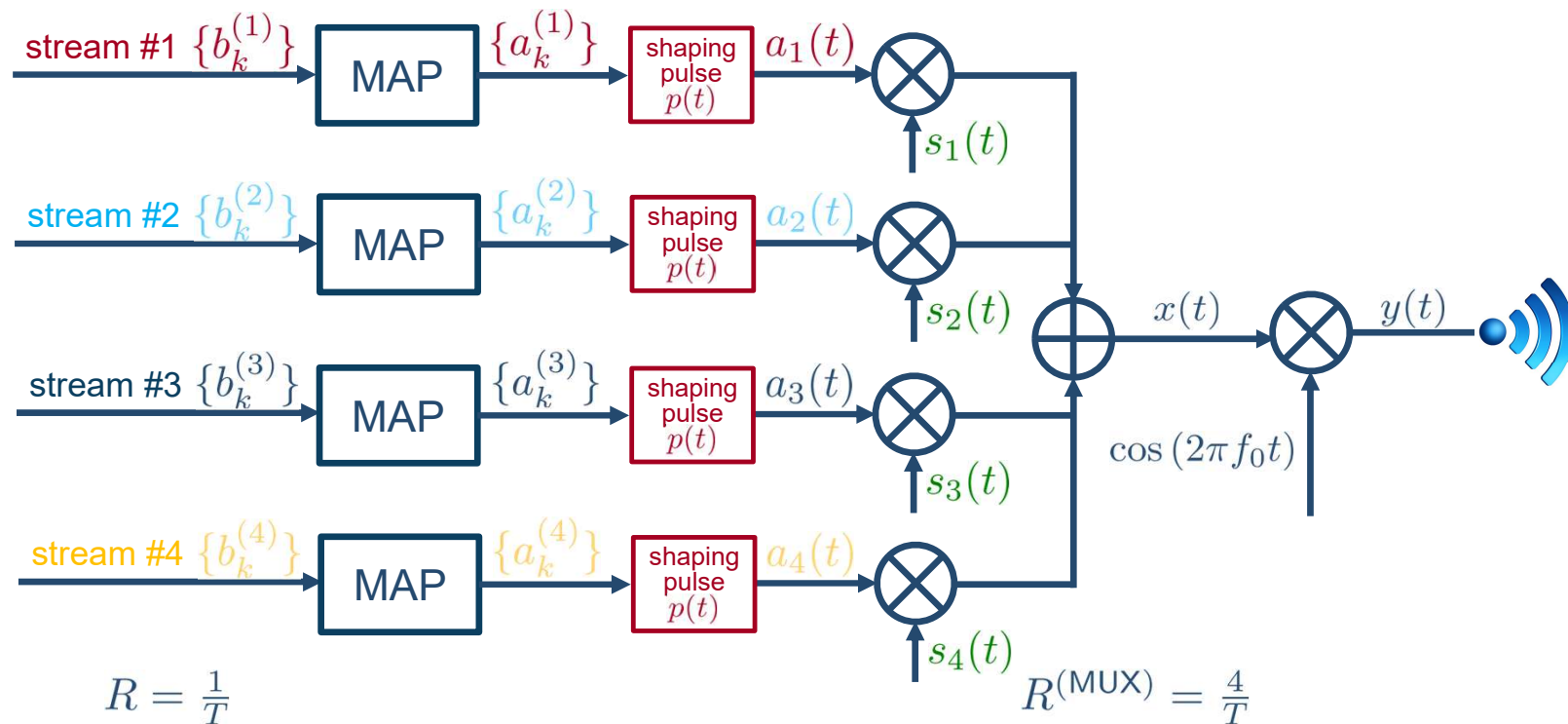


$$R = \frac{1}{T}$$

$$R^{(\text{MUX})} = \frac{4}{T}$$

Code division multiplexing (CDM) (2/4)

To better visualize it, let us use the following **equivalent** scheme:

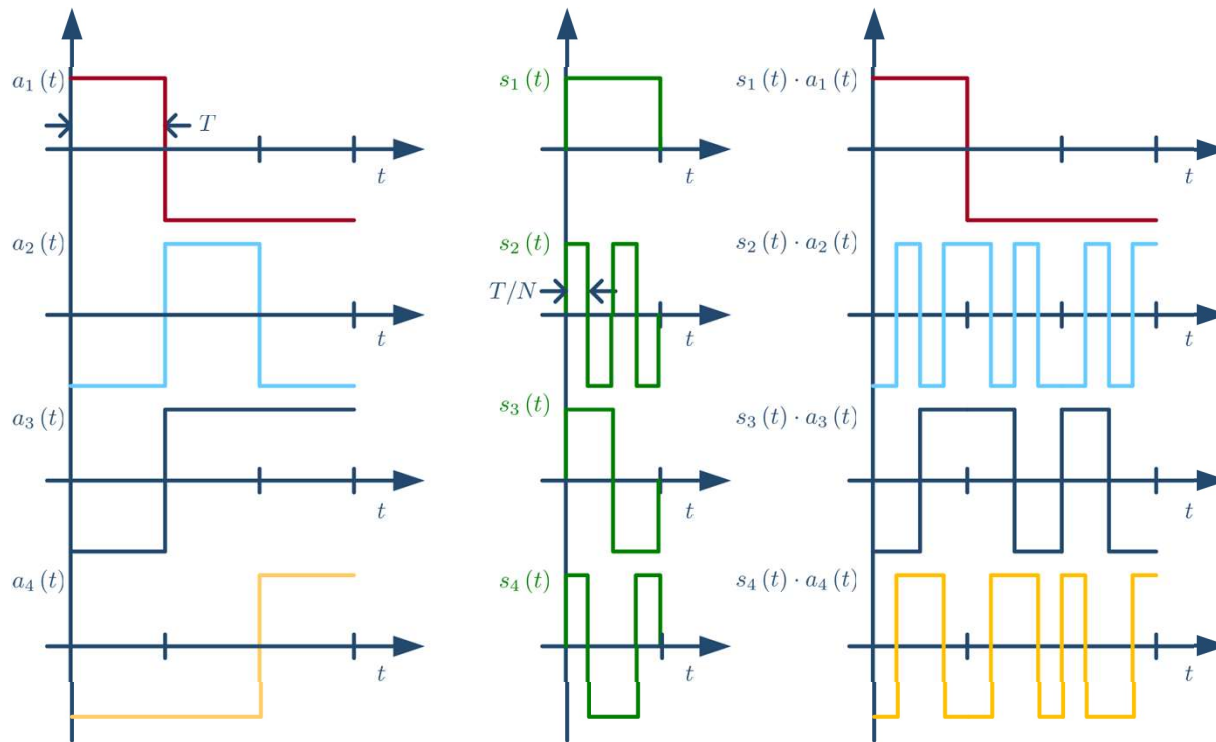


$$R = \frac{1}{T}$$

$$R^{(\text{MUX})} = \frac{4}{T}$$

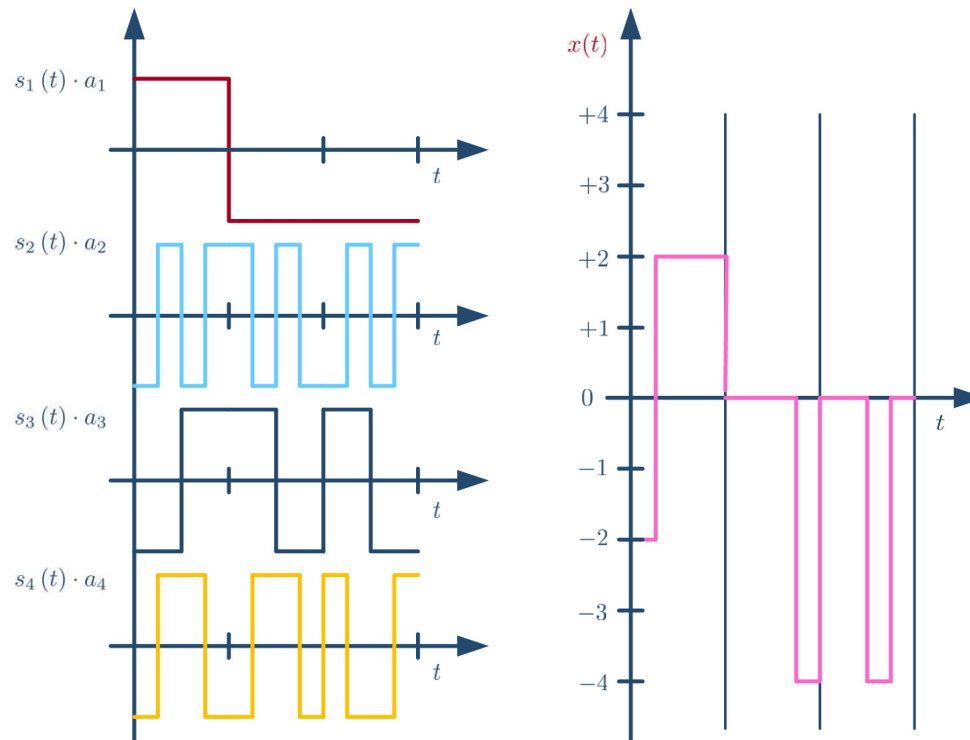
Code division multiplexing (CDM) (3/4)

In CDM, signatures are given by a code set $\{s_n(t)\}_{n=1}^N$:



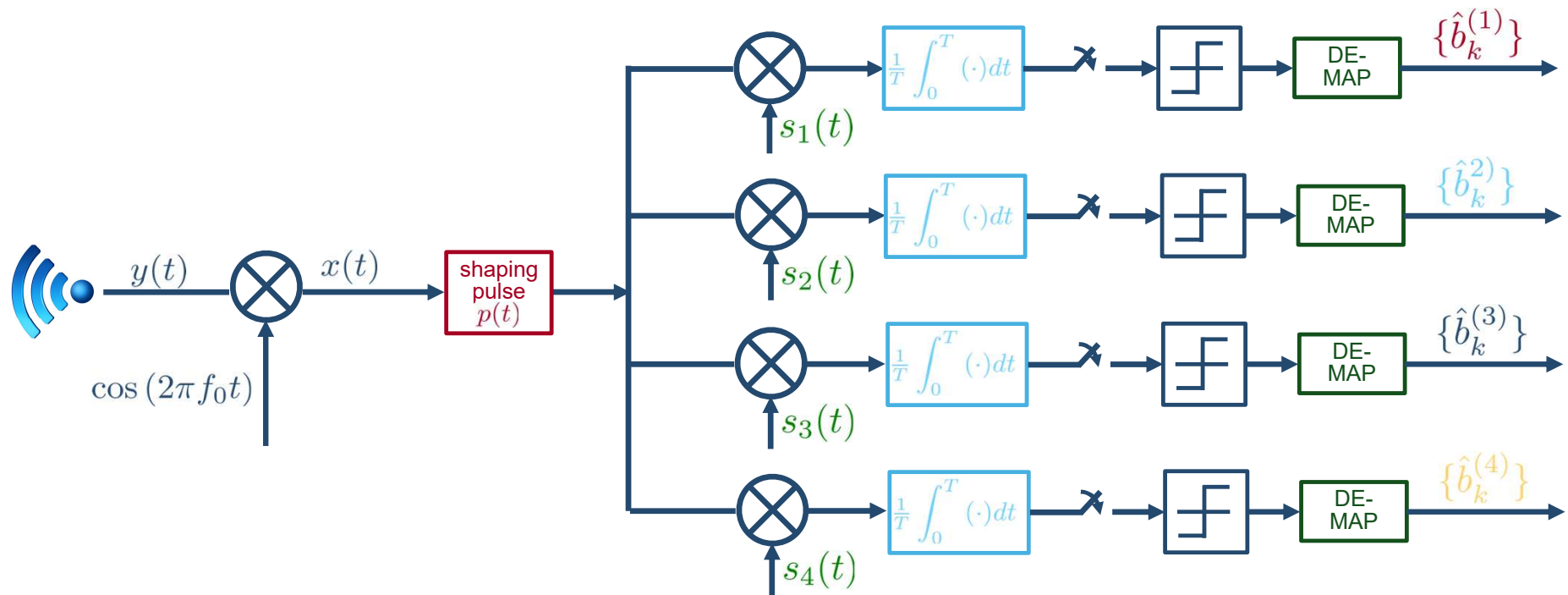
Code division multiplexing (CDM) (4/4)

The CDM-multiplexed signal is the summation of all coded streams:



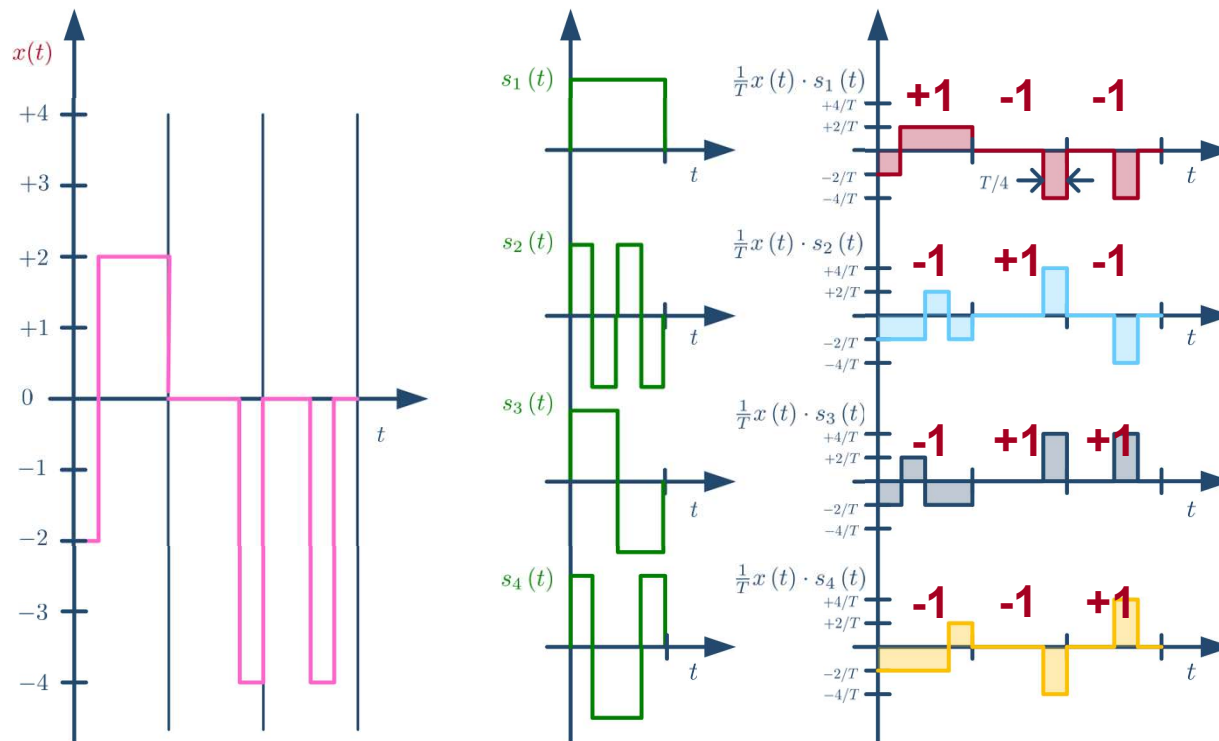
CDM demultiplexing (1/3)

At the receiver, the following operations needs to be done:



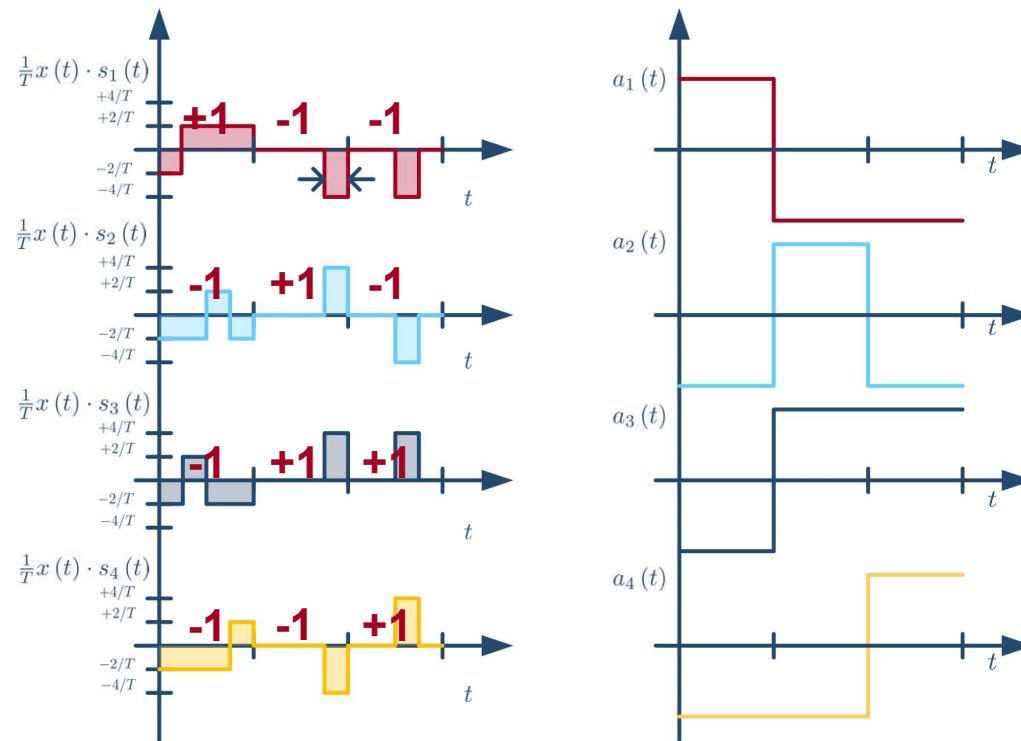
CDM demultiplexing (2/3)

To decode the n th stream, the receiver needs to know the code set:



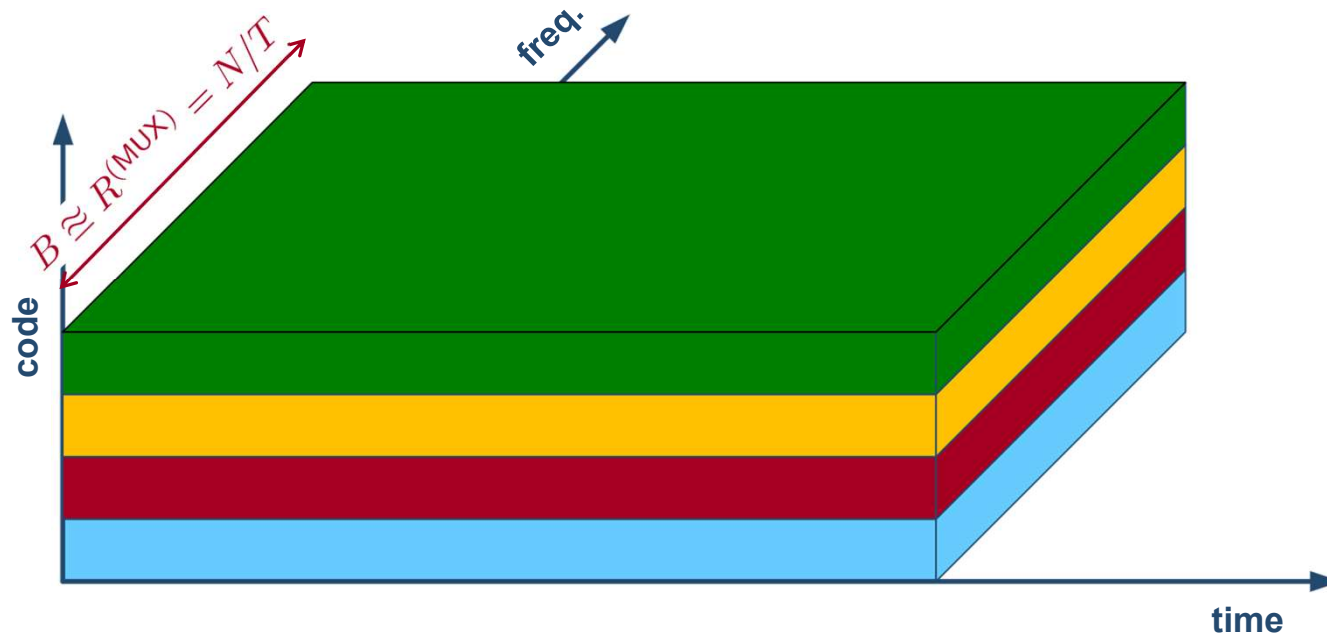
CDM demultiplexing (3/3)

To decode the n th stream, the receiver needs to know the code set:



CDM in 3D resource plan

This holds true for each CDM signal obtained with orthogonal codes: it makes **continuous** use of the **whole** bandwidth:



Walsh-Hadamard codes (1/4)

A useful set of signature codes for CDM is the **Walsh-Hadamard** (WH) code set

The n th code of the WH set is represented by the n th row of the N -order **Hadamard matrix** \mathbf{H}_N :

$$\mathbf{H}_4 = \begin{bmatrix} +1 & +1 & +1 & +1 \\ +1 & -1 & +1 & -1 \\ +1 & +1 & -1 & -1 \\ +1 & -1 & -1 & +1 \end{bmatrix} \begin{matrix} \mathbf{s}^{(1)} \\ \mathbf{s}^{(2)} \\ \mathbf{s}^{(3)} \\ \mathbf{s}^{(4)} \end{matrix}$$

Walsh-Hadamard codes (2/4)

The N -order WH code set, with cardinality $N = 2^W$, with $W \in \mathbb{N}$, can be obtained in a **recursive** fashion:

$$\mathbf{H}_2 \triangleq \begin{bmatrix} +1 & +1 \\ +1 & -1 \end{bmatrix}, \quad \mathbf{H}_N = \mathbf{H}_2 \otimes \mathbf{H}_{N/2} = \begin{bmatrix} \mathbf{H}_{N/2} & \mathbf{H}_{N/2} \\ \mathbf{H}_{N/2} & \overline{\mathbf{H}}_{N/2} \end{bmatrix}$$

where \otimes is the Kronecker product, and $\overline{\mathbf{H}}$ is the modulo-2 complement of the matrix \mathbf{H}



Walsh-Hadamard codes (3/4)

Examples:

$$\mathbf{H}_2 \triangleq \begin{bmatrix} +1 & +1 \\ +1 & -1 \end{bmatrix}$$

$$\mathbf{H}_4 = \begin{bmatrix} \mathbf{H}_2 & \mathbf{H}_2 \\ \mathbf{H}_2 & \overline{\mathbf{H}}_2 \end{bmatrix}$$

$$\mathbf{H}_8 = \begin{bmatrix} \mathbf{H}_4 & \mathbf{H}_4 \\ \mathbf{H}_4 & \overline{\mathbf{H}}_4 \end{bmatrix}$$

Walsh-Hadamard codes (4/4)

Exercise: Show that this signature set $\{c_n(t)\}_{n=1}^N$ is orthogonal

$$\frac{1}{T} \int_0^T c_n(t) \cdot c_m^*(t) dt = \delta[n - m] \quad \forall n, m$$

Thanks to this property, codes like the WH ones are called **orthogonal codes**



CDM vs. TDM (1/2)

Similarly to TDM, in CDM all streams need to be **synchronized** (hence, CDM is not suitable for analog systems)

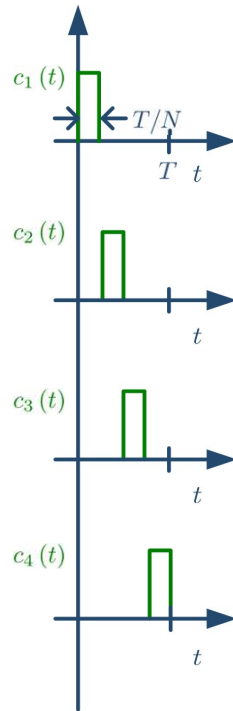
However, signatures in TDM are non-null only for a time slot, whereas codes in CDM are **pseudo-random noise sequences**:

$$\text{TDM:} \quad \frac{1}{T} \int_0^T c_n(t) dt = \frac{1}{N}$$

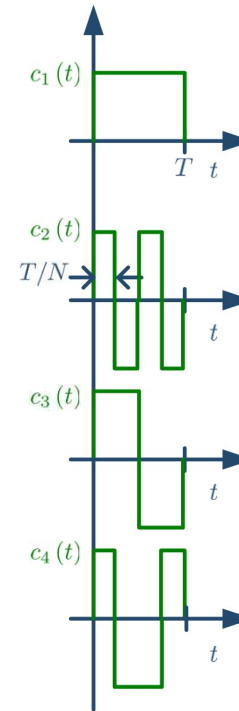
$$\text{CDM:} \quad \frac{1}{T} \int_0^T c_n(t) dt = 0$$

CDM vs. TDM (2/2)

$$\text{TDM: } \frac{1}{T} \int_0^T c_n(t) dt = \frac{1}{N}$$



$$\text{CDM: } \frac{1}{T} \int_0^T c_n(t) dt = 0$$

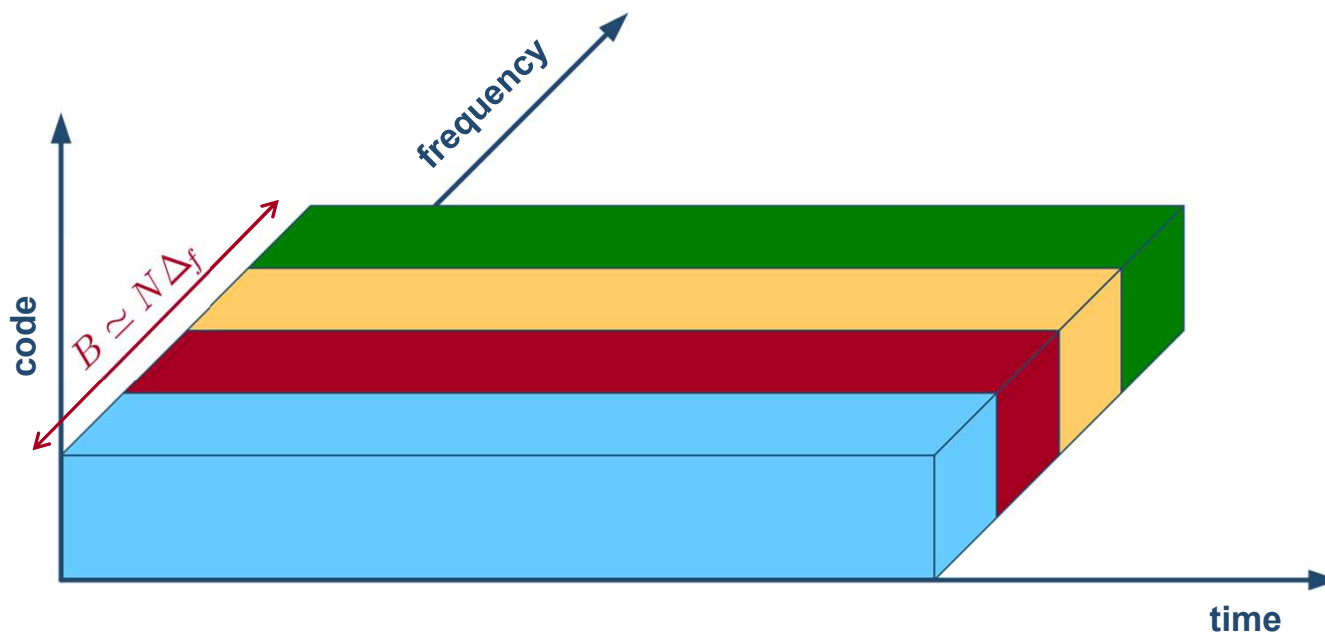


Orthogonal frequency division multiplexing (OFDM)



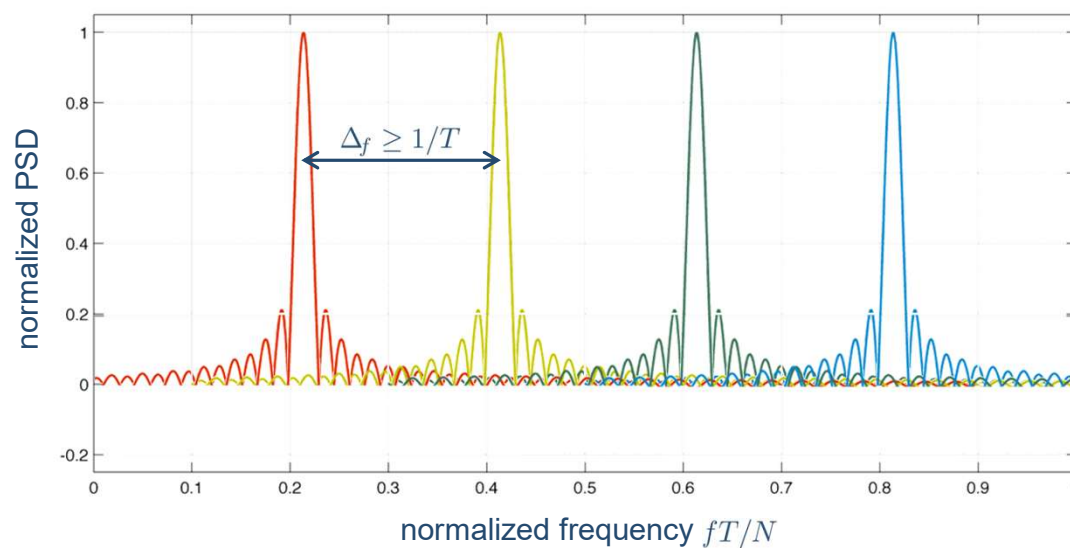
Frequency division multiplexing (FDM) (1/2)

We can also exploit the degree of freedom offered by the frequency, by separating N streams that do **not overlap** in the frequency domain, so as to form an FDM signal:



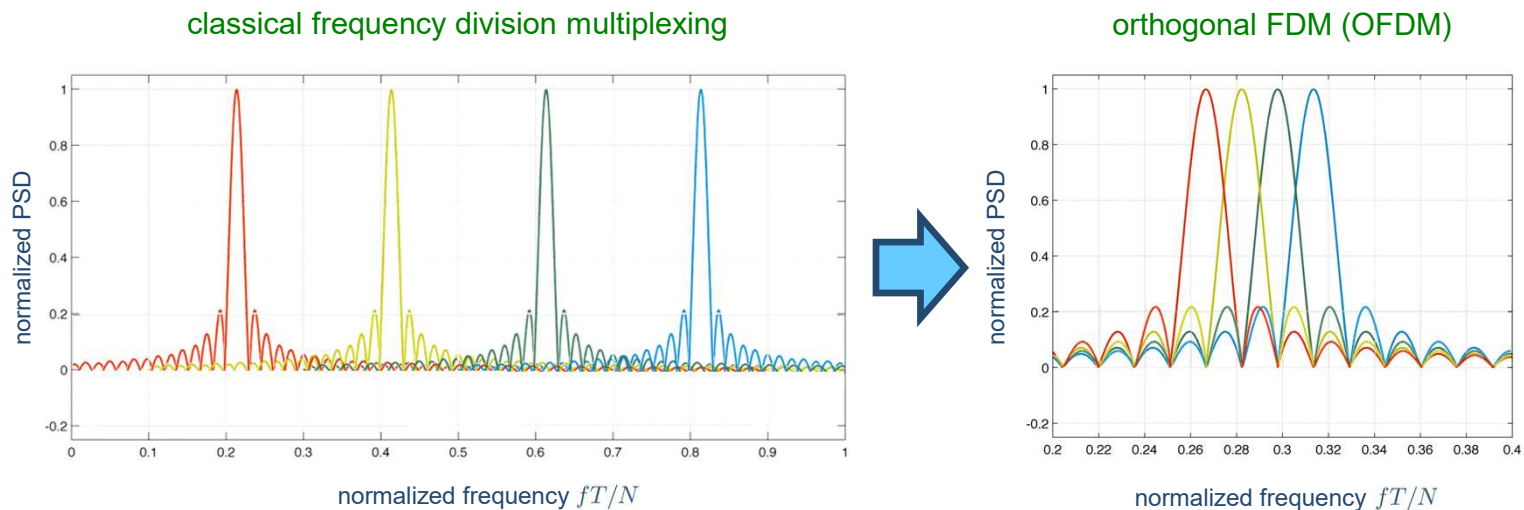
Frequency division multiplexing (FDM) (2/2)

The PSD of a frequency-division multiplexed signal is



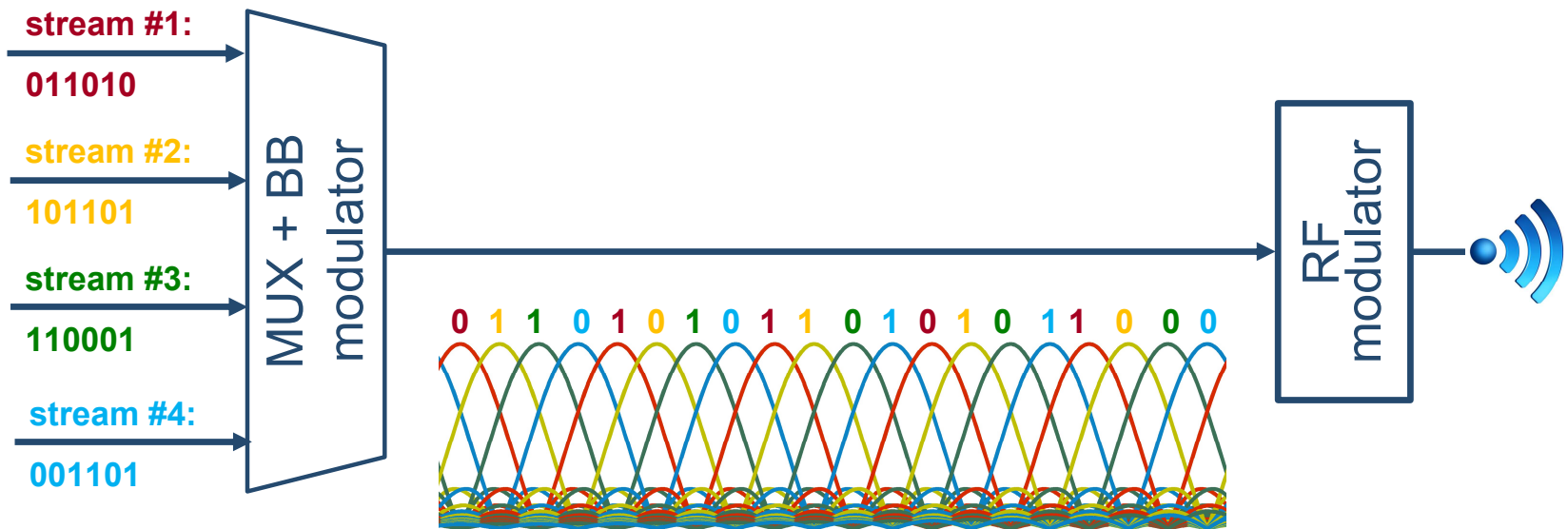
Orthogonal frequency division multiplexing (OFDM) (1/3)

The **minimum** bandwidth occupancy is given by $\Delta_f = 1/T$, corresponding to the first null of each stream's PSD:



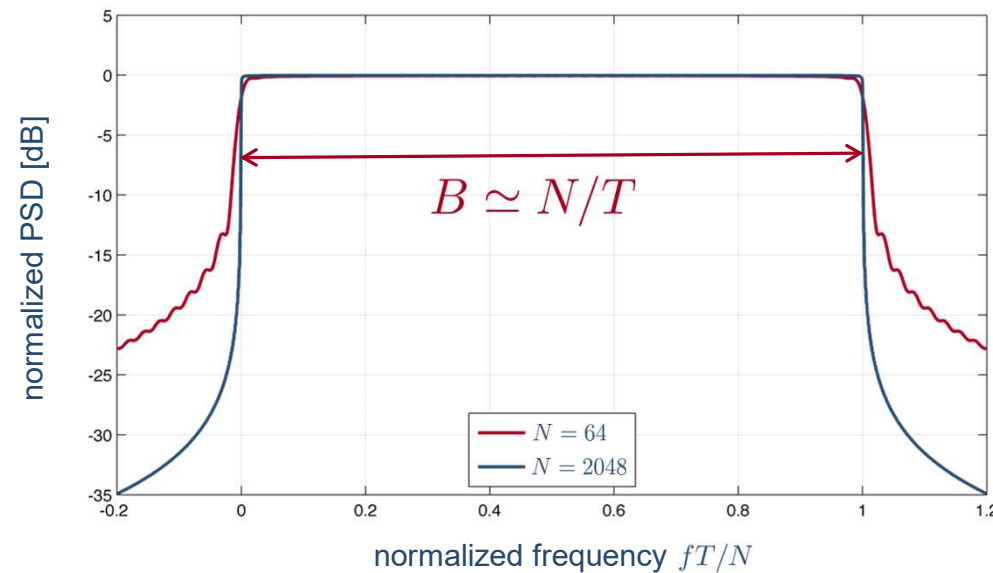
Orthogonal frequency division multiplexing (OFDM) (2/3)

OFDM works as follows:



Orthogonal frequency division multiplexing (OFDM) (3/3)

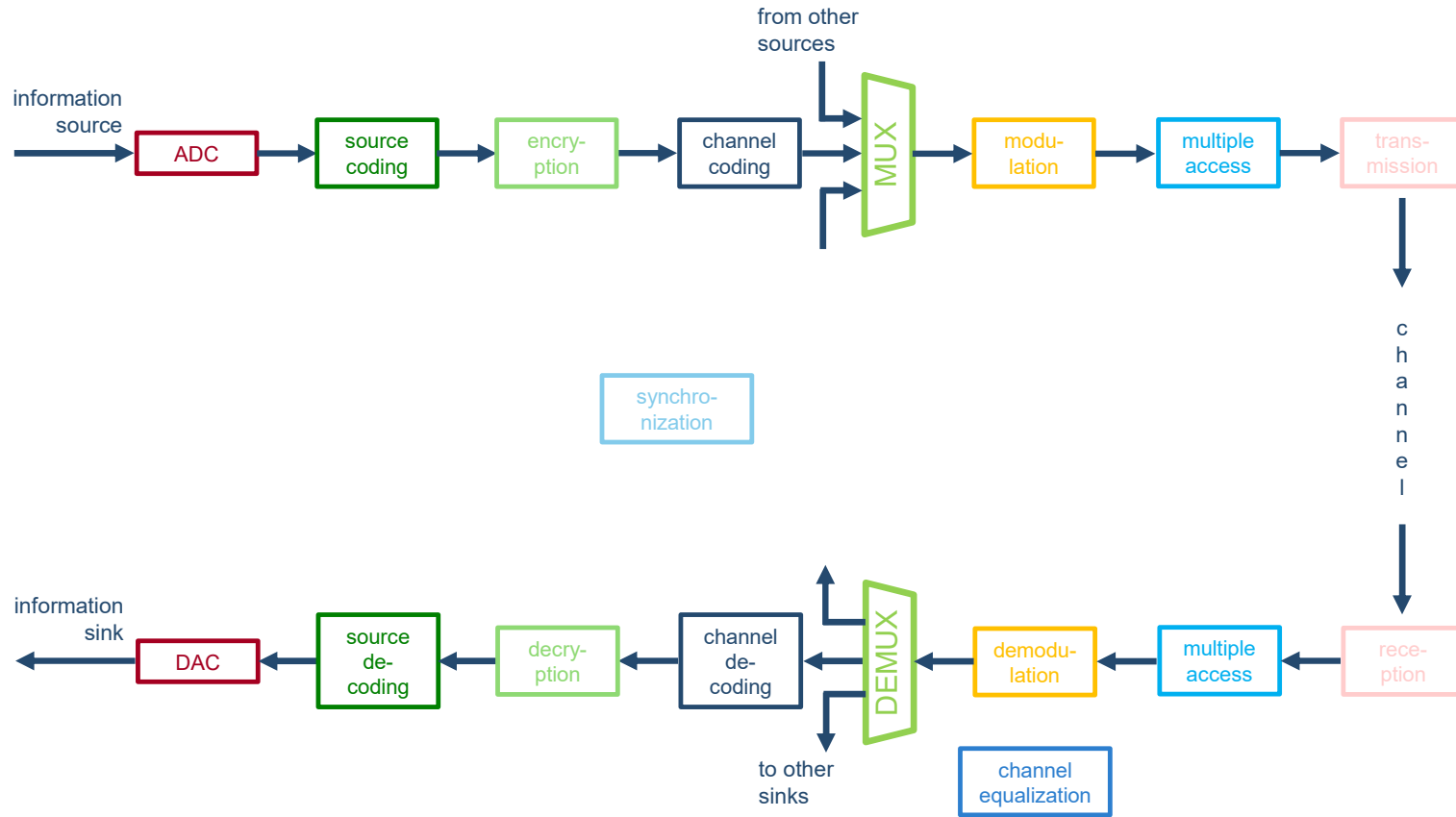
The PSD of the OFDM signal is given by $\mathcal{P}_{\text{MUX}}(f) = \sum_{n=1}^N \mathcal{P}_n(f - n/T)$, where $\mathcal{P}_n(f) = T \cdot \text{sinc}^2(fT)$



Multiple access

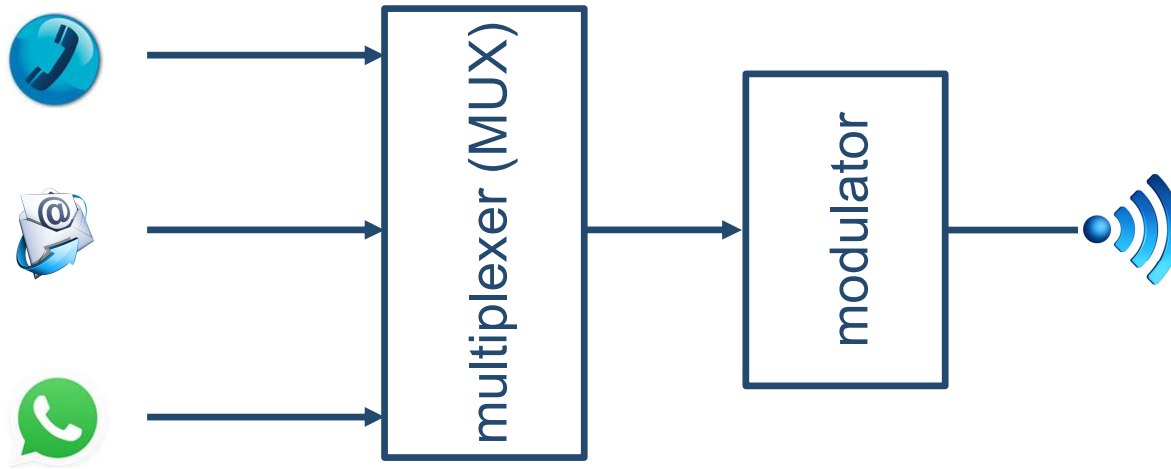


Elements of a digital communication system



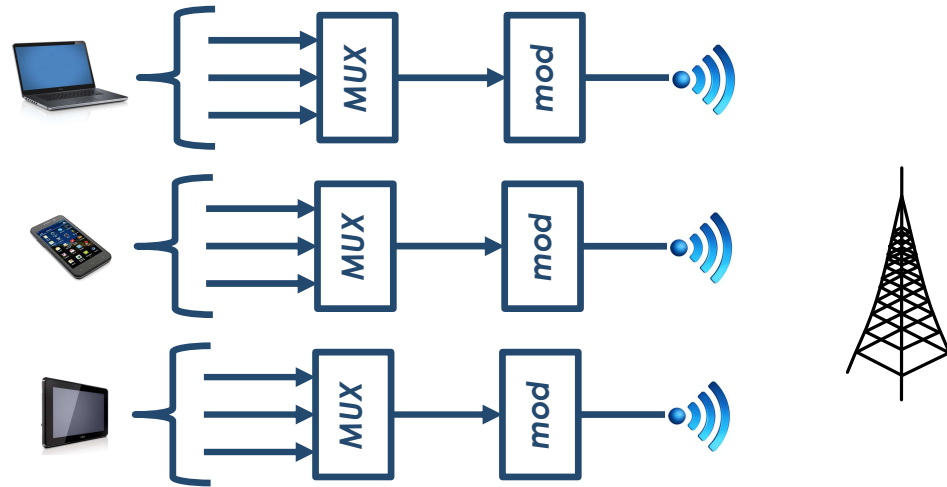
Multiplexing vs. multiple access (1/3)

Multiplexing: separating different flows at the same transmit side



Multiplexing vs. multiple access (2/3)

Multiple access: separating different users at the receiver side



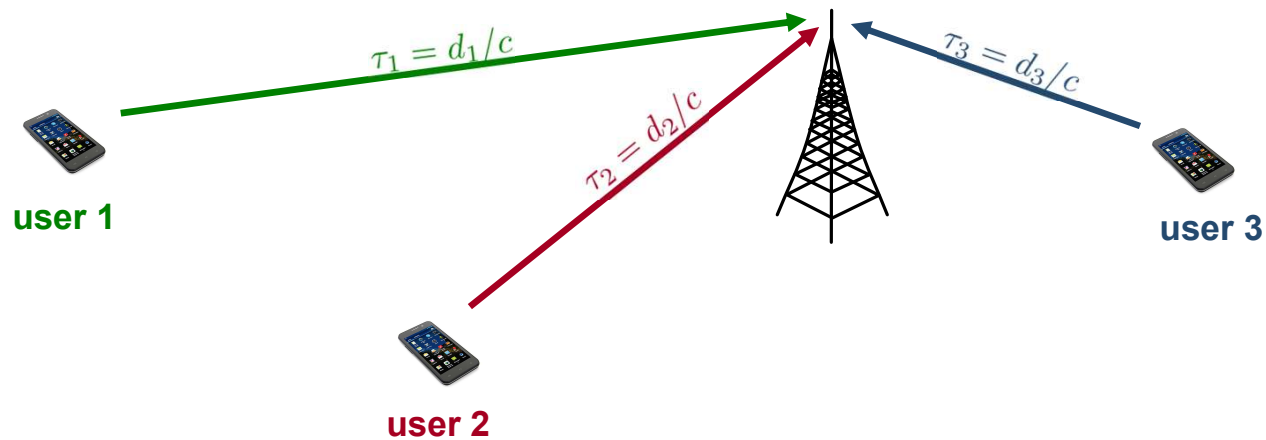
Time division multiple access (TDMA)



Time division multiple access (TDMA) (1/3)

To extend the TDM approach to **multiple users**, we need to account for a number of additional issues

Example: a typical cellular network



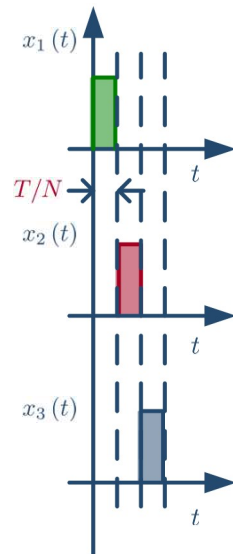
Time division multiple access (TDMA) (2/3)

- Users need to receive their own **time slot allocation**, assigned by the network through the **control plane**
- There is the need for **network synchronization** to align the users, which can be geographically sparse (and hence with different **propagation delays**)

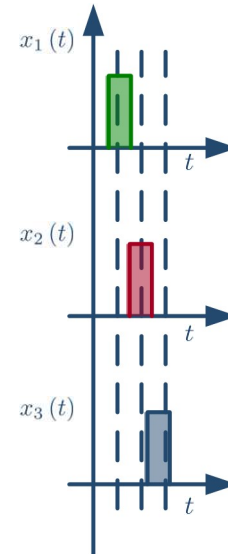


Time division multiple access (TDMA) (3/3)

Desired situation:



Actual situation:



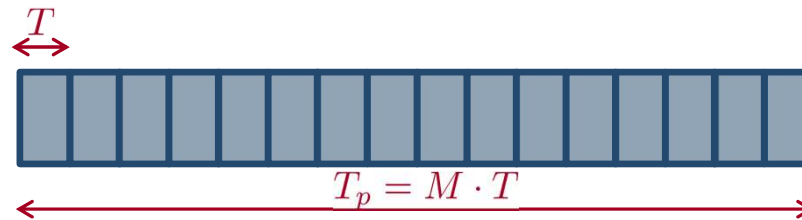
signals from different users overlap due to different propagation delays



Burst-based TDMA (1/2)

To simplify the synchronization tasks, time slots are grouped **per burst** instead of bit by bit

Each data burst is composed by a packet with duration $T_p = M \cdot T$, where M is the number of bits per packet

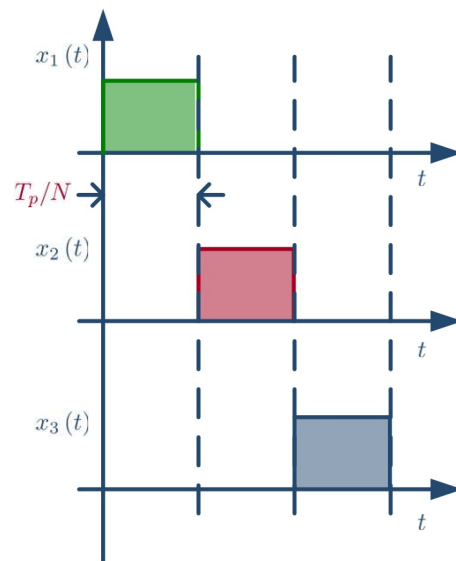


This approach allows the propagation times to be **compared** with T_p/N rather than with T/N (and hence there is a factor M)

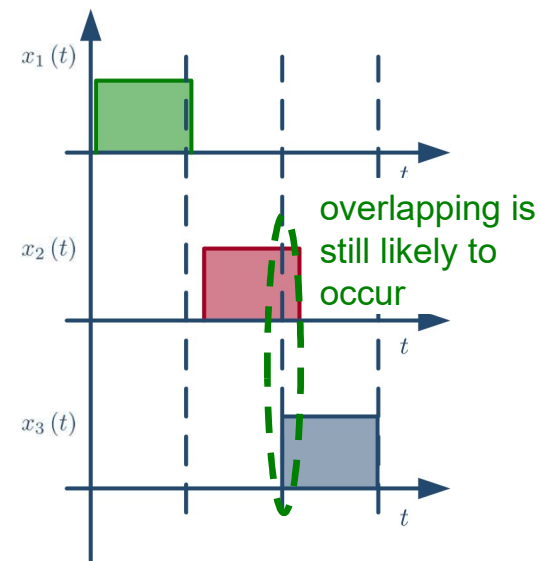
Burst-based TDMA (2/2)

The (**centralized**) network synchronization **feeds back** timing information to let the users anticipate or postpone transmissions

Desired situation:

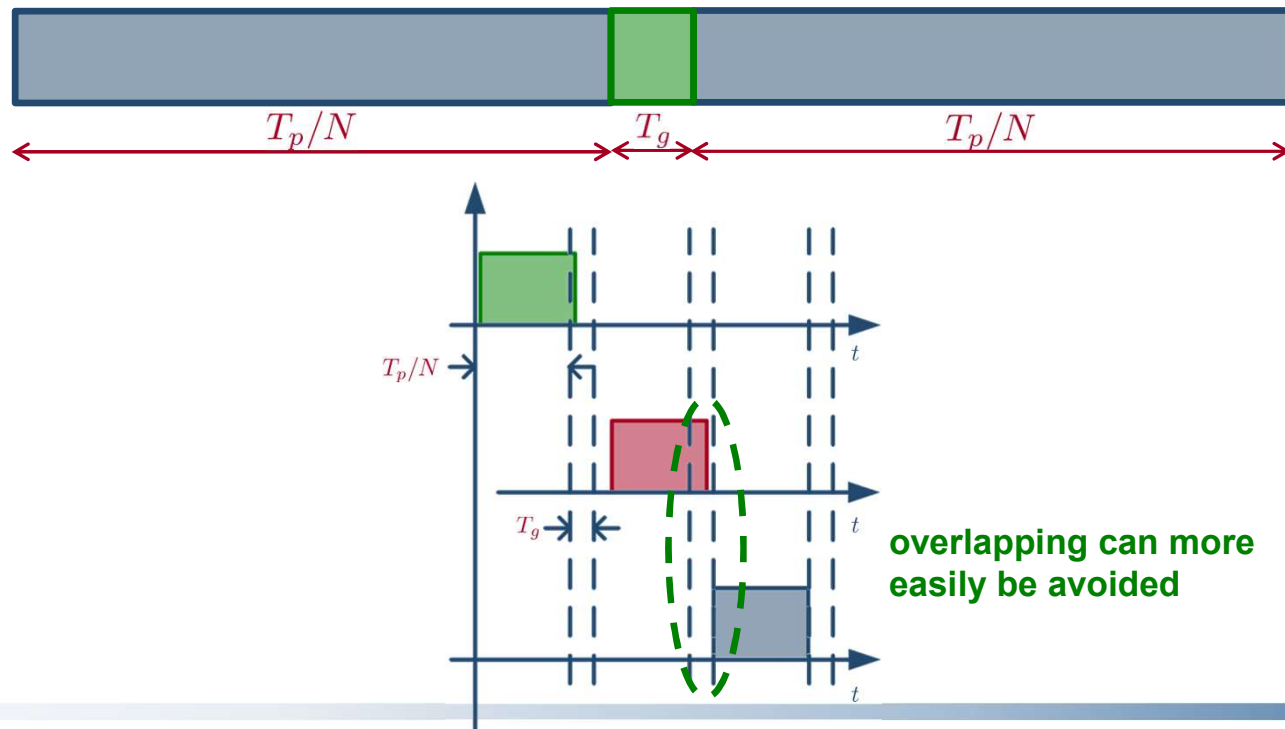


Actual situation:



Introducing a guard interval

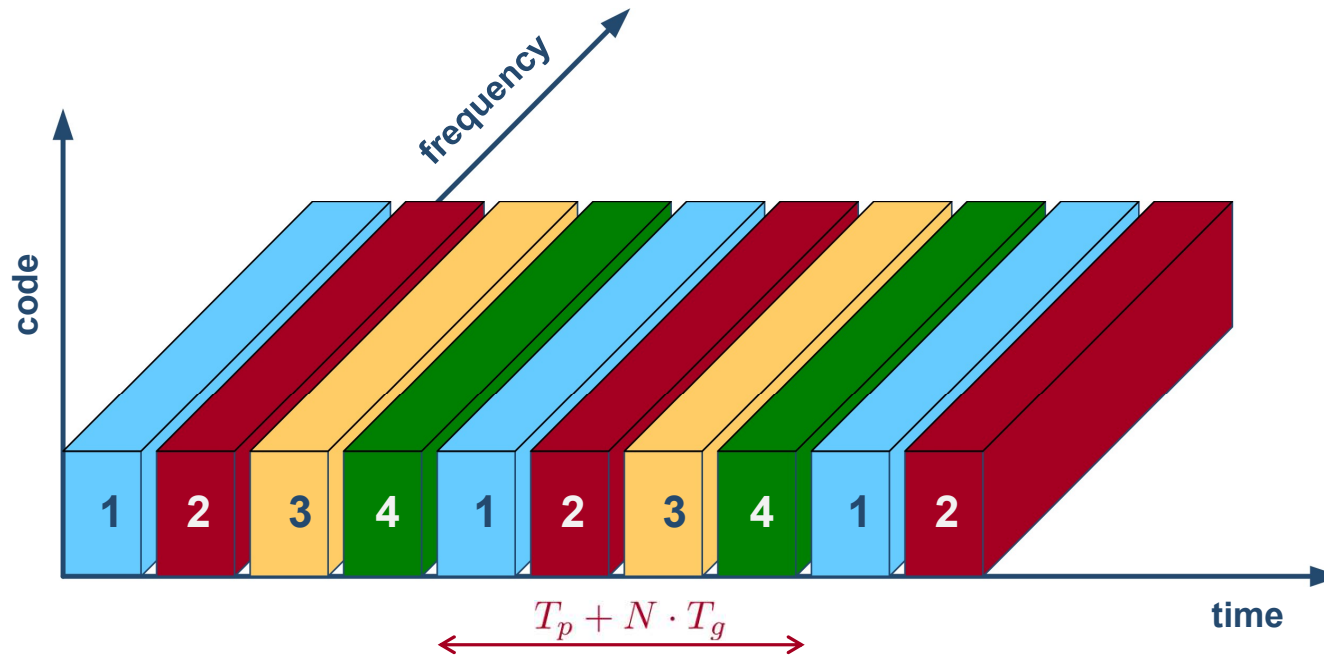
To relax the network synchronization requirements, we can introduce a **guard interval** T_g between each burst



overlapping can more easily be avoided

TDMA in 3D resource plan

The guard interval is a **tradeoff** between synchronization performance and optimal usage of network resources



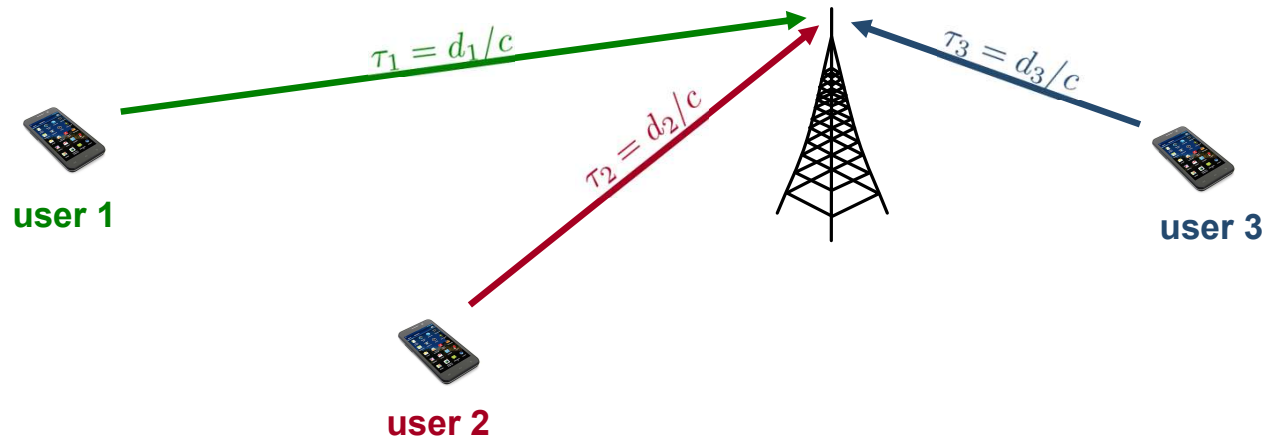
Code division multiple access (CDMA)



Code division multiple access (CDMA) (1/6)

The main difference between CDM and CDMA is due to **uncoordinated** times of arrival across the network users

Similarly to the TDMA scenario, different users experience **different** propagation delays:



Code division multiple access (CDMA) (2/6)

Let us evaluate the impact of **asynchronous** users on the aggregate signal measured at the receiver side:

$$x_{\text{MA}}(t) = \sum_{n=1}^N x_n(t - \tau_n) \cdot s_n(t - \tau_n)$$

For simplicity, let us focus on just two users and neglect the impact of AWGN and channel propagation on the output of the **matched-filter receiver** tailored for user #1 at sample $\ell = 0$:

$$\begin{aligned} a_1^{(0)} &= a_1(t)|_{t=\tau_1} \\ &= \frac{1}{T} \int_{\tau_1}^{T+\tau_1} x_{\text{MA}}(t) \cdot s_1^*(t - \tau_1) dt \end{aligned}$$

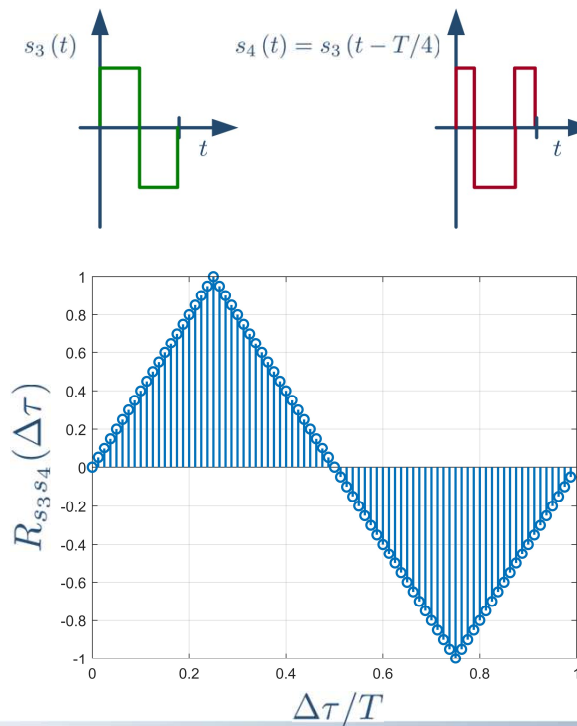
Code division multiple access (CDMA) (3/6)

$$\begin{aligned}
 a_1^{(0)} &= b_1^{(0)} + \frac{1}{T} \int_{\tau_1}^{T+\tau_1} b_2^{(0)} \cdot s_2(t - \tau_2) \cdot s_1^*(t - \tau_1) dt \\
 &= b_1^{(0)} + b_2^{(0)} \cdot \frac{1}{T} \int_0^T s_2(\alpha - \Delta\tau) \cdot s_1^*(\alpha) d\alpha \\
 &= b_1^{(0)} + R_{s_1 s_2}(\Delta\tau) \cdot b_2^{(0)}
 \end{aligned}$$

where $\Delta\tau \triangleq \tau_2 - \tau_1$ is the **interarrival time** between user #2 and user #1, and $R_{s_1 s_2}(\Delta\tau)$ is the **cross-correlation function** between codes $s_1(t)$ and $s_2(t)$, computed at time $\Delta\tau$

Code division multiple access (CDMA) (4/6)

When considering **orthogonal** codes (such as the WH code set), cross-correlation is negligible if and only if $\Delta\tau \ll T/N = T_c$



Code division multiple access (CDMA) (5/6)

This means that, in practice, the requirement is $\Delta\tau \leq T_c/10$

Example: in UMTS (3G), $T_c \approx 0.26 \mu\text{s}$, which implies $\Delta\tau \leq 26 \text{ ns}$

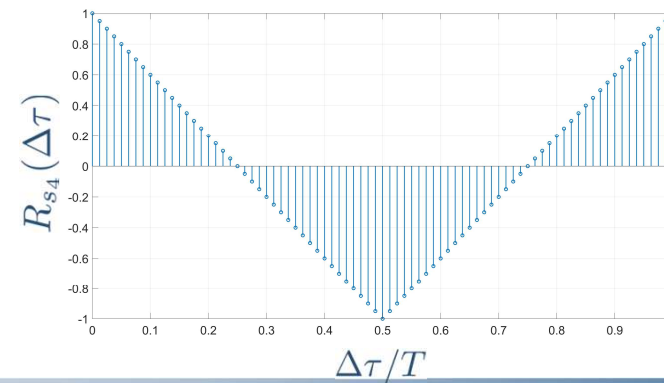
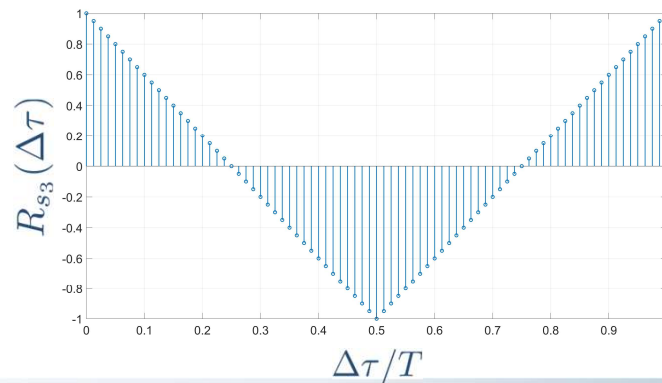
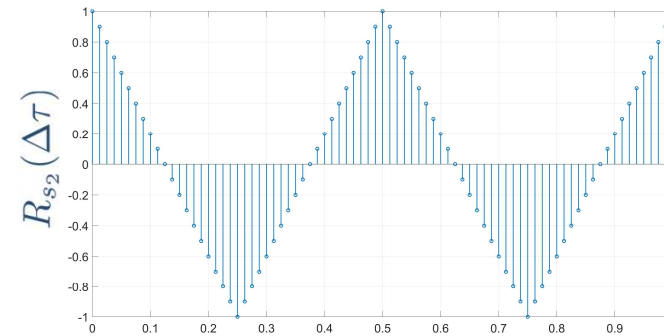
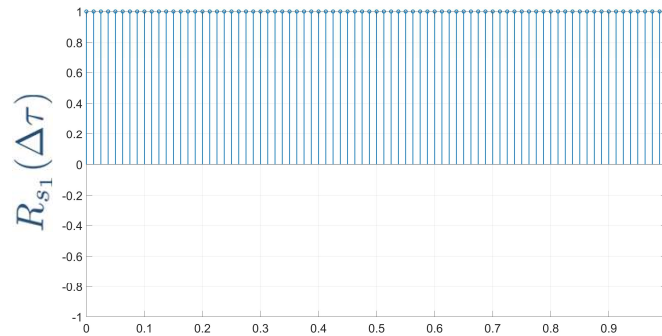
This accuracy is not **viable**, especially if compared with that required by TDMA, in which $\Delta\tau \leq T_g \approx T$ (typically, accuracy is two-three orders of magnitude higher in CDMA)



Code division multiple access (CDMA) (6/6)

Moreover, the estimation of τ_n relies on the properties of the **autocorrelation**

$$R_{s_n}(\Delta\tau) \triangleq \frac{1}{T} \int_0^T s_n(\alpha - \Delta\tau) \cdot s_n^*(\alpha) d\alpha$$



Non-orthogonal codes (1/4)

In this context, we need to identify signature codes that work pretty well in the **asynchronous** scenario

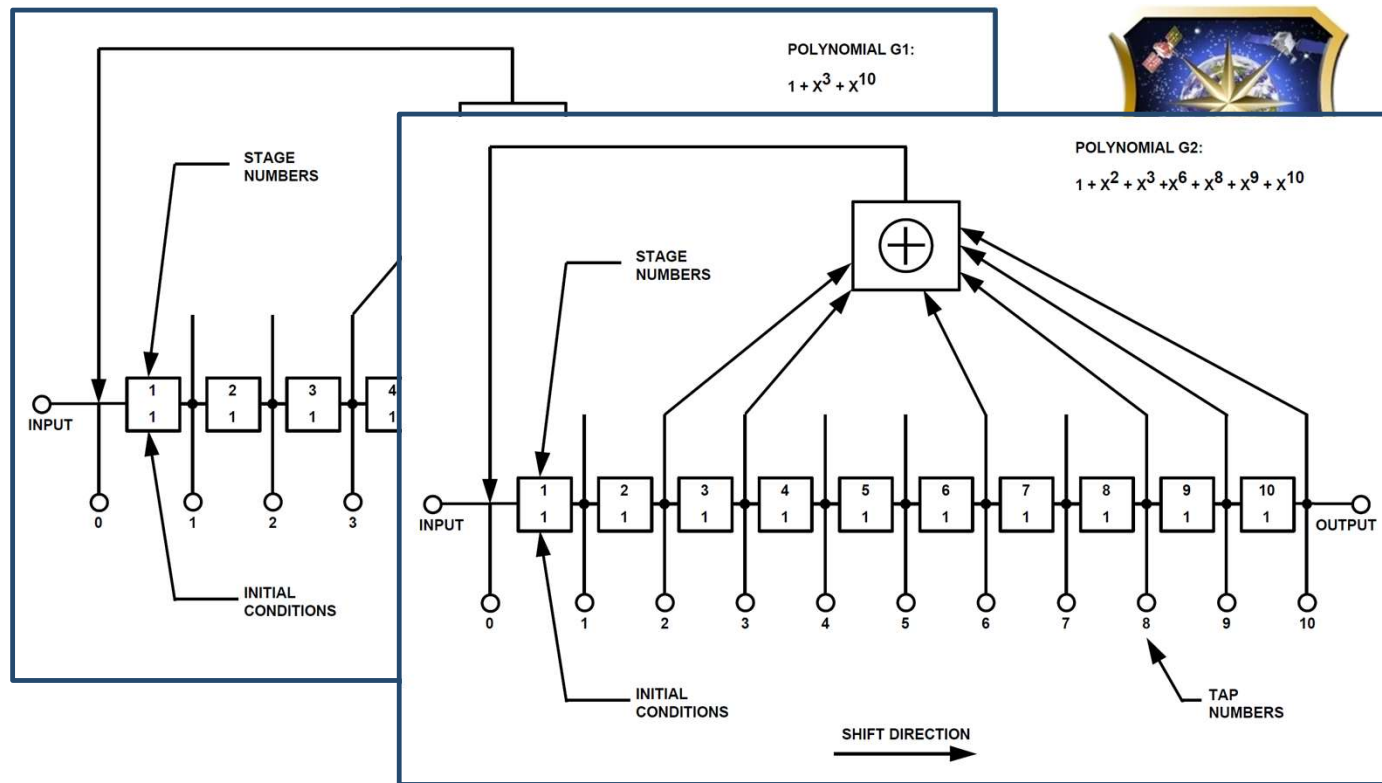
The class of **pseudo-random noise (PRN)** sequences, such as the **Gold codes** used in many systems, provide good performance in fully uncoordinated transmission patterns

PRN codes show **similarities** with the AWGN (e.g., the PSD is **almost flat** in the frequency domain), due to the pseudo-random nature of the chips; however, they are generated according to a well-defined **algorithm**, known to both transmit and receive sides



Non-orthogonal codes (2/4)

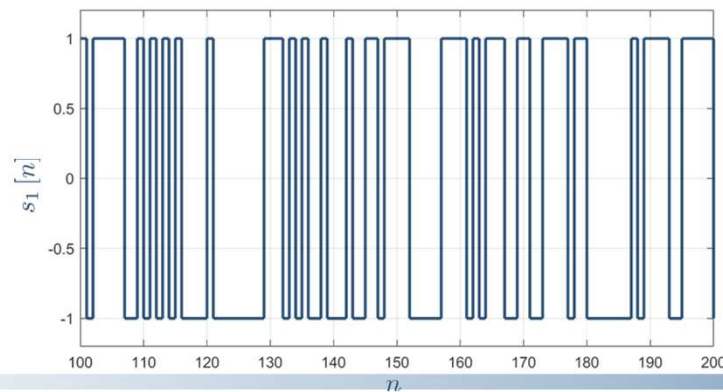
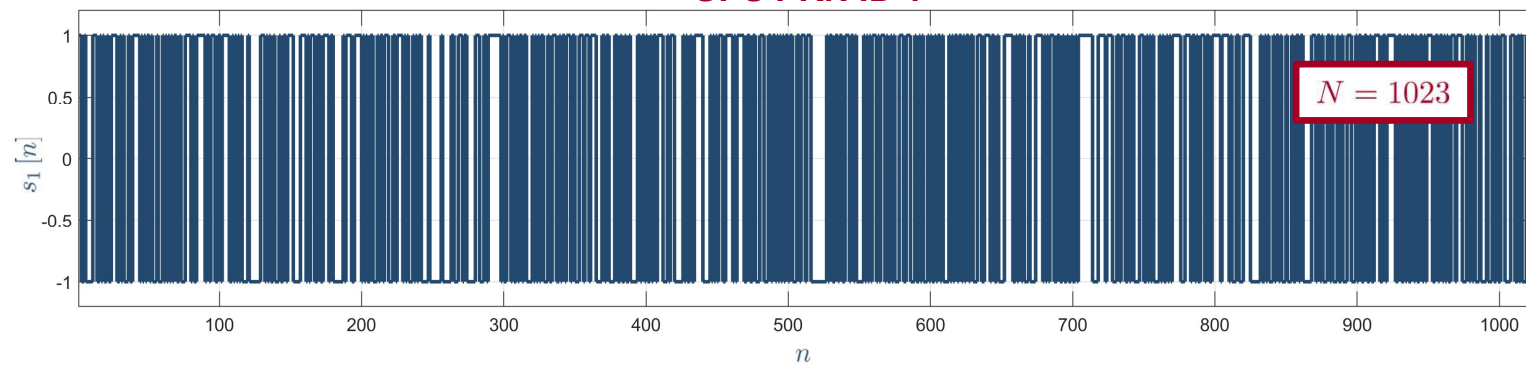
Example: PRN code generation in global positioning system (GPS)



Non-orthogonal codes (3/4)

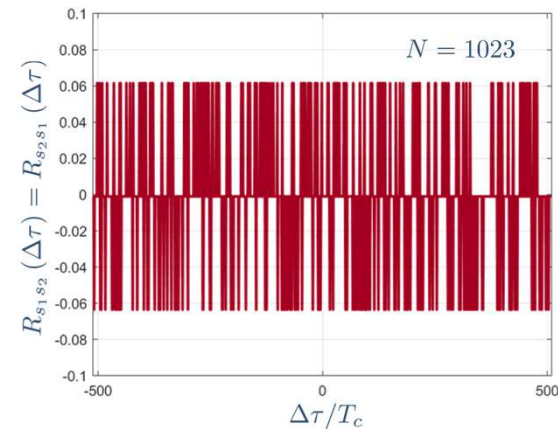
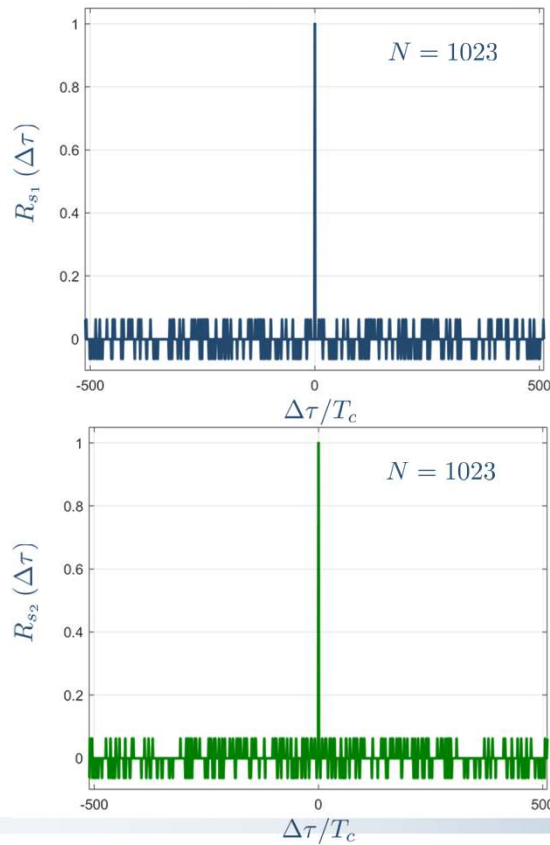
Example: PRN code generation in global positioning system (GPS)

GPS PRN ID 1



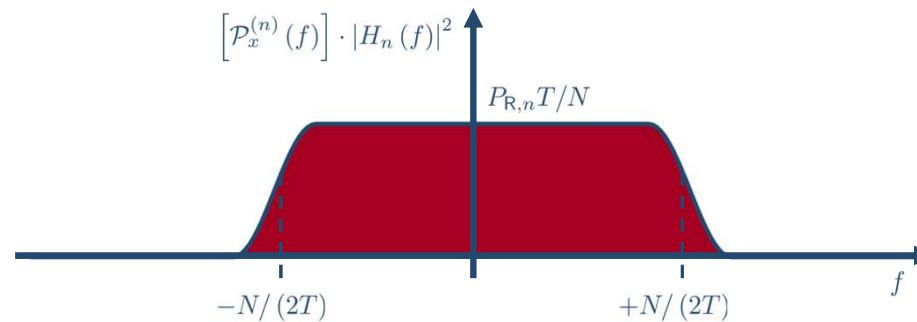
Non-orthogonal codes (4/4)

Example: PRN code generation in global positioning system (GPS)



Performance of CDMA (1/5)

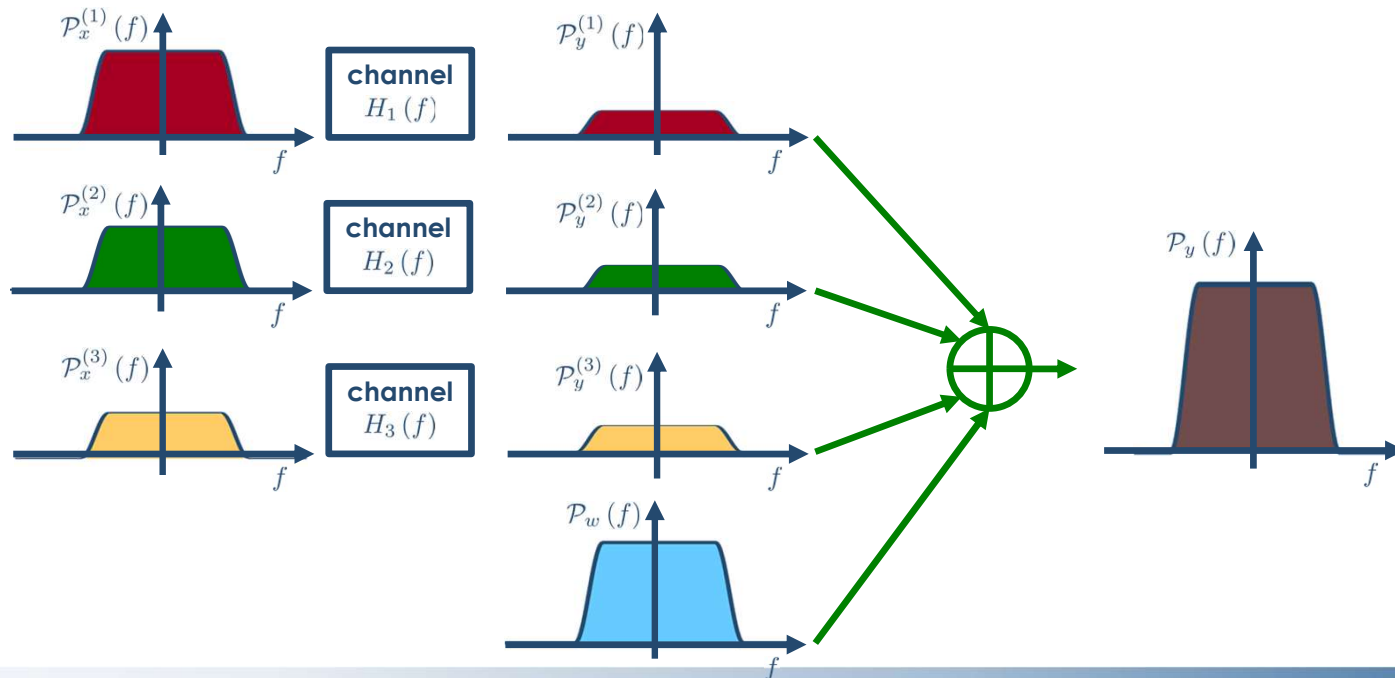
Thanks to the ad-hoc code chip generation, PRN codes show a **flat** PSD:



where $H_n(f)$ is the DFT of the channel experienced by user n , and $P_{R,n}$ is user n 's received power

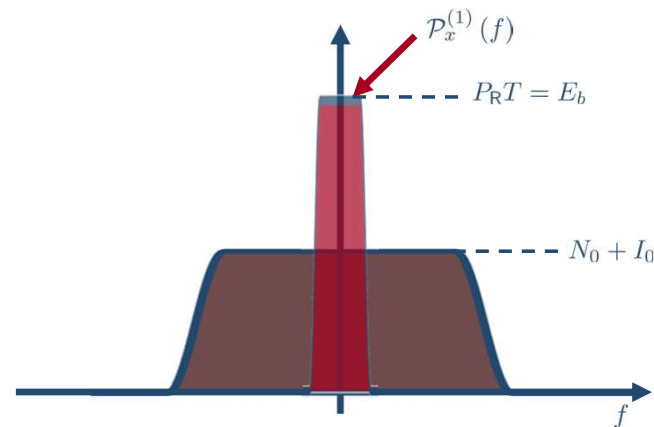
Performance of CDMA (2/5)

Hypothesis: our CDMA system adopts a closed-loop **power control** that equalizes all **received** powers $\{P_{R,n}\}_{n=1}^{N_A} = P_R$, where N_A is the number of users **simultaneously** active (note: $N_A \leq N$)



Performance of CDMA (3/5)

Decoding the n th user by applying the matched-filter approach is equivalent to extract **only** the desired spectrum out of the compound signal:



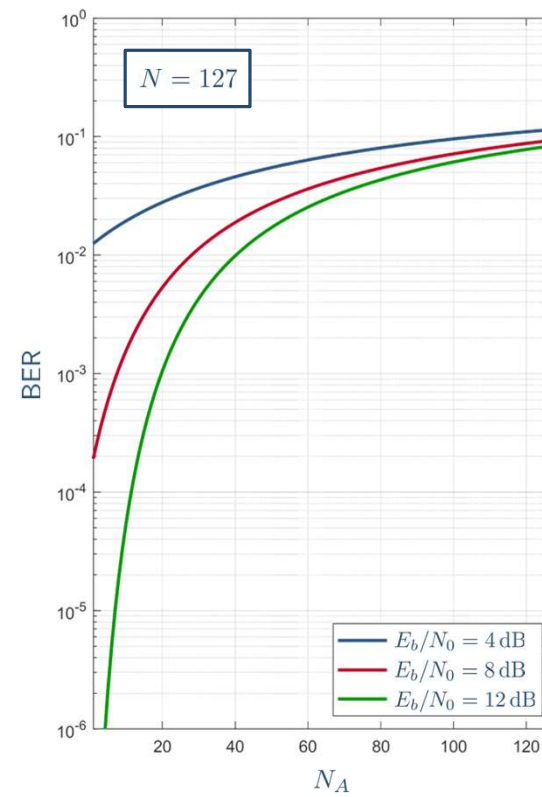
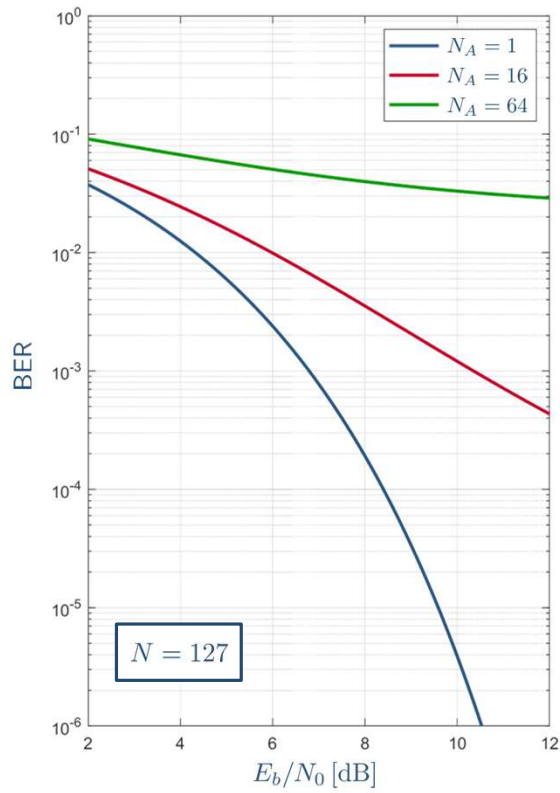
where the interference to the other users (the so-called **multiple access interference**, MAI) can be considered as a white Gaussian process as soon as $N_A \gg 1$ (say, $N_A \geq 10$)

$$a_1^{(\ell)} = b_1^{(\ell)} + \underbrace{\sum_{n=2}^{N_A} b_n^{(\ell)} \cdot R_{s_1 s_n}(\Delta\tau_n)}_{\text{multiple access interference (MAI)}} + z_1^{(\ell)}$$

When considering a **BPSK** or a **QPSK** constellation,

$$\begin{aligned} \text{BER} &= Q\left(\sqrt{\frac{2E_b}{N_0 + I_0}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0 + (N_A - 1) \cdot \frac{P_R}{N/T}}}\right) \\ &= Q\left(\sqrt{\frac{2E_b}{N_0}} \cdot \sqrt{\frac{1}{1 + \frac{N_A - 1}{N} \cdot \frac{E_b}{N_0}}}\right) \end{aligned}$$

Performance of CDMA (5/5)



Differences wrt TDMA and FDMA

Non-orthogonality of the signature codes significantly **degrades** the performance of the network

However, CDMA allows users to access the network in a **truly random** manner, without the need for synchronization across the users

This places CDMA closer to **statistical-based** multiple-access techniques, such as packet-oriented ones



Packet-oriented multiple access



What is packet-oriented multiple access? (1/2)

Connection-oriented multiple access:

- **coordinated access**, such as in TDMA, FDMA, and, to some extent, CDMA
- **deterministic approach**, well suited for constant-bitrate communications

Packet-oriented multiple access:

- **uncoordinated access**
- **statistical approach**, well suited for bursty-traffic communications



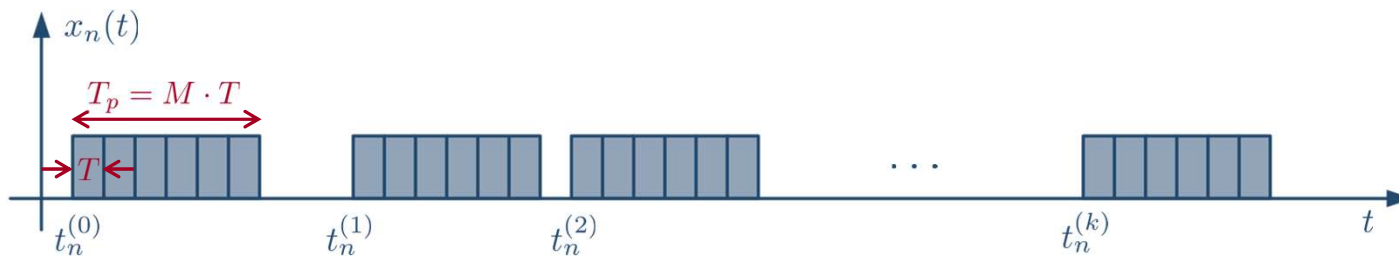
What is packet-oriented multiple access? (2/2)

Typical example of bursty/impulsive traffic: the **IoT scenario**



Packet-based MA: System model (1/4)

Let us suppose to have N active users, sending packets with constant duration T_p at random instants $\{t_n^{(k)}\}_{k=0}^{+\infty}$, using a fixed **packet rate** μ (measured in packets/second)



$$\text{average bitrate } \bar{R}_b = M \cdot \mu \text{ [b/s]}$$

Packet-based MA: System model (2/4)

To properly investigate this packet-based scheme, we need to characterize the **interarrival times**

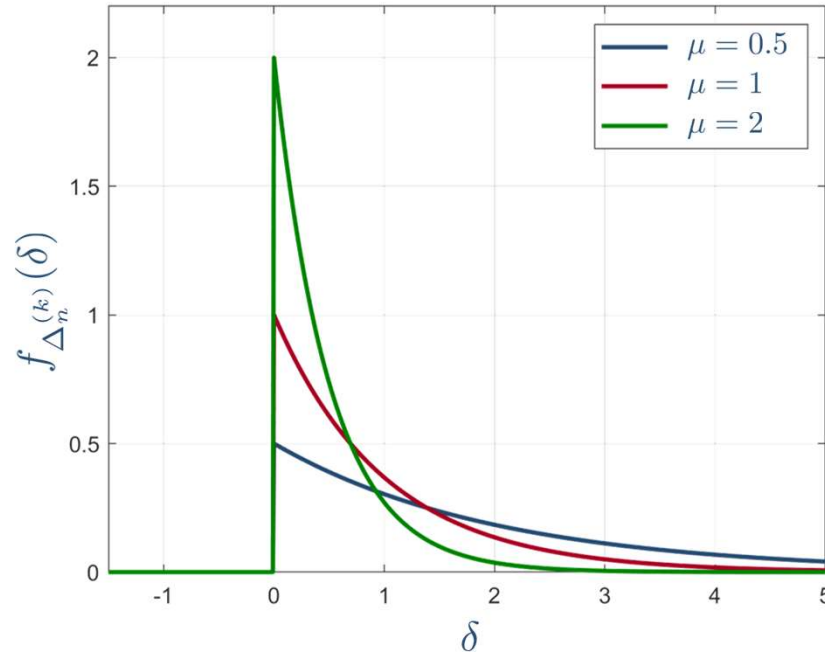
$$\Delta_n^{(k)} \triangleq t_n^{(k)} - t_n^{(k-1)}$$

A customary assumption in practical bursty systems is that interarrival times are **independent and exponentially distributed**

$$f_{\Delta_n^{(k)}}(\delta) = \mu e^{-\mu\delta} \cdot u(\delta)$$



Packet-based MA: System model (3/4)

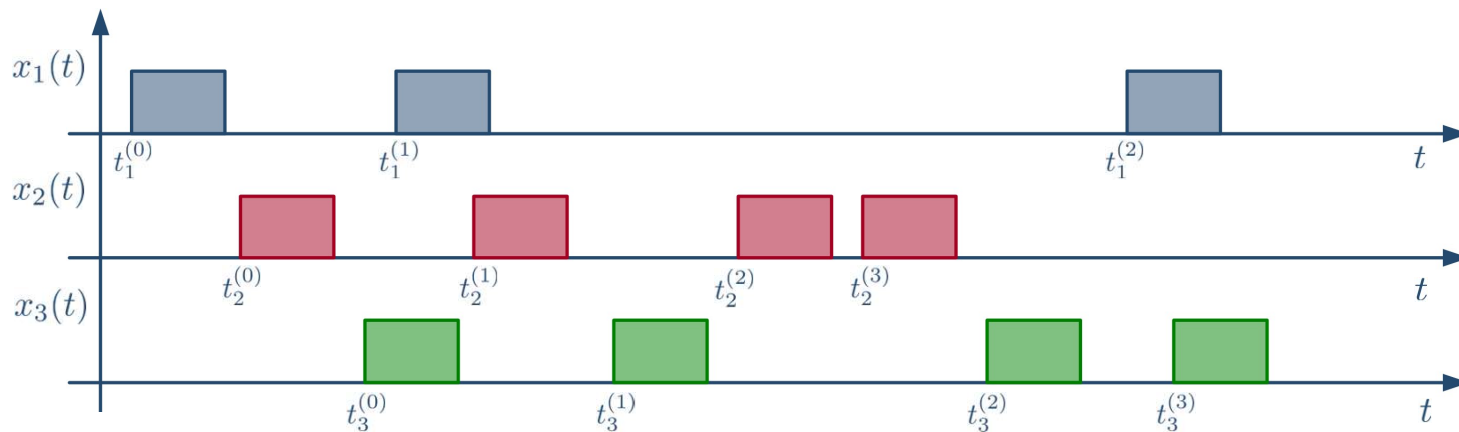


$\left\{ \Delta_n^{(k)} \right\}_{k=0}^{+\infty}$ is a Poisson process with intensity μ



Packet-based MA: System model (4/4)

How can we exploit this to model the N users?



The aggregate system can be seen as a **unique packet source**, with packet rate $N\mu$ and average interarrival time $1/(N\mu)$

The ALOHA protocol and its variants



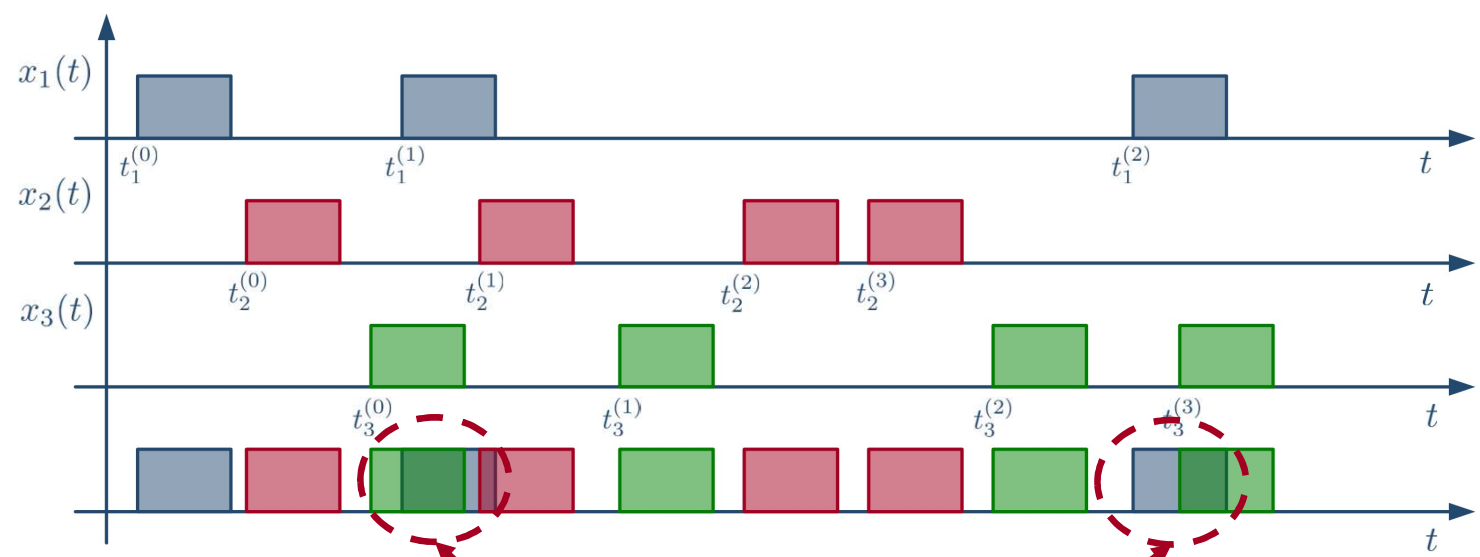
The ALOHA protocol (1/3)

Historically, the first protocol to address this issue was the ALOHAnet, or simply **ALOHA**, devised in the early 1970s

The main goal was to connect the research centers at the University of Hawaii, spread across the Hawaiian islands, with the main Oahu campus



The ALOHA protocol (2/3)



collisions due to the superposition (in the time domain) of packets from different users



The ALOHA protocol (3/3)

Unlike connection-oriented multiple-access scheme, the ALOHA protocol needs a **return channel**, to receive feedback from the receiver (using **acknowledgment** of correct reception)

In case of a missing acknowledgement (corresponding to an event of collision), the **re-transmission** follows a specific backoff time (based on a statistical approach – out of scope in this lecture)

Performance of ALOHA (1/5)

Intuitively, if the packet rate μ is too high, there will be a **large** number of collisions (and hence of re-transmissions), which **limit** the efficiency of the system

To measure this tradeoff, let us compute the **efficiency** as

$$\rho = \frac{\text{bitrate successfully delivered}}{\text{used bandwidth}}$$



Performance of ALOHA (2/5)

Used bandwidth: $B = \frac{1}{T}$

Bitrate successfully delivered: nominal bitrate $1/T$ times the average number of packets successfully received without a collision

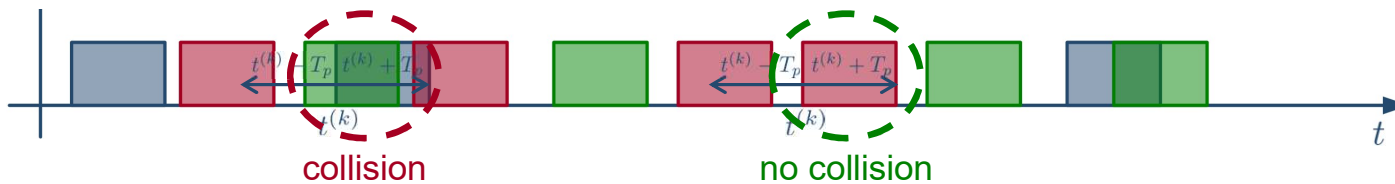
The latter depends on the average number of transmitted packets, and the probability of no collision across packets

Average number of transmitted packets: $N\mu \cdot T_p \triangleq G$



Performance of ALOHA (3/5)

Collisions can be avoided if $t^{(k-1)} + T_p \leq t^{(k)} \leq t^{(k+1)} - T_p$



$$\begin{aligned}
 P_s &= \Pr \{ \text{no collisions across packets} \} \\
 &= \Pr \left\{ t^{(k-1)} - T_p \leq t^{(k)} \leq t^{(k+1)} + T_p \right\} \\
 &= \Pr \{ \Delta \geq 2T_p \}
 \end{aligned}$$

Performance of ALOHA (4/5)

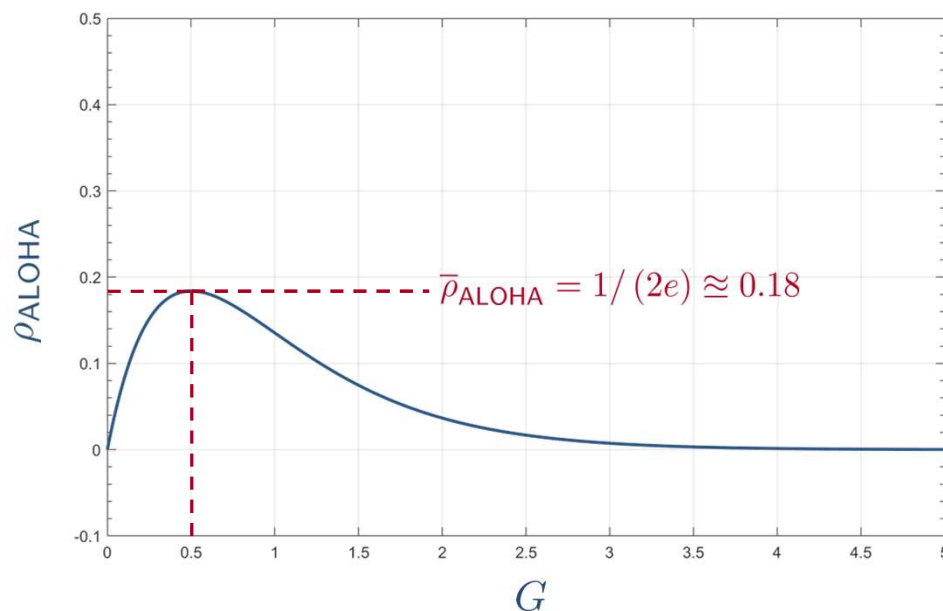
Exercise: Show that $P_s = e^{-2G}$



Performance of ALOHA (5/5)

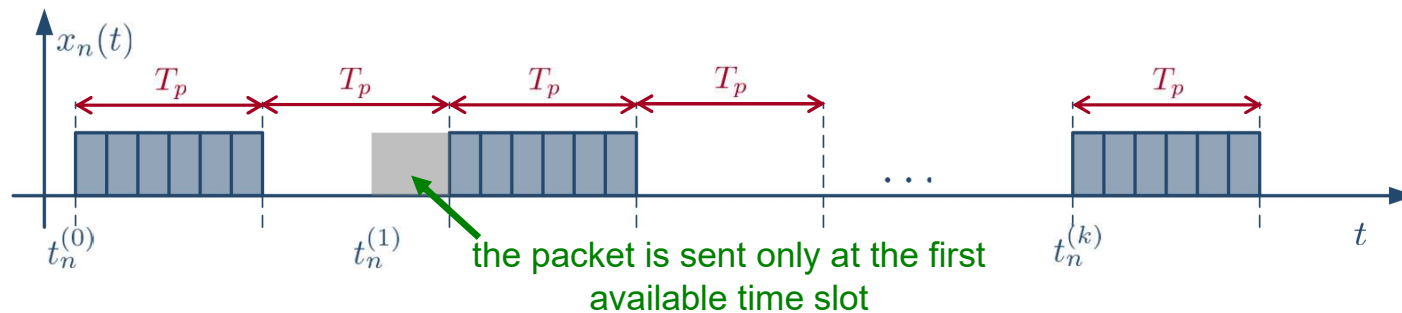
By collecting all pieces together, we get:

$$\rho_{\text{ALOHA}} = \frac{1/T \cdot G \cdot P_s}{1/T} = G \cdot e^{-2G}$$



The slotted-ALOHA (S-ALOHA) protocol (1/3)

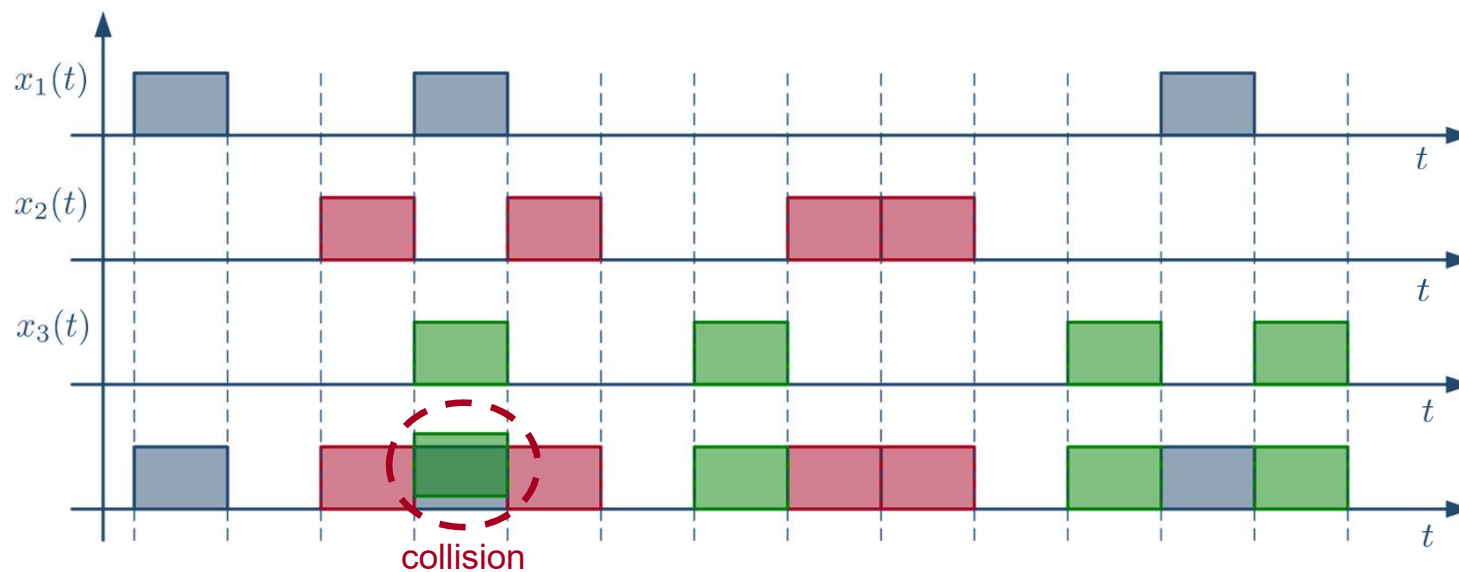
To reduce the occurrence of collision events, we can apply a centralized **network synchronization** similar to TDMA:



This modified version of ALOHA is called **slotted ALOHA (S-ALOHA)**

The slotted-ALOHA (S-ALOHA) protocol (2/3)

Collisions occur only when **more than one** source selects the same time slot to transmit the packet (i.e., partial collisions do not exist anymore)



The slotted-ALOHA (S-ALOHA) protocol (3/3)

When considering **time slotting**, the probability of no collision across packets becomes

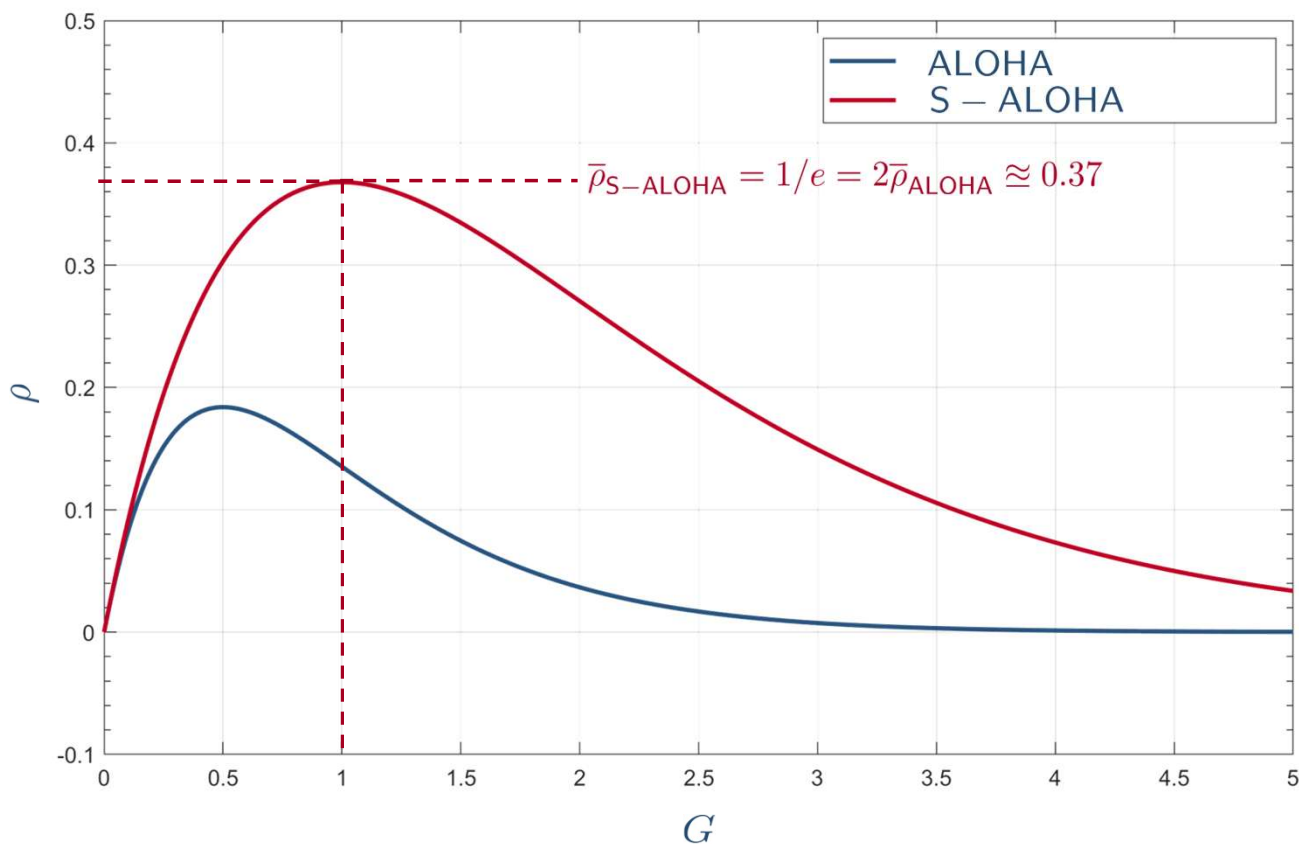
$$\begin{aligned} P_s &= \Pr \{ \Delta \geq T_p \} \\ &= \int_{T_p}^{+\infty} N\mu \cdot e^{-N\mu\delta} d\delta \\ &= e^{-G} \end{aligned}$$

Hence, we get:

$$\rho_{S\text{-ALOHA}} = G \cdot e^{-G}$$



ALOHA vs. S-ALOHA



Efficiency comparison across multiplexing and multiple access techniques



Efficiency of deterministic-based approaches

It is now interesting to **compare** the packet-oriented and the connection-oriented approaches in terms of efficiency, using the definition introduced above:

$$\rho = \frac{\text{bitrate successfully delivered}}{\text{used bandwidth}}$$



Efficiency of multiplexing techniques

When considering frequency / time / code division multiplexing:

- **used bandwidth:** $B = N/T$
- **bitrate successfully delivered:** $R_b = N \cdot 1/T = N/T$

As a consequence,

$$\rho_{\text{FDM}} = \rho_{\text{TDM}} = \rho_{\text{CDM}} = 1$$

To sum up: multiplexing has unitary efficiency, thanks to its **orthogonality**



Efficiency of FDMA

When dealing with FDMA, we need to account for the **guard bandwidth** B_g :

- **used bandwidth:** $B = N \cdot [(1 + \beta) / T + B_g]$
- **bitrate successfully delivered:** $R_b = N \cdot 1/T = N/T$

As a consequence,

$$\rho_{\text{FDMA}} = \frac{N/T}{N \cdot [(1 + \beta) / T + B_g]} = \frac{1}{1 + \beta + B_g T}$$

Example: with $\beta = 0.2$ and $B_g = 0.1/T$, we get $\rho_{\text{FDMA}} \approx 0.77$

Efficiency of TDMA

Similarly, when dealing with TDMA, efficiency is reduced by the **guard interval** T_g :

- **used bandwidth:** $B = N/T$
- **bitrate successfully delivered:** $R_b = \frac{N}{T} \cdot \frac{T_p/N}{T_p/N + T_g}$

This implies that

$$\rho_{\text{TDMA}} = \frac{N/T \cdot (MT/N)}{N/T \cdot (MT/N + T_g)} = \frac{1}{1 + NT_g/(MT)}$$

Example: with $T_g = 8.25T/N$ and $M = 148$ (GSM), we get $\rho_{\text{TDMA}} \approx 0.95$



Efficiency of CDMA (1/3)

With CDMA, the efficiency can be measured as follows:

- **used bandwidth:** $B = N/T$
- **bitrate successfully delivered:** $R_b = N_A \cdot 1/T$

which implies

$$\rho_{\text{CDMA}} = \frac{N_A}{N}$$

However, deriving the number of simultaneously active users N_A is **not straightforward**, as it depends on the desired **quality of service** (QoS), which impacts the selected SNR E_b/N_0



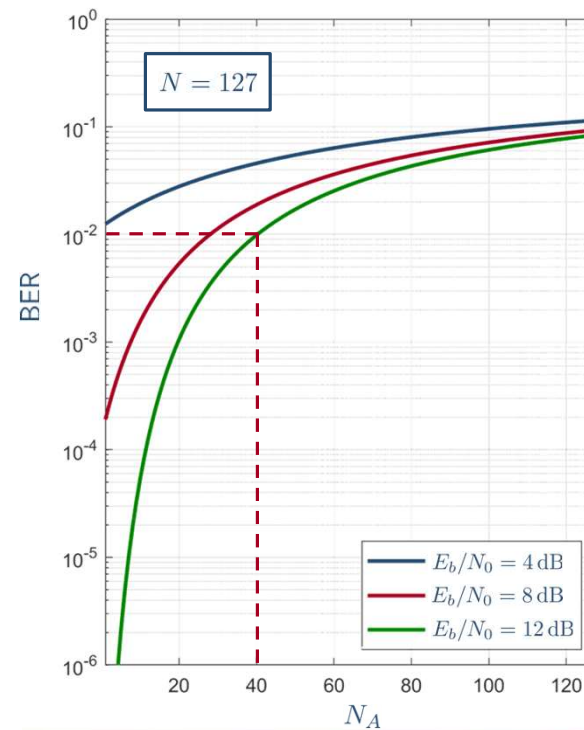
Efficiency of CDMA (2/3)

Example: $E_b/N_0 = 12$ dB, that yields $\text{BER} < 10^{-7}$ in the single-user case

Target BER in the multi-user case (voice applications):

$$\text{BER} = 10^{-2}$$

$$\rho_{\text{CDMA}} = \frac{N_A}{N} = \frac{40}{127} \approx 0.31$$



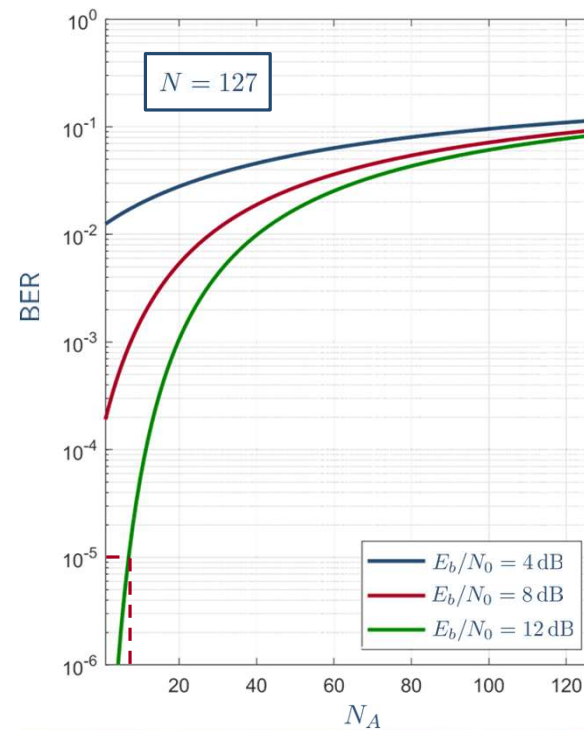
Efficiency of CDMA (3/3)

Example: $E_b/N_0 = 12$ dB, that yields $\text{BER} < 10^{-7}$ in the single-user case

Target BER in the multi-user case (video applications):

$$\text{BER} = 10^{-5}$$

$$\rho_{\text{CDMA}} = \frac{N_A}{N} = \frac{7}{127} \approx 0.06$$



Efficiency of coded CDMA (1/3)

The impact of MAI is a **very limiting factor** for the efficiency of a CDMA-based system

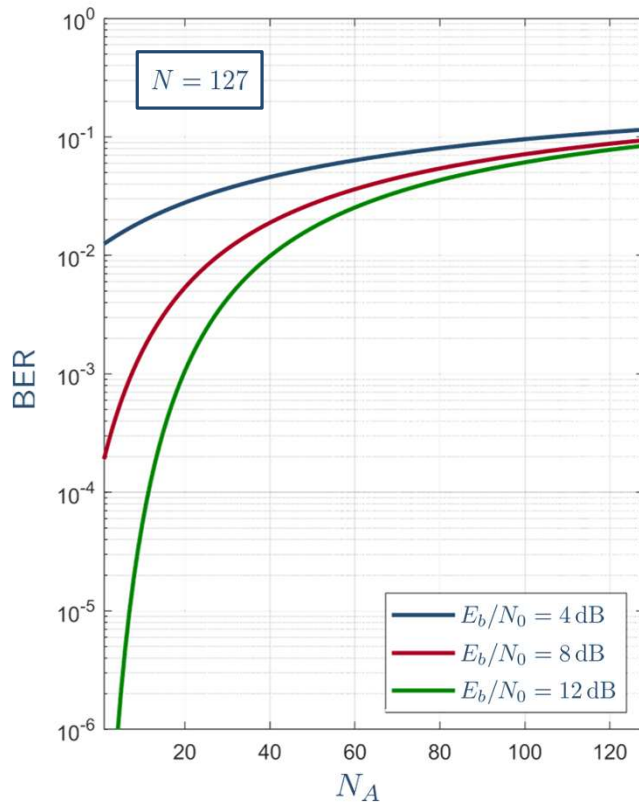
We can improve the efficiency performance by adopting **channel coding** techniques

Example: low-density parity check (LDPC) code with rate $1/2$, keeping the chip time equal to the uncoded case (and hence the used bandwidth)

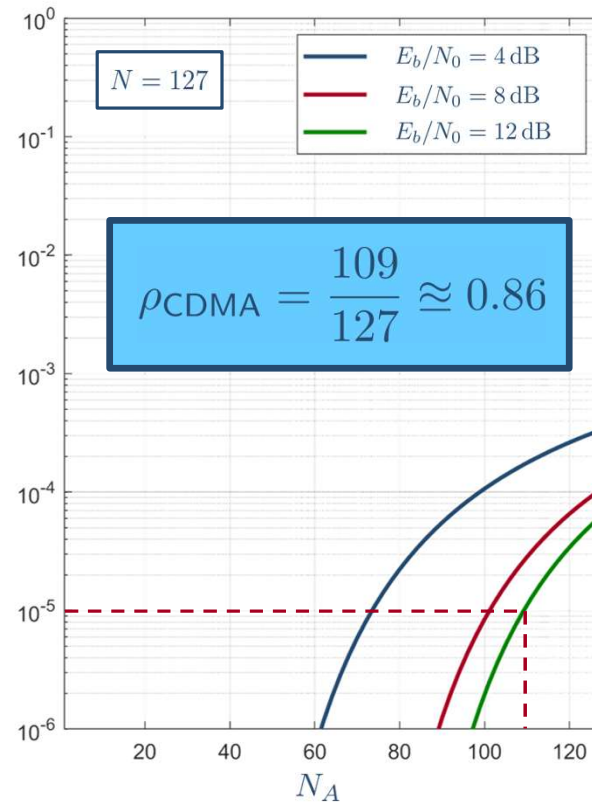


Efficiency of coded CDMA (2/3)

uncoded case



coded case



Efficiency of coded CDMA (3/3)

With channel coding, with CDMA we can attain efficiencies in the **same order** as TDMA and FDMA (i.e., systems with orthogonal multiple access) (by relaxing the QoS requirements, even $\rho_{\text{CDMA}} > 1$ are possible!)

Please note that using channel coding with TDMA and FDMA does **not** further improve the efficiency, yet increasing the energy efficiency of the system given a certain QoS

Channel coding can also be applied to packet-based multiple access schemes, thus originating **additional variants** to the ALOHA protocol (e.g., spread-spectrum ALOHA)



History of wireless communications



A brief history of wireless communications (1/3)

- **1864:** Maxwell proves the existence of electromagnetic waves
- **1887:** Hertz sends and receives wireless waves, using a spark transmitter and a resonator receiver
- **1895:** Guglielmo Marconi sends a radio signal over more than a mile, from the Isle of Wight to a tugboat 18 miles away
- **1904:** Fleming patents the diode
- **1906:** DeForest patents the triode amplifier; first speech wireless transmission, by Fessenden
- **WW I:** Rapid development of communications intelligence, intercept technology, cryptography
- **1920:** Marconi discovers short-wave radio, with wavelengths between 10 and 100 meters
- **1935:** Armstrong invents the frequency modulation (FM)



A brief history of wireless communications (2/3)

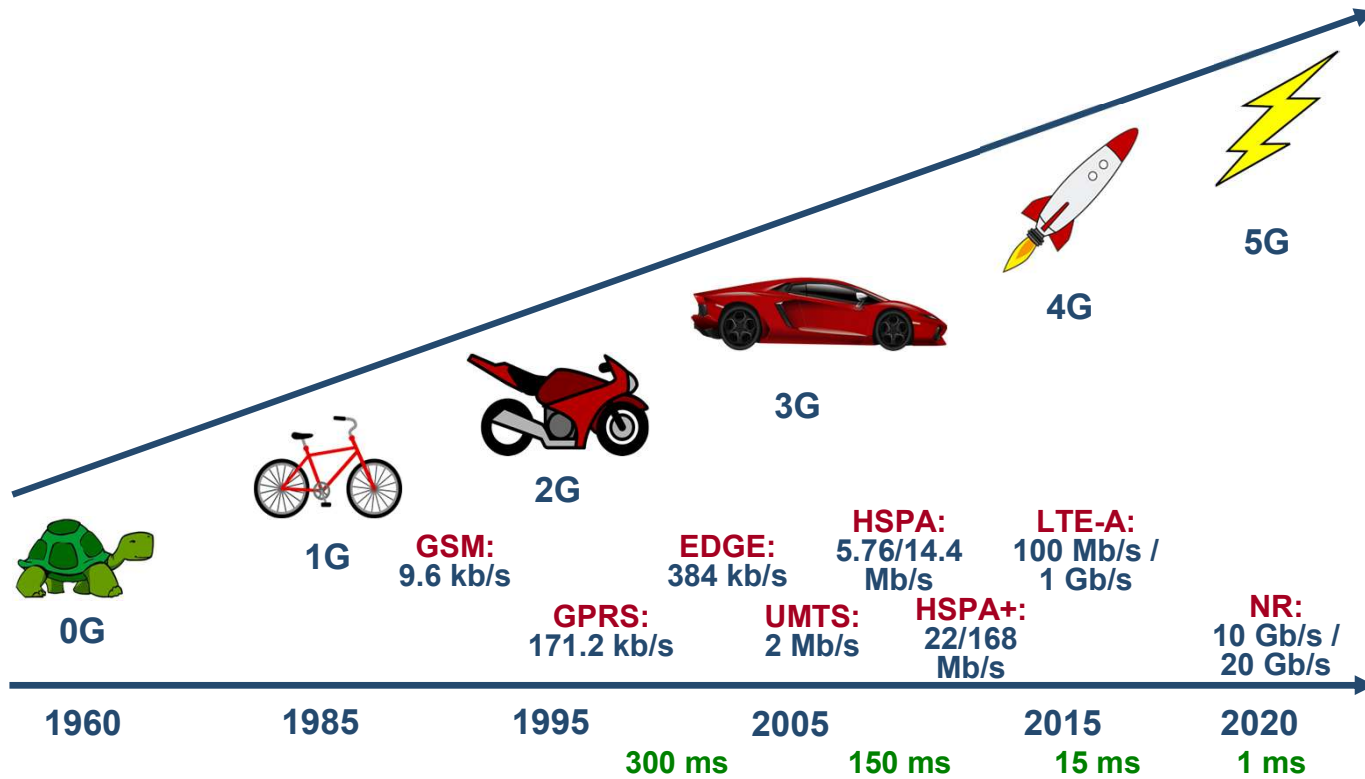
Mobile wireless systems ensure the **communications** between **mobile** nodes



In the last ninety years, wireless technology has **evolved** over many aspects:

- **increased coverage distance**
- **increased quality (throughput, error rate performance, spectral efficiency)**
- **improved availability of services (broadband communications)**
- **decreased energy consumption (energy efficiency)**
- **reduced costs (for both service providers and subscribers/users)**
- **reduced device sizes and costs**

A brief history of wireless communications (3/3)

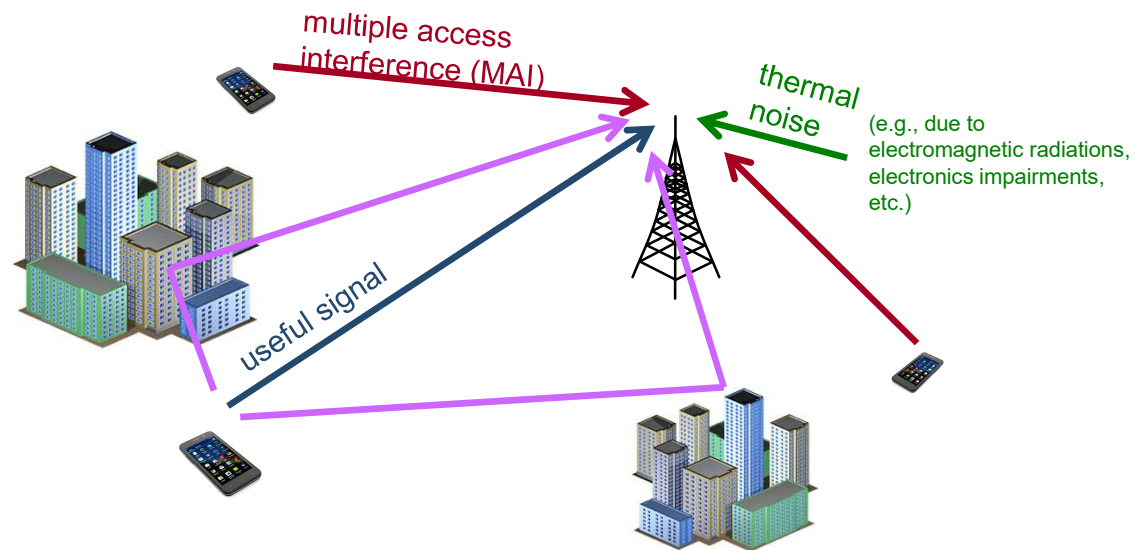


Basics of wireless propagation



The wireless propagation channel

Received contributions at the receiver (uplink):



The wireless channel between the transmitter and the receiver fluctuates **randomly** for a number of causes

Free-space propagation

If we consider the air as a perfectly uniform medium, the received power can be expressed as

$$P_R(d) = \frac{P_T}{L(d)}$$

where

$$L(d) = \frac{1}{G_T G_R} \left(\frac{4\pi d}{\lambda} \right)^2$$

gain of the transmit antenna
gain of the receive antenna
tx-rx distance
carrier wavelength

However, this model is **not** accurate to describe the wireless channel experienced by cellular-communication signals

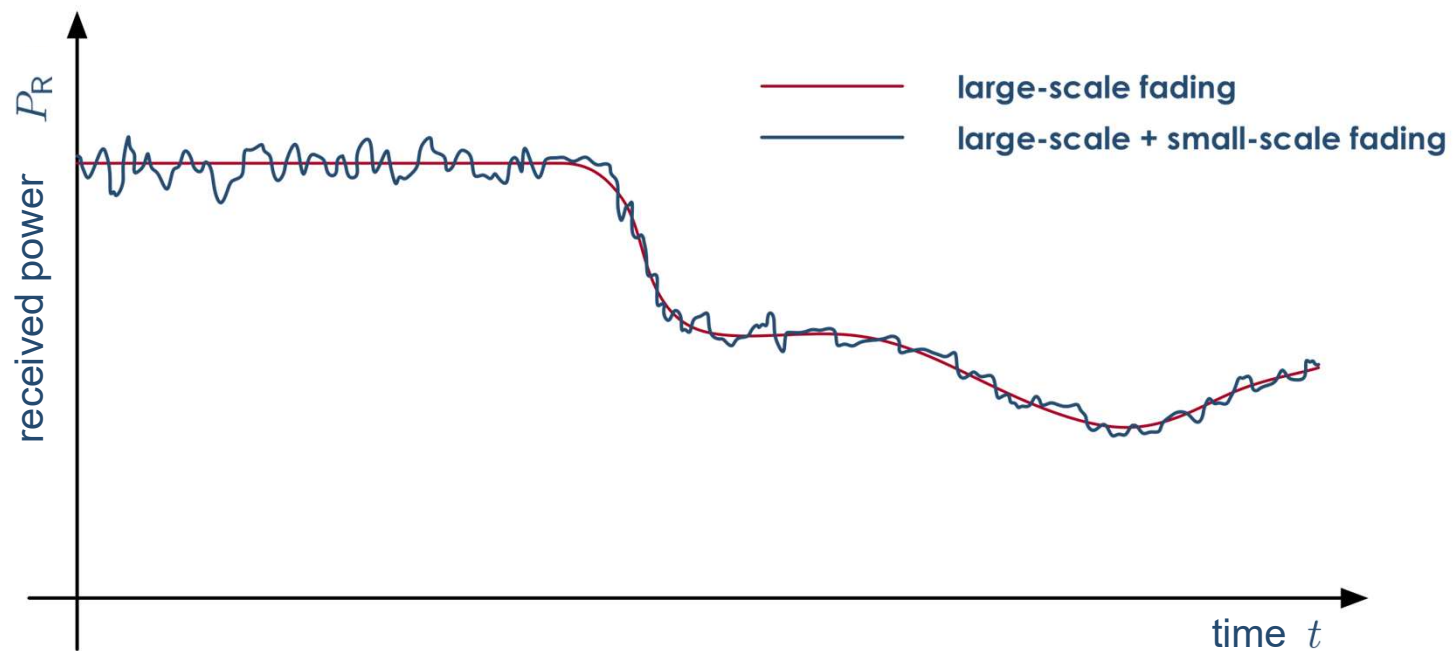
Large- and small-scale models (1/2)

A better suited propagation model is composed by:

- **large-scale models**, that predict the average energy received in a wireless system as a function of the distance between the transmitter and the receiver
- **small-scale models**, that account for the instantaneous variations in the propagation conditions



Large- and small-scale models (2/2)

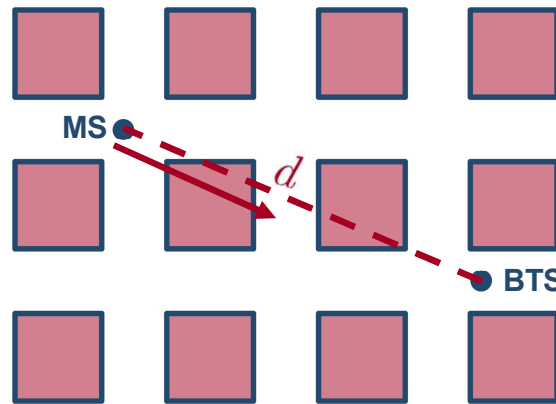


Large scale fading



Large-scale fading models (1/3)

Average received power as a function of the MS-BTS distance d



Using the Hata and Okumura models,

$$\bar{P}_R(d) = \begin{cases} P_T/L(d) = \chi' \cdot P_T/d^2, & \text{for } d \leq d_0 \\ \chi \cdot P_T/d^n = \chi' \cdot P_T \cdot d_0^{n-2}/d^n, & \text{for } d \geq d_0 \end{cases}$$

reference distance

Large-scale fading models (2/3)

Average received power as a function of the MS-BTS distance d

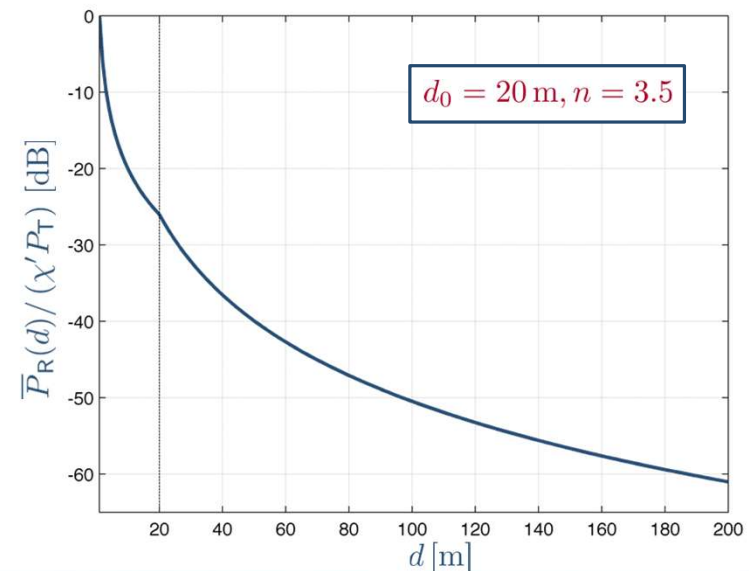
$$\bar{P}_R(d) = \begin{cases} P_T/L(d) = \chi' \cdot P_T/d^2, & \text{for } d \leq d_0 \\ \chi \cdot P_T/d^n = \chi' \cdot P_T \cdot d_0^{n-2}/d^n, & \text{for } d \geq d_0 \end{cases}$$

$$\chi' = G_T G_R \left(\frac{\lambda}{4\pi} \right)^2$$

$$\chi = \chi' \cdot d_0^{n-2} = G_T G_R \left(\frac{\lambda}{4\pi} \right)^2 d_0^{n-2}$$

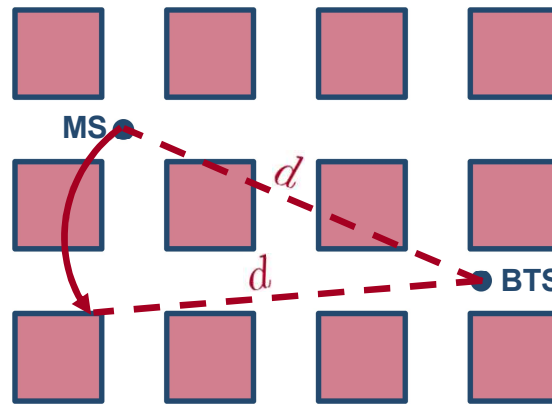
$$d_0 = \begin{cases} 20 \div 100 \text{ m}, & \text{urban scenarios} \\ 0.5 \div 1 \text{ km}, & \text{rural areas} \end{cases}$$

$$n = \begin{cases} 2, & \text{free space} \\ 2.7 \div 3.5 & \text{urban scenarios} \\ 4 \div 5 & \text{indoor} \end{cases}$$



Large-scale fading models (3/3)

Average received power as a function of a constant distance d



$$P_R(d) = 10^{\nu(d)/10}$$

where

$$\nu(d) \sim \mathcal{N}(\bar{\nu}(d), \sigma_\nu^2)$$

dependent on the propagation scenario

given by the Hata-Okumura model:
 $\bar{\nu}(d) = 10 \log_{10} \bar{P}_R(d)$

Small scale fading



Small-scale fading

The propagation laws can be computed using the **Maxwell equations**. However, this approach is not useful, due to:

- a **large** computational complexity, but also
- the need for a valid model for **different** propagation conditions, also considering the **time variability**



We need to identify a practical method to account for the **macroscopic** phenomena of wireless propagation

Wavelengths and frequencies in wireless systems (1/2)

Wireless radio spectrum:



Carrier wavelengths:

$$\lambda = \frac{c}{f_0} = 1 \text{ cm} \div 1 \text{ m}$$

speed of light, $3 \cdot 10^8 \text{ m/s}$

carrier frequency

Wavelengths and frequencies in wireless systems (2/2)

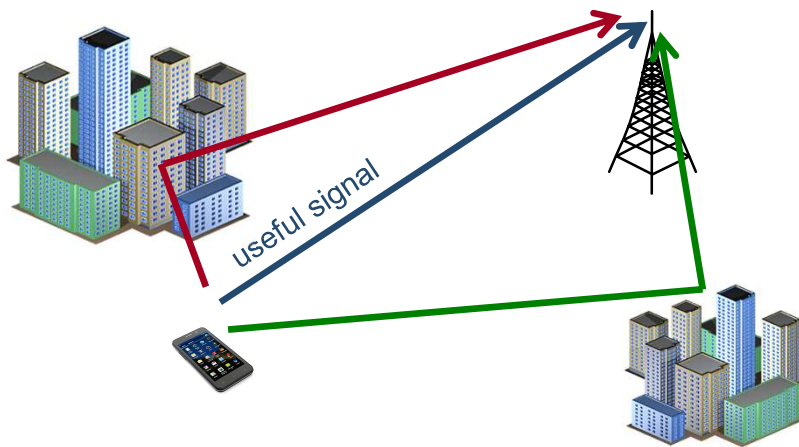
Why are such frequencies particularly **attractive**?

- larger f_0 's yield **larger** path losses: $L(d) \propto \frac{1}{\lambda^n}$
- smaller f_0 's call for **larger** antennas (with size comparable with λ)
- smaller f_0 's show favorable conditions for over-the-horizon (OTH) propagation, thus **reducing** the potential for frequency reuse
- such f_0 's can accommodate **large** enough channel spacing and provide room for **large** user multiplexing and multiple access
- such f_0 's have good **indoor** propagation



Multipath propagation

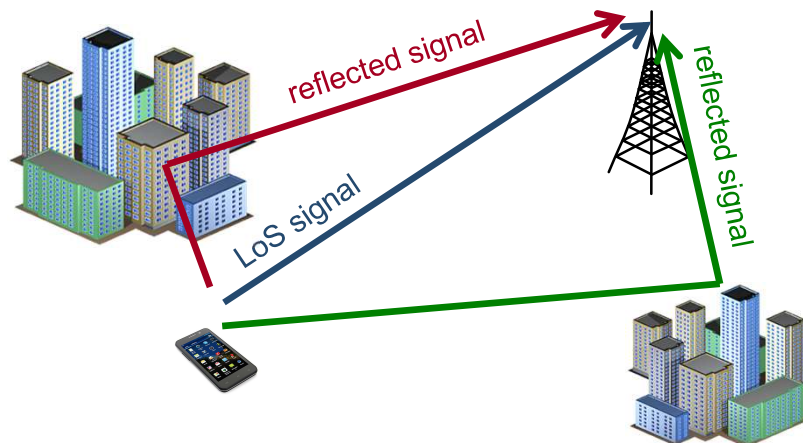
In this frequency spectrum, the wireless signal experiences a **multipath propagation**: the received signal is a **linear combination** of multiple paths



In addition to the **direct** path, a.k.a. line of sight (LoS) path, the wireless signal can propagate due to:

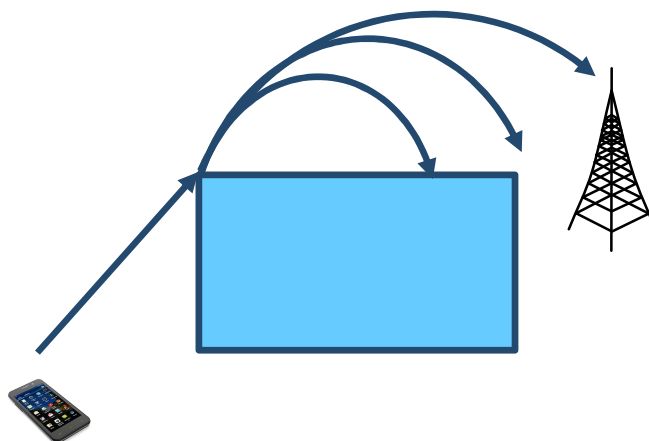
- **reflection:** $S \gg \lambda$
- **shadowing:** $S \simeq \lambda$
- **scattering:** $S \ll \lambda$

Reflection

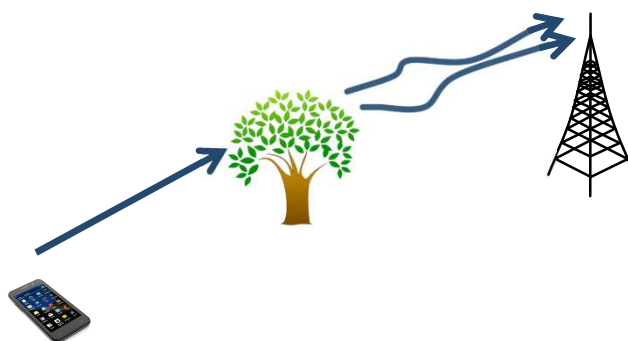


Due to the different propagation lengths, for each path the reflection introduces:

- amplitude attenuation
- group delay
- phase delay



Shadowing introduces **additional** paths when the transmitter and the receiver are **not** in visibility, thus affecting the statistics of the channel



Similarly, scattering introduced a **disordered** reflection of the electro-magnetic waves, thus impacting on attenuations and phase delays

Multipath propagation: frequency selectivity



Multipath propagation model

To sum up, the received signal is a linear **combination** of a number of different propagation paths, **each** having its own attenuation, phase rotation, and time delay:

$$\begin{aligned}
 y(t) &= \sum_{\ell=1}^{L(t)} \rho_{\ell}(t) e^{j\varphi_{\ell}(t)} x(t - \tau_{\ell}(t)) e^{-j2\pi f_0 \tau_{\ell}(t)} \\
 &= \sum_{\ell=1}^{L(t)} \rho_{\ell}(t) e^{j\theta_{\ell}(t)} x(t - \tau_{\ell}(t))
 \end{aligned}$$

$L(t)$: number of propagation paths

$\theta_{\ell}(t)$: phase delay of the ℓ -th path

$\rho_{\ell}(t)$: attenuation of the ℓ -th path

$\tau_{\ell}(t)$: time delay of the ℓ -th path



(Preliminary) classification of the wireless channel

Time domain:

- **static** (time-invariant): its statistics change very slowly wrt signaling time
- **time-varying**: its statistics are a function of time

Frequency domain:

- **frequency-flat**: its behavior is similar across the frequency components of the signal
- **frequency-selective**: each frequency component of the signal is distorted in a different way by the wireless channel



Static frequency-flat channels (1/4)

A **static** channel means: the random processes $L(t)$, $\{\rho_\ell(t)\}$, $\{\theta_\ell(t)\}$, and $\{\tau_\ell(t)\}$ are **not** functions of time (i.e., they are just **random variables**):

$$y(t) = \sum_{\ell=1}^L \rho_\ell e^{j\theta_\ell} x(t - \tau_\ell)$$

Let us suppose that the standard deviation $\sigma_\tau = \sqrt{\mathbb{E}\{|\tau_\ell - \bar{\tau}|^2\}}$ is **much smaller** than the **signaling interval** T , where $\bar{\tau} = \mathbb{E}\{\tau_\ell\}$:

$$\sigma_\tau \ll T$$

With good accuracy, we can approximate

$$\tau_\ell \approx \bar{\tau} \quad \forall \ell$$



Static frequency-flat channels (2/4)

Hence,

$$\begin{aligned} y(t) &= \sum_{\ell=1}^L \rho_{\ell} e^{j\theta_{\ell}} x(t - \tau_{\ell}) \cong x(t - \bar{\tau}) \cdot \sum_{\ell=1}^L \rho_{\ell} e^{j\theta_{\ell}} \\ &= \bar{\rho} e^{j\bar{\theta}} x(t - \bar{\tau}) \end{aligned}$$

where

$$\bar{\rho} = \left| \sum_{\ell=1}^L \rho_{\ell} e^{j\theta_{\ell}} \right|, \quad \bar{\theta} = \angle \left(\sum_{\ell=1}^L \rho_{\ell} e^{j\theta_{\ell}} \right)$$

In practice, the received signal is just a **scaled copy** of the transmitted signal $x(t)$, delayed by $\bar{\tau}$, attenuated by $\bar{\rho}$, and rotated by $\bar{\theta}$

Static frequency-flat channels (3/4)

This happens for **each frequency component** of the input signal $x(t)$:

$$\begin{aligned} Y(f) &\triangleq \mathcal{F}\{y(t)\} = \mathcal{F}\{\bar{\rho}e^{j\bar{\theta}}x(t - \bar{\tau})\} \\ &= \bar{\rho}e^{j\bar{\theta}}e^{-j2\pi f\bar{\tau}}X(f) \end{aligned}$$

where

$$X(f) \triangleq \mathcal{F}\{x(t)\} = \int_{-\infty}^{+\infty} x(t) e^{-j2\pi ft} dt$$

is the **Fourier transform** of the signal $x(t)$

If $\sigma_{\tau} \ll T$, the channel is **frequency-flat**: $H(f) = \frac{Y(f)}{X(f)} = \bar{\rho}e^{j(\bar{\theta} - 2\pi f\bar{\tau})}$



Static frequency-flat channels (4/4)

What is the **statistical distribution** of $\bar{\tau}$, $\bar{\rho}$, and $\bar{\theta}$?

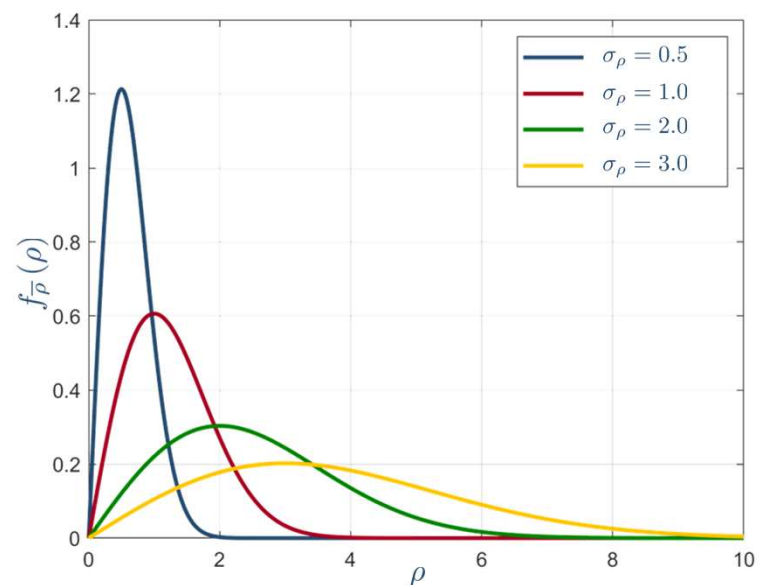
- usually, $\bar{\tau}$ depends on the propagation scenario, and it is determined by extensive **measurement campaigns**
- the probability density function (pdf) of $\bar{\rho}$ and $\bar{\theta}$ depends on the two different situations:
 - **non-LoS (NLoS) propagation** (typically, urban scenarios)
 - **LoS propagation** (typically, rural areas)



- the attenuation $\bar{\rho}$ follows a **Rayleigh distribution**:

$$f_{\bar{\rho}}(\rho) = \frac{\rho}{\sigma_{\rho}^2} e^{-\rho^2 / (2\sigma_{\rho}^2)} u(\rho)$$

where $\mathbb{E}\{\bar{\rho}^2\} = 2\sigma_{\rho}^2 = \bar{P}_R(d)$
 is the average value given by
large-scale fading models



- the phase delay $\bar{\theta}$ is **uniformly** distributed in $[-\pi, +\pi]$



LoS scenarios

- the attenuation $\bar{\rho}$ follows a **Rice distribution**:

$$f_{\bar{\rho}}(\rho) = \frac{\rho}{\sigma_{\rho}^2} e^{-\rho^2 / (2\sigma_{\rho}^2)} e^{-\kappa} \times I_0\left(\sqrt{2\kappa} \frac{\rho}{\sigma_{\rho}}\right) u(\rho)$$

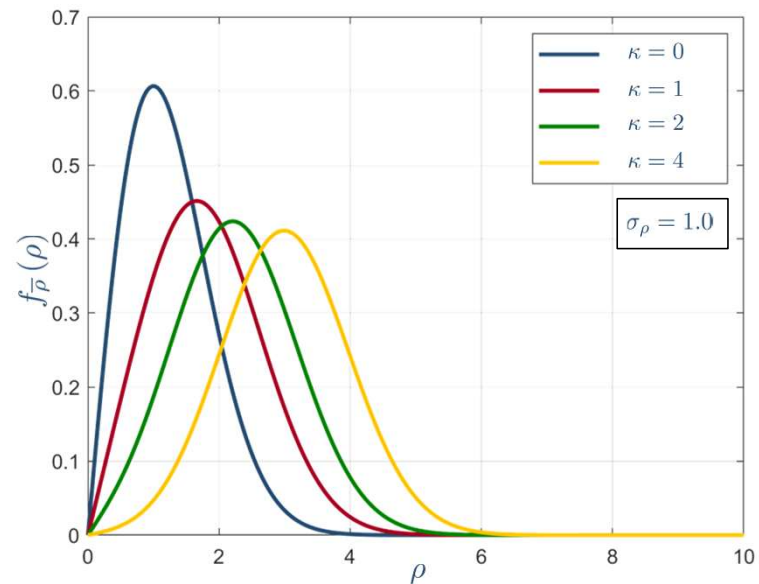
where

$$\kappa \triangleq \frac{\rho_1^2}{\sigma_{\rho}^2}$$

average power of the LoS path

average power due to multipath propagation

is the **Rice factor**



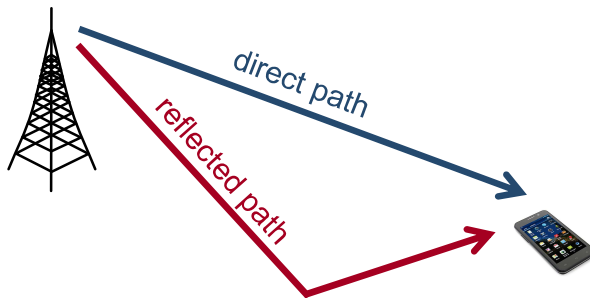
- the pdf of the phase delay $\bar{\theta}$ **cannot** be written in a closed form

Static frequency-selective channels (1/4)

Suppose now that the hypothesis $\sigma_\tau \ll T$ does **not** hold: this means that we now have

$$y(t) = \sum_{\ell=1}^L \rho_\ell e^{j\theta_\ell} x(t - \tau_\ell)$$

For the sake of simplicity, let's consider the **two-ray channel**, i.e., $L = 2$:



$$y(t) = \underbrace{\rho_1 e^{j\theta_1} x(t - \tau_1)}_{\text{direct (LoS) path}} + \underbrace{\rho_2 e^{j\theta_2} x(t - \tau_2)}_{\text{reflected path}}$$

Static frequency-selective channels (2/4)

To simplify the notation, let us take:

$$\begin{aligned}\rho_1 &= 1, & \theta_1 &= 0, & \tau_1 &= 0 \\ \rho_2 &= \rho, & \theta_2 &= \theta, & \tau_2 &= \tau\end{aligned}$$

received signal: $y(t) = x(t) + \rho e^{j\theta} x(t - \tau)$

Fourier transform: $Y(f) = X(f) \cdot [1 + \rho e^{j\theta} e^{-j2\pi f\tau}]$

The **frequency response** of the channel is

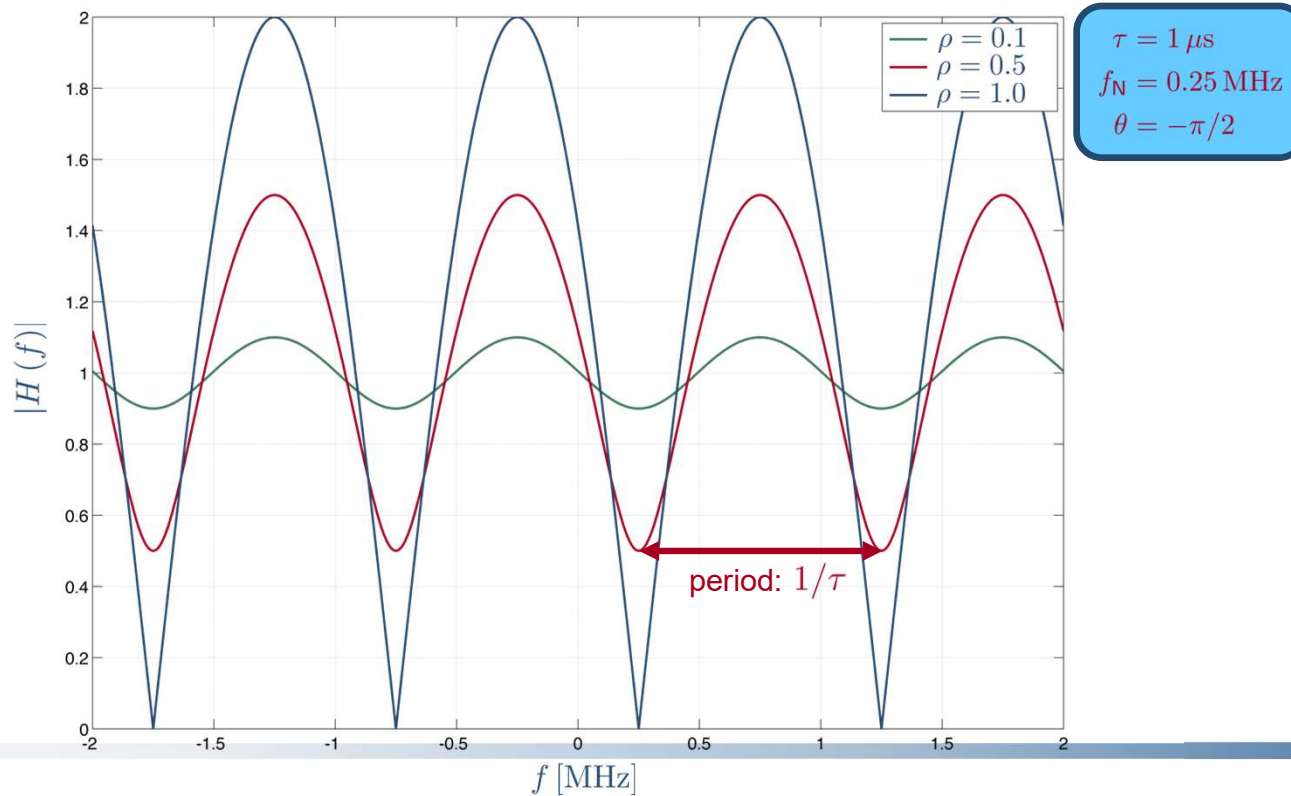
$$H(f) = \frac{Y(f)}{X(f)} = 1 - \rho e^{-j2\pi(f-f_N)\tau}$$

where $f_N = \frac{1}{2\tau} + \frac{\theta}{2\pi\tau}$ is the **notch frequency** of the channel

Static frequency-selective channels (3/4)

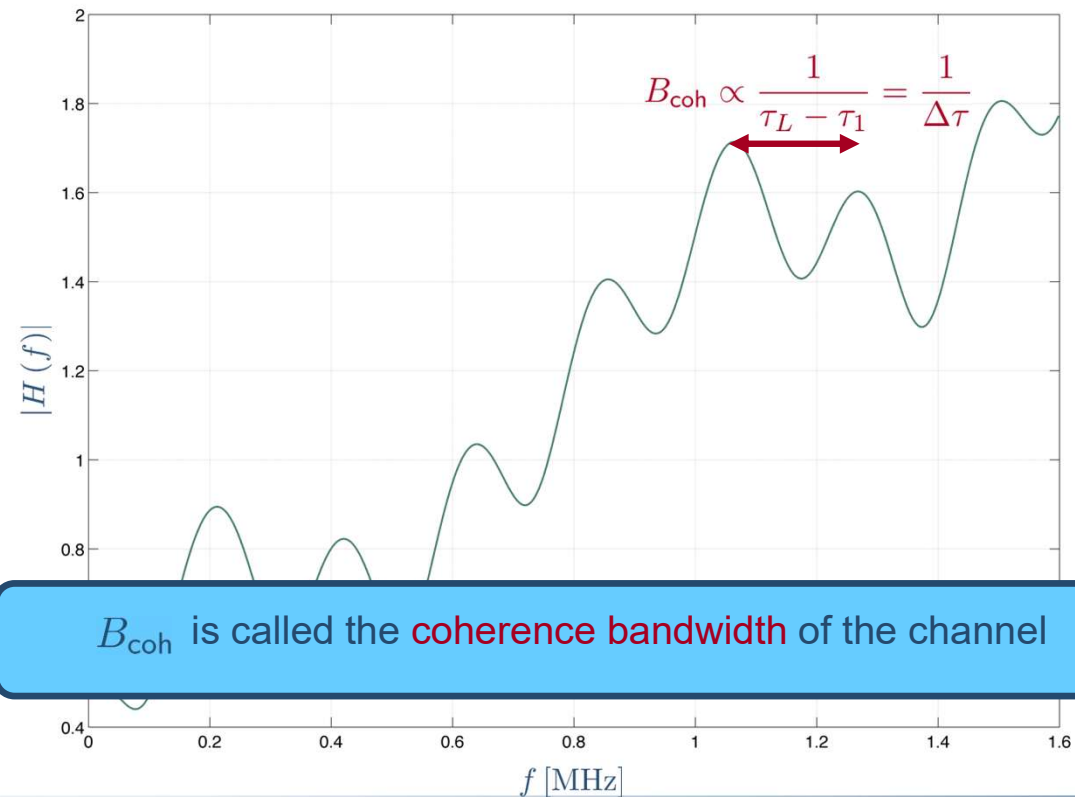
The amplitude response of the two-ray channel is

$$|H(f)| = \sqrt{1 + \rho^2 - 2\rho \cos [2\pi (f - f_N) \tau]}$$



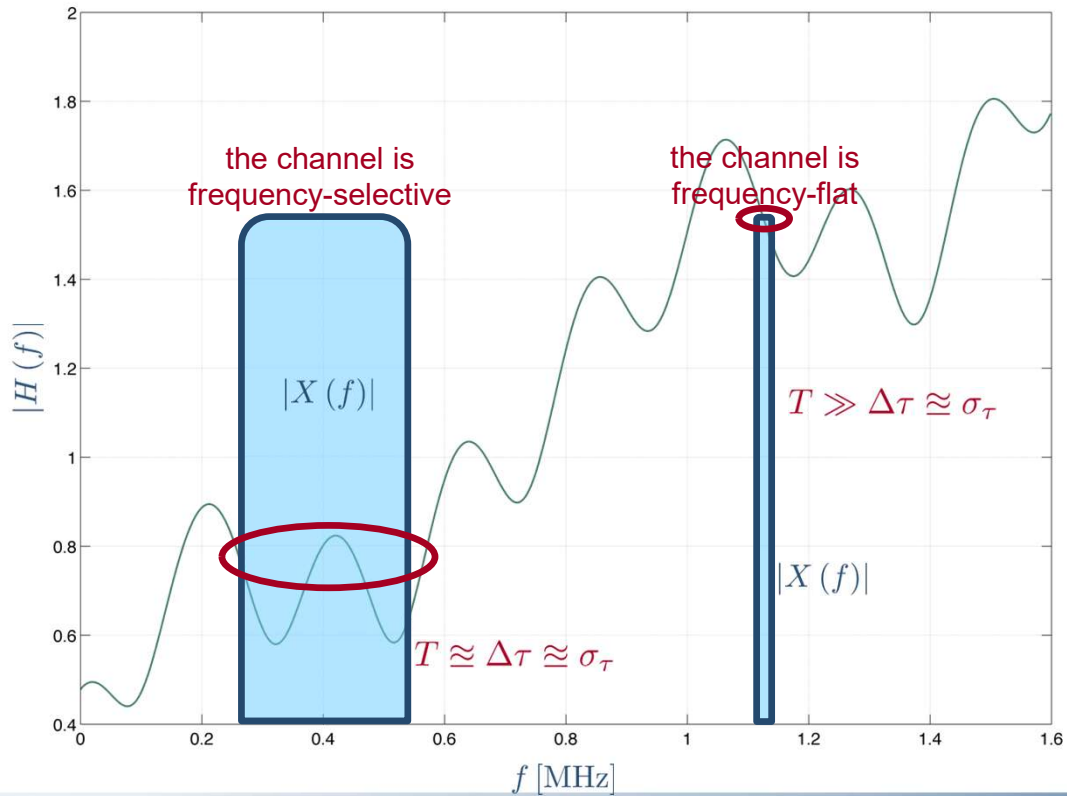
Static frequency-selective channels (4/4)

When extending the calculations to the L -ray channel, we get



The concept of frequency selectivity (1/2)

We know that the bandwidth of a signal $x(t)$ is $B \propto 1/T$



The concept of frequency selectivity (2/2)

The frequency selectivity depends on the statistics of the channel **and** of the input signal

There is a practical way to assess the frequency selectivity of a channel:

- $B \ll B_{\text{coh}} \Leftrightarrow T \gg \sigma_{\tau}$: **frequency-flat** channel
- $B \approx B_{\text{coh}} \Leftrightarrow T \approx \sigma_{\tau}$: **frequency-selective** channel

Example:

- **urban scenarios:** $\sigma_{\tau} \approx 1 \mu\text{s} \Rightarrow B_{\text{coh}} \approx 1 \text{ MHz}$
- **3G and 4G signals:** $B \geq 3.5 \text{ MHz}$

Some form of **equalization** is needed to combat the frequency selectivity



Multipath propagation: time selectivity



Multipath propagation model

In a multipath scenario, the received signal is a linear **combination** of a number of different propagation paths, **each** having its own attenuation, phase rotation, and time delay:

$$\begin{aligned}
 y(t) &= \sum_{\ell=1}^{L(t)} \rho_{\ell}(t) e^{j\varphi_{\ell}(t)} x(t - \tau_{\ell}(t)) e^{-j2\pi f_0 \tau_{\ell}(t)} \\
 &= \sum_{\ell=1}^{L(t)} \rho_{\ell}(t) e^{j\theta_{\ell}(t)} x(t - \tau_{\ell}(t))
 \end{aligned}$$

$L(t)$: number of propagation paths

$\theta_{\ell}(t)$: phase delay of the ℓ -th path

$\rho_{\ell}(t)$: attenuation of the ℓ -th path

$\tau_{\ell}(t)$: time delay of the ℓ -th path



Frequency selectivity

To assess the frequency selectivity of a channel, we need to compare the parameters of the input signal (bandwidth B , time interval T) with the characteristics of the channel (coherence bandwidth B_{coh} , delay spread σ_τ):

- $B \ll B_{\text{coh}} \Leftrightarrow T \gg \sigma_\tau$: **frequency-flat** channel
- $B \approx B_{\text{coh}} \Leftrightarrow T \approx \sigma_\tau$: **frequency-selective** channel



Time-varying frequency-flat channels (1/4)

Due to the relative **motion** between the transmitter and the receiver, the communication medium (the wireless channel) **evolves** through time:

$$y(t) = \sum_{\ell=1}^{L(t)} \rho_{\ell}(t) e^{j\theta_{\ell}(t)} x(t - \tau_{\ell}(t))$$

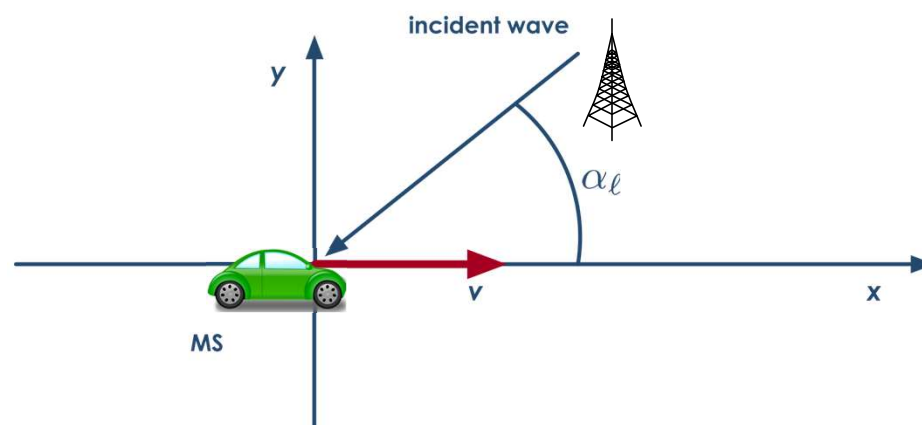
For simplicity, let's assume a **frequency-flat** channel: $\sigma_{\tau} \ll T \Rightarrow \tau_{\ell}(t) \cong \bar{\tau} \quad \forall \ell$

Similarly to the static case,

$$\begin{aligned} y(t) &\cong x(t - \bar{\tau}) \cdot \sum_{\ell=1}^{L(t)} \rho_{\ell}(t) e^{j\theta_{\ell}(t)} \\ &= \bar{\rho}(t) \cdot e^{j\bar{\theta}(t)} \cdot x(t - \bar{\tau}) \\ &= \underbrace{A(t)} \cdot x(t - \bar{\tau}) \\ &\quad \text{fading process} \end{aligned}$$

Time-varying frequency-flat channels (2/4)

To study time and frequency characteristics of $A(t)$, let us use the **kinematic model** for the MS:



Due to **Doppler effect**, each band pass frequency $f \in [f_0 - \frac{B}{2}, f_0 + \frac{B}{2}]$, where f_0 is the carrier frequency, is shifted at the receive side by its **Doppler shift** Δf :

$$\Delta f = \frac{v}{c} \cdot f \cdot \cos(\alpha_l)$$

Time-varying frequency-flat channels (3/4)

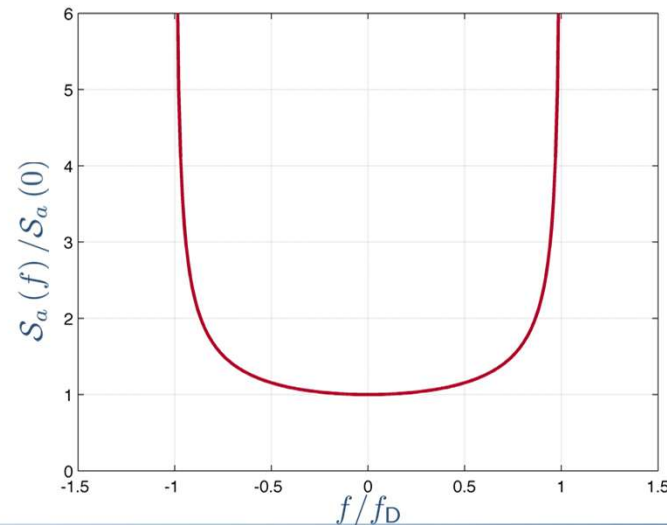
The behavior of $A(t)$ is given by the impact of the Doppler effect over **all** signal frequency components $f \in [f_0 - \frac{B}{2}, f_0 + \frac{B}{2}]$

A key parameter is the maximum Doppler shift at the carrier frequency f_0 , called the **Doppler spread** f_D :

$$f_D \triangleq \max_{\alpha_\ell} |\Delta f| = \frac{v}{c} \cdot f_0$$

Using the **Clarke's model**, we can compute the power spectral density (PSD) of the random process $A(t)$:

$$S_a(f) = \frac{\sigma_\rho^2}{2\pi f_D} \cdot \frac{1}{\sqrt{1 - (f/f_D)^2}}$$

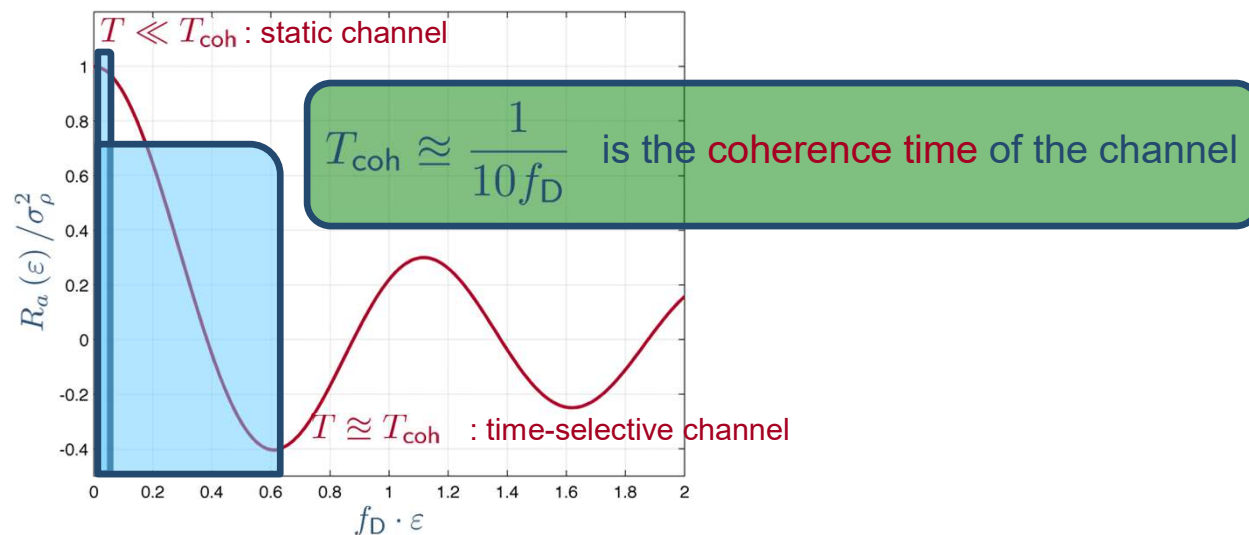


Time-varying frequency-flat channels (4/4)

Another useful statistical parameter to investigate the properties of $A(t)$ is its **autocorrelation** function:

$$R_a(\varepsilon) = \mathcal{F}^{-1} \{ \mathcal{S}_a(f) \} = \mathbb{E} \{ A(t) \cdot A(t + \varepsilon) \}$$

Using again the Clarke's model,



The concept of time selectivity

The time selectivity depends on the statistics of the channel **and** of the input signal

There is a practical way to assess the time selectivity of a channel:

- $B \gg f_D \Leftrightarrow T \ll T_{\text{coh}}$: **static** channel
- $B \approx f_D \Leftrightarrow T \approx T_{\text{coh}}$: **time-selective** channel

Example (3G systems):

- $v = 120 \text{ km/h}, f_0 = 2 \text{ GHz} : T_{\text{coh}} = 0.45 \text{ ms}$
- **slot duration:** $T_{\text{slot}} = 0.66 \text{ ms}$

Some **design constraints** must be added to combat the time selectivity



Multipath propagation: A summary



Frequency and time selectivity: A summary (1/5)

Both time- and frequency-selectivity are functions of **both** the channel and the input signal properties:

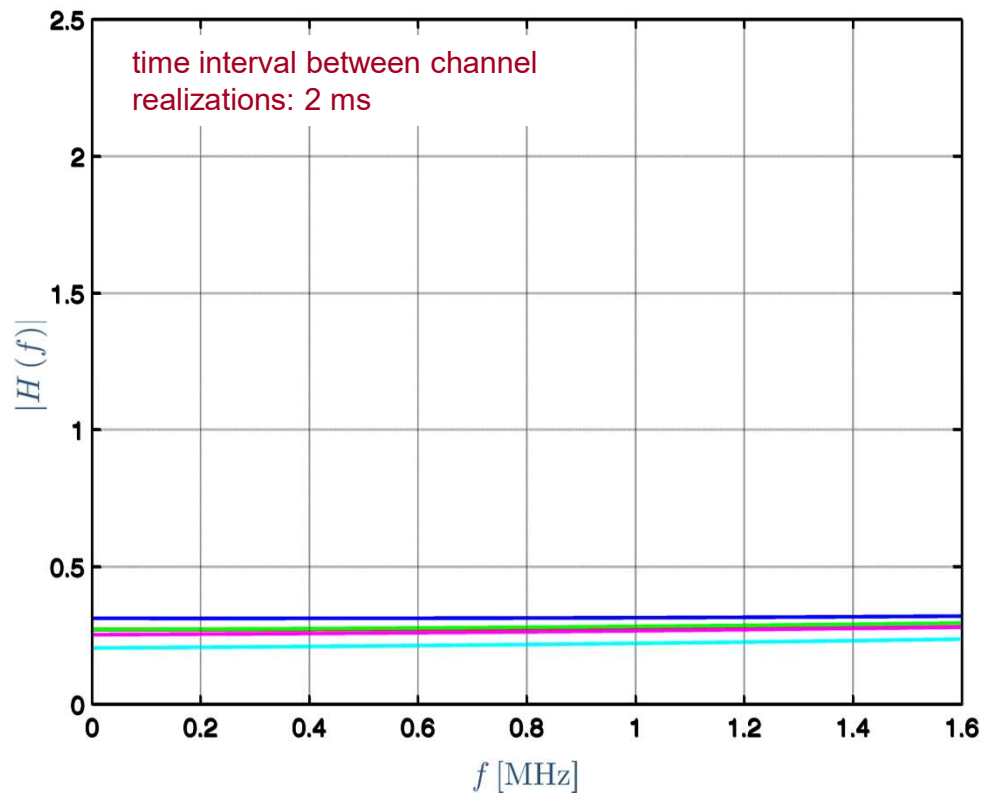
	frequency-flat	frequency-selective
static	$f_D \ll B \ll B_{coh}$	$f_D \ll B \approx B_{coh}$
time-selective	$f_D \approx B \ll B_{coh}$	$f_D \approx B \approx B_{coh}$

- frequency-selective = time-dispersive
- time-selective = frequency-dispersive
- frequency-selective \neq time-selective!



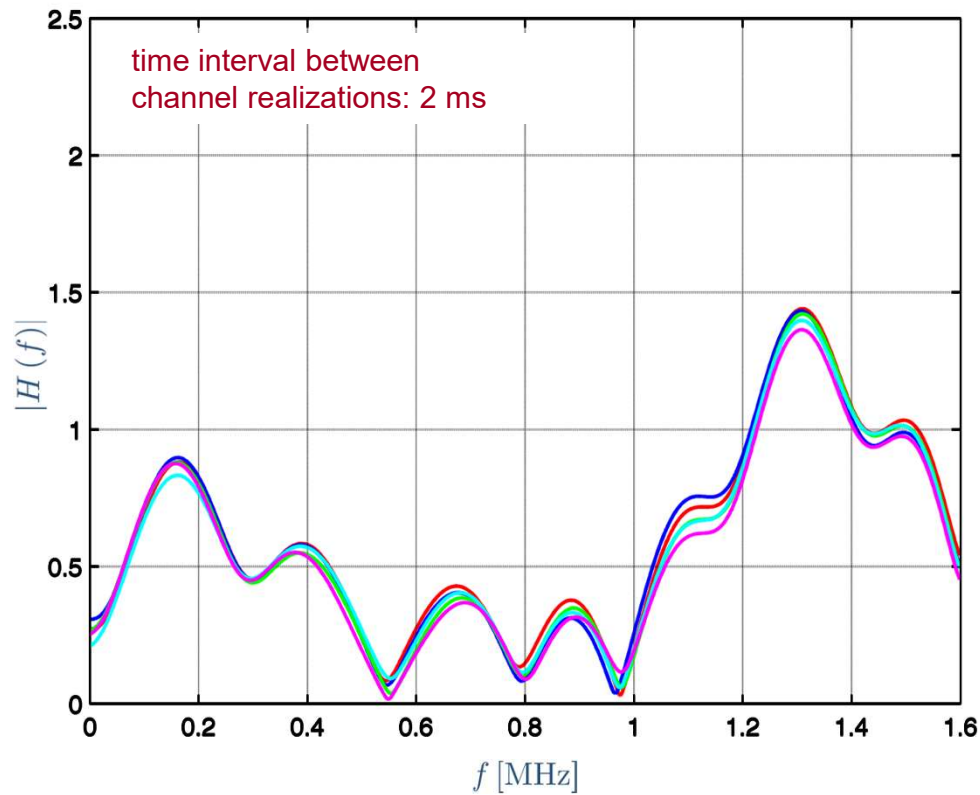
Frequency and time selectivity: A summary (2/5)

A static frequency-flat channel ($T_{\text{coh}} = 100 \text{ ms}$, $B_{\text{coh}} = 10 \text{ MHz}$):



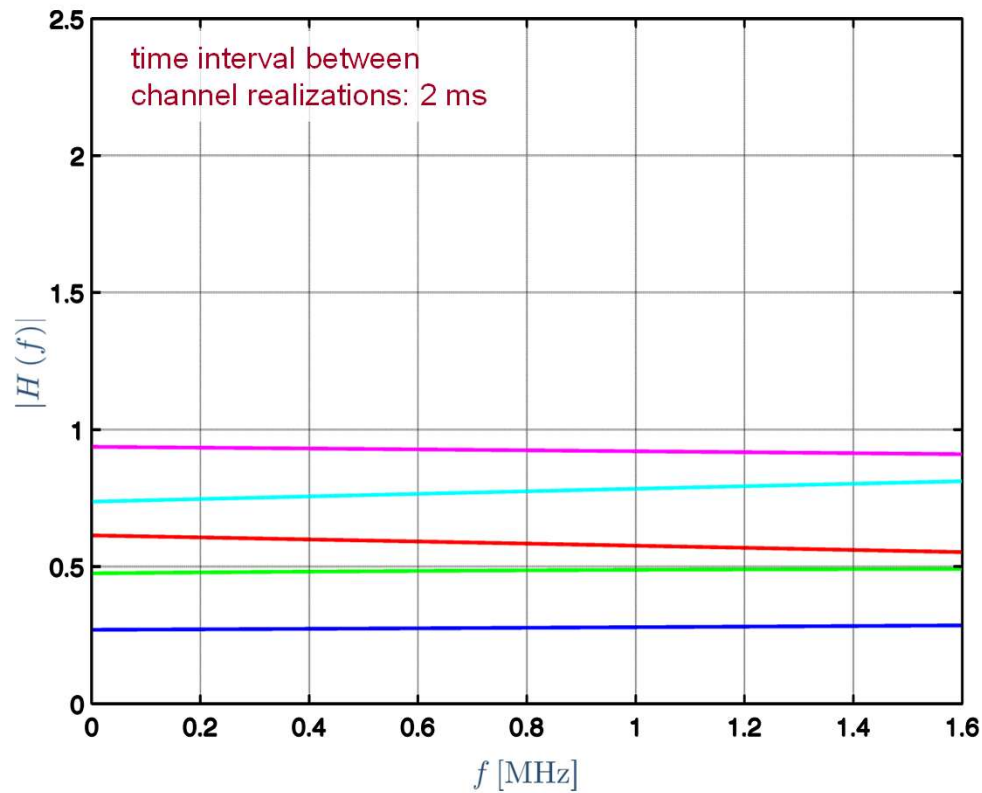
Frequency and time selectivity: A summary (3/5)

A static frequency-selective channel ($T_{\text{coh}} = 100 \text{ ms}$, $B_{\text{coh}} = 100 \text{ kHz}$):



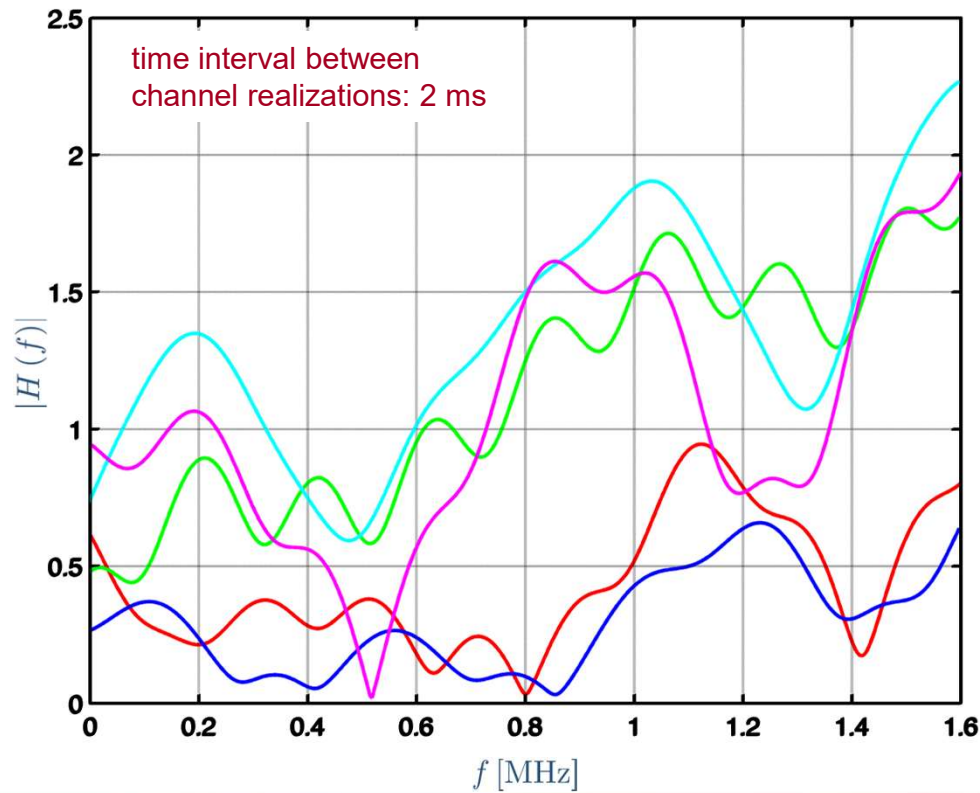
Frequency and time selectivity: A summary (4/5)

A time-selective frequency-flat channel ($T_{\text{coh}} = 1 \text{ ms}$, $B_{\text{coh}} = 10 \text{ MHz}$):



Frequency and time selectivity: A summary (5/5)

A doubly-selective channel ($T_{\text{coh}} = 1 \text{ ms}$, $B_{\text{coh}} = 100 \text{ kHz}$):



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